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# Existence of positive solutions of nonlinear fractional *q*-difference equation with parameter

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# Abstract

In this paper, we study the boundary value problem of a class of nonlinear fractional *q*-difference equations with parameter involving the Riemann-Liouville fractional derivative. By means of a fixed point theorem in cones, some positive solutions are obtained. As applications, some examples are presented to illustrate our main results. **MSC:** 39A13; 34B18; 34A08

**Keywords:** fractional *q*-difference equations; boundary value problems; fixed point theorem in cones; positive solutions

# **1** Introduction

The q-difference calculus is an interesting and old subject that many researchers devote their time to studying. The q-difference calculus or quantum calculus were first developed by Jackson [1, 2], while basic definitions and properties can be found in the papers [3, 4]. The q-difference calculus describes many phenomena in various fields of science and engineering [1].

The origin of the fractional q-difference calculus can be traced back to the works in [5, 6] by Al-Salam and by Agarwal.

The *q*-difference calculus is a necessary part of discrete mathematics. More recently, there has been much research activity concerning the fractional *q*-difference calculus [7–15]. Relevant theory about fractional *q*-difference calculus has been established [16], such as *q*-analogues of integral and difference fractional operators properties as Mittag-Leffler function [17], *q*-Laplace transform, *q*-Taylor's formula [18, 19], just to mention some. It is not only the requirements of the fractional *q*-difference calculus theory but also its the broad application.

Apart from this old history of *q*-difference equations, the subject has received a considerable interest of many mathematicians and from many aspects, theoretical and practical. Specifically, *q*-difference equations have been widely used in mathematical physical problems, dynamical system and quantum models [20], *q*-analogues of mathematical physical problems including heat and wave equations [21], sampling theory of signal analysis [22, 23]. What is more, the fractional *q*-difference calculus plays an important role in quantum calculus.

As generalizations of integer order q-difference, fractional q-difference can describe physical phenomena much better and more accurately. Perhaps due to the development of



© 2013 Li et al.; licensee Springer. This is an Open Access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/2.0), which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited. fractional differential equations [24-26], an interest has been observed in studying boundary value problems of fractional *q*-difference equations, especially about the existence of solutions for boundary value problems [3, 4, 27, 28].

In 2010, Ferreita [3] considered the existence of nontrivial solutions to the fractional *q*-difference equation

$$\left(D_q^{\alpha}y\right)(x) = -f\left(x, y(x)\right), \quad 0 < x < 1,$$

subjected to the boundary conditions

$$y(0) = 0, \qquad y(1) = 0,$$

where  $1 < \alpha \le 2$  and  $f : [0,1] \times \mathbb{R} \to \mathbb{R}$  is a nonnegative continuous function.

In 2011, Ferreita [4] went on studying the existence of positive solutions to the fractional *q*-difference equation

$$(D_q^{\alpha}y)(x) = -f(x, y(x)), \quad 0 < x < 1,$$

subjected to the boundary conditions

$$y(0) = (D_q y)(0) = 0,$$
  $(D_q y)(1) = \beta \ge 0,$ 

where  $2 < \alpha \le 3$  and  $f : [0,1] \times \mathbb{R} \to \mathbb{R}$  is a nonnegative continuous function. By constructing a special cone and using Krasnosel'skii fixed point theorem, some existence results of positive solutions were obtained.

In 2011, El-Shahed and Al-Askar [27] studied the existence of a positive solution for a boundary value problem of the nonlinear factional *q*-difference equation

$$_{c}D_{q}^{\alpha}u+a(t)f(t)=0, \quad 0\leq t\leq 1, 2$$

with the boundary conditions

$$u(0) = D_q^2 u(0) = 0,$$
  
 $\gamma D_q u(1) + \beta D_q^2 u(1) = 0,$ 

where  $\gamma$ ,  $\beta \leq 0$  and  $_{c}D_{q}^{\alpha}$  is fractional *q*-derivative of Caputo type.

In 2012, Liang and Zhang [28] studied the existence and uniqueness of positive solutions for the three-point boundary problem of fractional *q*-differences

$$\begin{split} & \left(D_q^{\alpha} u\right)(t) + f\left(t, u(t)\right) = 0, \quad 0 < t < 1, 2 < \alpha < 3, \\ & u(0) = (D_q u)(0) = 0, \qquad (D_q u)(1) = \beta(D_q u)(\eta), \end{split}$$

where  $0 < \beta \eta^{\alpha-2} < 1$ . By using a fixed-point theorem in partially ordered sets, they got some sufficient conditions for the existence and uniqueness of positive solutions to the above boundary problem.

To the best of our knowledge, there are few papers that consider the boundary value of nonlinear fractional q-difference equations with parameters. Theories and applications seem to be just being initiated. In this paper we investigate the existence of solutions for the following two-point boundary value problem of nonlinear fractional q-difference equations

$$\left(D_q^{\alpha}u\right)(x) + \lambda f\left(u(x)\right) = 0, \quad 0 < x < 1, \tag{1.1}$$

subject to the boundary conditions

$$u(0) = D_q u(0) = D_q u(1) = 0, (1.2)$$

where  $0 < q < 1, 2 < \alpha < 3, f : C((0, 1), (0, \infty))$ . We prove the existence of positive solutions for boundary value problem (1.1)-(1.2) by utilizing a fixed point theorem in cones. Several existence results for positive solutions in terms of different values of the parameter  $\lambda$  are obtained. This work is motivated by papers [25, 28].

The paper is organized as follows. In Section 2, we introduce some definitions of q-fractional integral and differential operator together with some basic properties and lemmas to prove our main results. In Section 3, we investigate the existence of positive solutions for boundary value problem (1.1)-(1.2) by a fixed point theorem in cones. Moreover, some examples are given to illustrate our main results.

## 2 Preliminaries

In the following section, we collect some definitions and lemmas about fractional *q*-integral and fractional *q*-derivative which are referred to in [3].

Let  $q \in (0, 1)$  and define

$$[a]_q = \frac{1-q^a}{1-q}, \quad a \in \mathbb{R}.$$

The *q*-analogue of the power function  $(a - b)^n$  with  $n \in \mathbb{N}_0$  is

$$(a-b)^0 = 1,$$
  $(a-b)^n = \prod_{k=0}^{n-1} (a-bq^k),$   $n \in \mathbb{N}, a, b \in \mathbb{R}.$ 

More generally, if  $\alpha \in \mathbb{R}$ , then

$$(a-b)^{(\alpha)} = a^{\alpha} \prod_{n=0}^{\infty} \frac{a-bq^n}{a-bq^{\alpha+n}}.$$

It is easy to see that  $[a(t-s)]^{(\alpha)} = a^{\alpha}(t-s)^{(\alpha)}$ . And note that if b = 0 then  $a^{(\alpha)} = a^{\alpha}$ . The *q*-gamma function is defined by

$$\Gamma_q(x) = rac{(1-q)^{(x-1)}}{(1-q)^{x-1}}, \quad x \in \mathbb{R} \setminus \{0, -1, -2, \ldots\},$$

and satisfies  $\Gamma_q(x+1) = [x]_q \Gamma_q(x)$ .

$$(D_q f)(x) = \frac{f(x) - f(qx)}{(1 - q)x}$$
 for  $x \neq 0$ ,  $(D_q f)(0) = \lim_{x \to 0} (D_q f)(x)$ ,

and *q*-derivatives of higher order by

$$(D_q^0 f)(x) = f(x)$$
 and  $(D_q^n f)(x) = D_q (D_q^{n-1} f)(x), n \in \mathbb{N}.$ 

The *q*-integral of a function f defined on the interval [0, b] is given by

$$(I_q f)(x) = \int_0^x f(t) \, d_q t = x(1-q) \sum_{n=0}^\infty f(xq^n) q^n, \quad x \in [0,b].$$

If  $a \in [0, b]$  and f is defined on the interval [0, b], its q-integral from a to b is defined by

$$\int_{a}^{b} f(t) \, d_{q}t = \int_{0}^{b} f(t) \, d_{q}t - \int_{0}^{a} f(t) \, d_{q}t.$$

Similarly as done for derivatives, an operator  $I_q^n$  can be defined as

$$(I_q^0 f)(x) = f(x)$$
 and  $(I_q^n f)(x) = I_q(I_q^{n-1} f)(x), \quad n \in \mathbb{N}.$ 

From the definition of *q*-integral and the properties of series, we can get the following results concerning *q*-integral, which are helpful in the proofs of our main results.

**Lemma 2.1** (1) *If f and g are q-integral on the interval*  $[a, b], \alpha \in \mathbb{R}, c \in [a, b]$ , *then* 

(i)  $\int_{a}^{b} (f(t) + g(t)) d_{q}t = \int_{a}^{b} f(t) d_{q}t + \int_{a}^{b} g(t) d_{q}t;$ (ii)  $\int_{a}^{b} \alpha f(t) d_{q}t = \alpha \int_{b}^{a} f(t) d_{q}t;$ (iii)  $\int_{a}^{b} f(t) d_{q}t = \int_{a}^{c} f(t) d_{q}t + \int_{c}^{b} f(t) d_{q}t;$ (2) If |f| is q-integral on the interval [0, x], then  $|\int_{0}^{x} f(t) d_{q}t| \le \int_{0}^{x} |f(t)| d_{q}t;$ (3) If f and g are q-integral on the interval [0, x],  $f(t) \le g(t)$  for all  $t \in [0, x]$ , then  $\int_{0}^{x} f(t) d_{q}t \le \int_{0}^{x} g(t) d_{q}t.$ 

The fundamental theorem of calculus applies to these operators  $I_q$  and  $D_q$ , *i.e.*,

$$(D_q I_q f)(x) = f(x),$$

and if f is continuous at x = 0, then

$$(I_q D_q f)(x) = f(x) - f(0).$$

Basic properties of q-integral operator and q-differential operator can be found in the book [16].

We now point out three formulas that will be used later  $({}_iD_q$  denotes the derivative with respect to variable i)

$${}_{t}D_{q}(t-s)^{(\alpha)} = [\alpha]_{q}(t-s)^{(\alpha-1)},$$
  
 $\left({}_{x}D_{q}\int_{0}^{x}f(x,t)\,d_{q}t\right)(x) = \int_{0}^{x}{}_{x}D_{q}f(x,t)\,d_{q}t + f(qx,x).$ 

**Remark 2.1** We note that if  $\alpha > 0$  and  $a \le b \le t$ , then  $(t - a)^{(\alpha)} \ge (t - b)^{(\alpha)}$ .

**Definition 2.1** [6] Let  $\alpha \ge 0$  and f be a function defined on [0, 1]. The fractional q-integral of the Riemann-Liouville type is  $(I_{\alpha}^{0}f)(x) = f(x)$  and

$$\left(I_q^{\alpha}f\right)(x) = \frac{1}{\Gamma_q(\alpha)} \int_0^x (x-qt)^{(\alpha-1)}f(t) \, d_q t, \quad \alpha > 0, x \in [0,1].$$

**Definition 2.2** [18] The fractional *q*-derivative of the Riemann-Liouville type of order  $\alpha \ge 0$  is defined by  $(D_{\alpha}^{0}f)(x) = f(x)$  and

$$(D_q^{\alpha}f)(x) = (D_q^p I_q^{p-\alpha}f)(x), \quad \alpha > 0,$$

where *p* is the smallest integer greater than or equal to  $\alpha$ .

Next, we list some properties about *q*-derivative and *q*-integral that are already known in the literature.

**Lemma 2.2** [6, 18] Let  $\alpha, \beta \ge 0$  and f be a function defined on [0,1]. Then the following formulas hold:

(i)  $(I_q^{\beta}I_q^{\alpha}f)(x) = (I_q^{\alpha+\beta}f)(x);$ (ii)  $(D_q^{\alpha}I_q^{\alpha}f) = f(x).$ 

**Lemma 2.3** [3] Let  $\alpha > 0$  and p be a positive integer. Then the following equality holds:

$$\left(I_q^{\alpha}D_q^pf\right)(x) = \left(D_q^pI_q^{\alpha}f\right)(x) - \sum_{k=0}^{p-1}\frac{x^{\alpha-p+k}}{\Gamma_q(\alpha+k-p+1)}\left(D_q^kf\right)(0).$$

**Lemma 2.4** [29] Let X be a Banach space and  $P \subseteq X$  be a cone. Suppose that  $\Omega_1$  and  $\Omega_2$  are bounded open sets contained in X such that  $0 \in \Omega_1 \subseteq \overline{\Omega}_1 \subseteq \Omega_2$ . Suppose further that  $S: P \cap (\overline{\Omega}_2 \setminus \Omega_1) \to P$  is a completely continuous operator. If either

- (i)  $||Su|| \le ||u||$  for  $u \in P \cap \partial \Omega_1$  and  $||Su|| \ge ||u||$  for  $u \in P \cap \partial \Omega_2$ , or
- (ii)  $||Su|| \ge ||u||$  for  $u \in P \cap \partial \Omega_1$  and  $||Su|| \le ||u||$  for  $u \in P \cap \partial \Omega_2$ , then S has at least one fixed point in  $P \cap (\overline{\Omega}_2 \setminus \Omega_1)$ .

The next result is important in the sequel.

**Lemma 2.5** [4] Let  $f(u(x)) \in C[0,1]$  be a given function. Then the boundary value problem

$$(D_q^{\alpha}u)(x) + f(u(x)) = 0, \quad 0 < x < 1,$$
 (2.1)

$$u(0) = D_q u(0) = D_q u(1) = 0, (2.2)$$

has a unique solution

$$u(x) = \int_0^1 G(x,qt) f(u(t)) d_q t,$$

where

$$G(x,qt) = \frac{1}{\Gamma_q(\alpha)} \begin{cases} (1-qt)^{(\alpha-2)} x^{\alpha-1} - (x-qt)^{\alpha-1}, & 0 \le qt \le x \le 1, \\ (1-qt)^{(\alpha-2)} x^{\alpha-1}, & 0 \le x \le qt \le 1, \end{cases}$$

is the Green function of boundary value problem (2.1)-(2.2).

The following properties of the Green function play important roles in this paper.

**Lemma 2.6** [4] Function G defined above satisfies the following conditions:

(1) 
$$G(x,qt) \ge 0 \text{ and } G(x,qt) \le G(1,qt) \text{ for all } 0 \le x,t \le 1.$$
 (2.3)

(2)  $G(x,qt) \ge g(x)G(1,qt)$  for all  $0 \le x, t \le 1$  with  $g(x) = x^{\alpha - 1}$ .

# 3 Main results

We are now in a position to state and prove our main results in this paper.

Let the Banach space B = C[0,1] be endowed with the norm  $||u|| = \sup_{x \in [0,1]} |u(x)|$ . Let  $\tau$  be a real constant with  $0 < \tau < 1$  and define the cone  $P \subset B$  by  $P = \{u \in C[0,1] \mid u(x) \ge 0, \min_{x \in [\tau,1]} u(x) \ge \tau^{\alpha-1} ||u||\}$ .

Suppose that u is a solution of boundary value problem (1.1)-(1.2). Then

$$u(x) = \lambda \int_0^1 G(x, qt) f(u(t)) d_q t, \quad t \in [0, 1].$$
(3.1)

Define the operator  $A_{\lambda} : P \to B$  by

$$A_{\lambda}u(x) = \lambda \int_0^1 G(x,qt)f(u(t)) d_q t.$$

Then we have the following results.

**Lemma 3.1**  $A_{\lambda}: P \rightarrow P$  is completely continuous.

*Proof* It is easy to see that the operator  $A_{\lambda} : P \to P$  is continuous in view of continuity of *G* and *f*.

By Lemmas 2.1 and 2.6, we have

$$\begin{split} \min_{x \in [\tau, 1]} A_{\lambda} \big( u(x) \big) &= \min_{x \in [\tau, 1]} \lambda \int_{0}^{1} G(x, qt) f\big( u(t) \big) \, d_{q}t \\ &\geq \tau^{\alpha - 1} \bigg( \lambda \int_{\tau}^{1} G(1, qt) f\big( u(t) \big) \, d_{q}t \bigg) \\ &= \tau^{\alpha - 1} \| A_{\lambda} u \|. \end{split}$$

Thus,  $A_{\lambda}(P) \subset P$ .

Now, let  $\Omega \subset P$  be bounded, *i.e.*, there exists a positive constant M > 0 such that  $||u|| \le M$  for all  $u \in \Omega$ . Let  $L = \max_{||u|| \le M} |f(u(x))| + 1$ . Then, for  $u \in \Omega$ , from Lemmas 2.1 and 2.6, we have

$$|A_{\lambda}u(x)| \leq \lambda \int_0^1 |G(x,qt)f(u(t))| dt \leq \lambda L \int_0^1 G(1,qt) d_q t.$$

Hence,  $A_{\lambda}(\Omega)$  is bounded.

On the other hand, for any given  $\varepsilon > 0$  , setting

$$\delta = \min\left\{\frac{1}{2}, \frac{\varepsilon \Gamma_q(\alpha)}{2L\lambda}\right\},\,$$

then for each  $u \in \Omega$ ,  $0 \le x_1 \le x_2 \le 1$  and  $|x_2 - x_1| < \delta$ , one has  $|A_{\lambda}u(x_2) - A_{\lambda}u(x_1)| < \varepsilon$ , that is to say,  $A_{\lambda}(\Omega)$  is equicontinuous. In fact,

$$\begin{split} \left| A_{\lambda} u(x_{2}) - A_{\lambda} u(x_{1}) \right| \\ &= \left| \lambda \int_{0}^{1} G(x_{2}, qt) f\left(u(t)\right) d_{q}t - \lambda \int_{0}^{1} G(x_{1}, qt) f\left(u(t)\right) d_{q}t \right| \\ &\leq \lambda \int_{0}^{1} \left| G(x_{2}, qt) - G(x_{1}, qt) f\left(u(t)\right) \right| d_{q}t \lambda L \int_{0}^{1} \left| G(x_{2}, qt) - G(x_{1}, qt) \right| d_{q}t \\ &= \lambda L \left( \int_{0}^{x_{1}} \left| G(x_{2}, qt) - G(x_{1}, qt) \right| d_{q}t + \int_{x_{1}}^{x_{2}} \left| G(x_{2}, qt) - G(x_{1}, qt) \right| d_{q}t \\ &+ \int_{x_{2}}^{1} \left| G(x_{2}, qt) - G(x_{1}, qt) \right| d_{q}t \right) \\ &= \lambda L \left( \int_{0}^{x_{1}} \frac{1}{\Gamma_{q}(\alpha)} \left[ (1 - qt)^{(\alpha - 2)} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) - (x_{2} - qt)^{(\alpha - 1)} + (x_{1} - qt)^{(\alpha - 1)} \right] d_{q}t \\ &+ \int_{x_{1}}^{x_{2}} \frac{1}{\Gamma_{q}(\alpha)} \left[ (1 - qt)^{(\alpha - 2)} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) - (1 - qt)^{(\alpha - 2)} x_{1}^{\alpha - 1} \right] d_{q}t \\ &+ \int_{x_{2}}^{1} \frac{1}{\Gamma_{q}(\alpha)} \left[ (1 - qt)^{(\alpha - 2)} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) \right] d_{q}t \right). \end{split}$$

Now we rearrange the above equation as follows, and from the properties of *q*-integral, we get

$$\begin{split} \left| A_{\lambda} u(x_{2}) - A_{\lambda} u(x_{1}) \right| \\ &= \lambda L \frac{1}{\Gamma_{q}(\alpha)} \left\{ \int_{0}^{1} (1 - qt)^{(\alpha - 2)} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) d_{q}t \right. \\ &+ \int_{0}^{x_{1}} (x_{1} - qt)^{(\alpha - 1)} d_{q}t - \int_{0}^{x_{2}} (x_{2} - qt)^{(\alpha - 1)} d_{q}t \right\} \\ &\leq \lambda L \frac{1}{\Gamma_{q}(\alpha)} \left\{ \int_{0}^{1} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) d_{q}t + \int_{0}^{x_{1}} (x_{1} - qt)^{(\alpha - 1)} d_{q}t - \int_{0}^{x_{2}} (x_{2} - qt)^{(\alpha - 1)} d_{q}t \right\} \\ &\leq \lambda L \frac{1}{\Gamma_{q}(\alpha)} \left\{ \int_{0}^{1} (x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1}) d_{q}t + x_{1}^{\alpha} \int_{0}^{1} (1 - qt)^{(\alpha - 1)} d_{q}t - x_{2}^{\alpha} \int_{0}^{1} (1 - qt)^{(\alpha - 1)} d_{q}t \right\} \\ &= \lambda L \frac{1}{\Gamma_{q}(\alpha)} \left\{ \left( x_{2}^{\alpha - 1} - x_{1}^{\alpha - 1} \right) \int_{0}^{1} d_{q}t + \left( x_{1}^{\alpha} - x_{2}^{\alpha} \right) \int_{0}^{1} (1 - qt)^{(\alpha - 1)} d_{q}t \right\} \end{split}$$

$$\begin{split} &= \lambda L \frac{1}{\Gamma_q(\alpha)} \left\{ \left( x_2^{\alpha-1} - x_1^{\alpha-1} \right) (1-q) \sum_{n=0}^{\infty} q^n + \left( x_1^{\alpha} - x_2^{\alpha} \right) (1-q) \sum_{n=0}^{\infty} (1-q^{n+1})^{(\alpha-1)} q^n \right\} \\ &\leq \lambda L \frac{1}{\Gamma_q(\alpha)} \left( \left( x_2^{\alpha-1} - x_1^{\alpha-1} \right) + \left( x_1^{\alpha} - x_2^{\alpha} \right) \right) (1-q) \sum_{n=0}^{\infty} q^n \\ &= \lambda L \frac{1}{\Gamma_q(\alpha)} \left\{ \left( x_2^{\alpha-1} - x_1^{\alpha-1} \right) + \left( x_1^{\alpha} - x_2^{\alpha} \right) \right\} \\ &\leq \lambda L \frac{1}{\Gamma_q(\alpha)} \left( x_2^{\alpha-1} - x_1^{\alpha-1} \right). \end{split}$$

Now, we estimate  $x_2^{\alpha-1} - x_1^{\alpha-1}$ :

- (1) for  $0 \le x_1 < \delta$ ,  $\delta \le x_2 < 2\delta$ ,  $x_2^{\alpha 1} x_1^{\alpha 1} \le x_2^{\alpha 1} < (2\delta)^{\alpha 1} \le 2\delta$ ;
- (2) for  $0 \le x_1 < x_2 \le \delta$ ,  $x_2^{\alpha 1} x_1^{\alpha 1} \le x_2^{\alpha 1} < \delta^{\alpha 1} \le 2\delta$ ;
- (3) for  $\delta \le x_1 < x_2 \le 1$ , from the mean value theorem of differentiation, we have  $x_2^{\alpha-1} x_1^{\alpha-1} \le (\alpha 1)(x_2 x_1) \le 2\delta$ .

Thus, we have that

$$|A_{\lambda}u(x_2)-A_{\lambda}u(x_1)|<\frac{2\lambda L\delta}{\Gamma_q(\alpha)}<\varepsilon.$$

By means of the Arzela-Ascoli theorem,  $A_{\lambda}: P \to P$  is completely continuous. The proof is completed.

For convenience, we define

$$F_{0} = \limsup_{u \to 0^{+}} \frac{f(u)}{u}, \qquad F_{\infty} = \limsup_{u \to +\infty} \frac{f(u)}{u},$$
$$f_{0} = \liminf_{u \to 0^{+}} \frac{f(u)}{u}, \qquad f_{\infty} = \liminf_{u \to +\infty} \frac{f(u)}{u},$$
$$C_{1} = \int_{0}^{1} G(1,qt) d_{q}t, \qquad C_{2} = \int_{\tau}^{1} \tau^{2\alpha-2} G(1,qt) d_{q}t$$

The main results of the paper are as follows.

**Theorem 3.1** If  $f_{\infty}C_2 > F_0C_1$  holds, then for each

$$\lambda \in \left( (f_{\infty}C_2)^{-1}, (F_0C_1)^{-1} \right), \tag{3.2}$$

boundary value problem (1.1)-(1.2) has at least one positive solution. Here we impose  $(f_{\infty}C_2)^{-1} = 0$  if  $f_{\infty} = +\infty$  and  $(F_0C_1)^{-1} = +\infty$  if  $F_0 = 0$ .

*Proof* Let  $\lambda$  satisfy (3.2) and  $\varepsilon > 0$  be such that

$$\left((f_{\infty}-\varepsilon)C_{2}\right)^{-1} \leq \lambda \leq \left((F_{0}+\varepsilon)C_{1}\right)^{-1}.$$
(3.3)

By the definition of  $F_0$ , we can know that there exists  $r_1 > 0$  such that

$$f(u) \le (F_0 + \varepsilon)u \quad \text{for } 0 \le u \le r_1, \tag{3.4}$$

so if  $u \in P$  with  $||u|| = r_1$ , then by (2.3) and (3.4), we have

$$\begin{split} \|A_{\lambda}u\| &\leq \lambda \int_{0}^{1} G(1,qt) f(u(t)) d_{q}t \\ &\leq \lambda \int_{0}^{1} G(1,qt) (F_{0}+\varepsilon) r_{1} d_{q}t \\ &\leq \lambda (F_{0}+\varepsilon) r_{1} C_{1} \leq r_{1} \\ &= \|u\|. \end{split}$$

Hence, if we choose  $\Omega_1 = \{u \in B : ||u|| < r_1\}$ , then

$$\|A_{\lambda}\| \le \|u\| \quad \text{for } u \in P \cap \partial\Omega_1.$$
(3.5)

Let  $r_3 > 0$  be such that

$$f(u) \ge (f_{\infty} - \varepsilon)u \quad \text{for } u \ge r_3.$$
 (3.6)

If  $u \in P$  with  $||u|| = r_2 = \max\{2r_1, \tau^{1-\alpha}r_3\}$ , then by (2.3) and (3.6) we have

$$\begin{split} \|A_{\lambda}u\| &\geq A_{\lambda}(u(t)) = \lambda \int_{0}^{1} G(x,qt) f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} G(x,qt) f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{\alpha-1} G(1,qt) (f_{\infty} - \varepsilon) u(t) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{2\alpha-2} G(1,qt) (f_{\infty} - \varepsilon) \|u\| d_{q}t \\ &= \lambda C_{2} (f_{\infty} - \varepsilon) \|u\| \\ &\geq \|u\|. \end{split}$$

$$(3.7)$$

Thus, if we set

$$\Omega_2 = \{ u \in B : \|u\| < r_2 \}, \tag{3.8}$$

then

$$\|A_{\lambda}u\| \ge \|u\| \quad \text{for } u \in P \in \partial\Omega_2.$$
(3.9)

Now, from (3.5), (3.9) and Lemma 2.4, we conclude that  $A_{\lambda}$  has a fixed point  $u \in P \cap (\overline{\Omega}_2 \setminus \Omega_1)$  with  $r_1 \leq ||u|| \leq r_2$ , and it is clear that u is a positive solution of (1.1)-(1.2). The proof is completed.

**Theorem 3.2** If  $f_0C_2 > F_{\infty}C_1$  holds, then for each

$$\lambda \in \left( (f_0 C_2)^{-1}, (F_\infty C_1)^{-1} \right), \tag{3.10}$$

boundary value problem (1.1)-(1.2) has at least one positive solution. Here we impose  $(f_0C_2)^{-1} = 0$  if  $f_0 = +\infty$  and  $(F_{\infty}C_1)^{-1} = +\infty$  if  $F_{\infty} = 0$ .

*Proof* Let  $\lambda$  satisfy (3.10) and  $\varepsilon > 0$  be given such that

$$\left(\left(f_0 - \varepsilon\right)C_2\right)^{-1} \le \lambda \le \left(\left(F_\infty + \varepsilon\right)C_1\right)^{-1}.$$
(3.11)

From the definition of  $f_0$ , we can see that there exists  $r_1 > 0$  such that

$$f(u) \ge (f_0 - \varepsilon)u, \quad 0 < u \le r_1. \tag{3.12}$$

Further, if  $u \in P$ ,  $||u|| = r_1$ , then the flowing is similar to the second part of Theorem 3.1:

$$\begin{split} \|A_{\lambda}u\| &\geq \lambda \int_{0}^{1} G(x,qt) f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} G(x,qt) f(u(t)) dt \\ &\geq \lambda \int_{\tau}^{1} \tau^{\alpha-1} G(1,qt) f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{\alpha-1} G(1,qt) (f_{0}-\varepsilon) u(t) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{2\alpha-2} G(1,qt) (f_{0}-\varepsilon) \|u\| d_{q}t \\ &= \lambda C_{2} (f_{0}-\varepsilon) \|u\| \geq \|u\|. \end{split}$$

We can obtain that  $||A_{\lambda}u|| \ge ||u||$ . Thus, if we choose  $\Omega_1 = \{u \in B : ||u|| < r_1\}$ , then

$$\|A_{\lambda}u\| \ge \|u\| \quad \text{for } u \in P \cap \partial\Omega_1.$$
(3.13)

Next, we may choose  $R_1 > 0$  such that

$$f(u) \le (F_{\infty} + \varepsilon)u \quad \text{for } u \ge R_1.$$
 (3.14)

We consider two cases.

Case 1. Suppose that f is bounded. Then there exists some M > 0 such that  $f(u) \le M$  for  $u \in (0, +\infty)$ . Define  $r_3 = \max\{2r_1, \lambda MC_1\}$ . Then if  $u \in P$  with  $||u|| = r_3$ , we have

$$\|A_{\lambda}u\| \leq \lambda \int_0^1 G(1,qt) f(u(t)) d_q t \leq \lambda M \int_0^1 G(1,qt) d_q t \leq \lambda M C_1 \leq r_3 = \|u\|.$$

Hence,

$$||A_{\lambda}u|| \le ||u|| \quad \text{for } u \in (0, +\infty).$$
 (3.15)

Case 2. Suppose f is unbounded. Then there exists some  $r_4 > \max\{2r_1, \tau^{1-\alpha}R_1\}$  such that

$$f(u) \le f(r_4) \quad \text{for } 0 < u \le r_4.$$
 (3.16)

$$\begin{split} \|A_{\lambda}u\| &\leq \lambda \int_0^1 G(1,qt) f(u(t)) \, d_q t \leq \lambda \int_0^1 G(1,qt) (F_{\infty} + \varepsilon) u \, d_q t \\ &= \lambda C_1 (F_{\infty} + \varepsilon) \|u\| \leq \|u\|. \end{split}$$

Thus, (3.15) is also true.

In both Cases 1 and 2, if we set  $\Omega_2 = \{u \in B : ||u|| < r_2\}$ , where  $r_2 = \max\{r_3, r_4\}$ , then

$$\|A_{\lambda}\| \le \|u\| \quad \text{for } u \in P \cap \partial\Omega_2. \tag{3.17}$$

Now that we have obtained (3.13) and (3.17), it follows from Lemma 2.4 that  $A_{\lambda}$  has a fixed point  $u \in P \cap (\overline{\Omega}_2 \setminus \Omega_1)$  with  $r_1 \leq ||u|| \leq r_2$ . It is clear that u is a positive solution of (1.1)-(1.2). The proof is completed.

**Theorem 3.3** If there exist  $k_1 > k_2 > 0$  such that

$$\max_{0 \le u \le k_1} f(u) \le \frac{k_1}{\lambda C_1}, \qquad \min_{\tau \le u \le k_2} f(u) \ge \frac{k_2}{\lambda C_2},$$

then boundary value problem (1.1)-(1.2) has a positive solution  $u \in P$  with  $k_2 \leq ||u|| \leq k_1$ .

*Proof* Choose  $\Omega_1 = \{u \in B : ||u|| < k_2\}$ . Then, for  $u \in P \cap \partial \Omega_1$ , we have

$$\begin{split} \|A_{\lambda}u\| &\geq A_{\lambda}u(t) = \lambda \int_{0}^{1} G(x,qt)f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} G(1,qt)f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{\alpha-1}G(1,qt) \min_{\tau \leq u \leq k_{2}} f(u(t)) d_{q}t \\ &\geq \lambda \int_{\tau}^{1} \tau^{2\alpha-2}G(1,qt) \frac{k_{2}}{\lambda C_{2}} d_{q}t \\ &= \lambda C_{2} \frac{k_{2}}{\lambda C_{2}} = k_{2} = \|u\|. \end{split}$$

$$(3.18)$$

For another thing, choose  $\Omega_2 = \{u \in B : ||u|| < k_1\}$ , then, for  $u \in P \cap \partial \Omega_2$ , we have

$$\|A_{\lambda}u\| \leq \lambda \int_{0}^{1} G(1,qt) f(u(t)) d_{q}t \leq \lambda \int_{0}^{1} G(1,qt) \max_{0 \leq u \leq k_{1}} f(u(t)) d_{q}t$$
  
$$\leq \lambda \int_{0}^{1} G(1,qt) \frac{k_{1}}{\lambda C_{1}} d_{q}t = k_{1} = \|u\|.$$
(3.19)

Now that we have obtained (3.18) and (3.19), it follows from Lemma 2.4 that  $A_{\lambda}$  has a fixed point  $u \in P \cap (\overline{\Omega}_2 \setminus \Omega_1)$  with  $k_2 \leq ||u|| \leq k_1$ . It is clear that u is a positive solution of (1.1)-(1.2). The proof is completed.

# 4 Examples

In this section, we present some examples to illustrate our main results.

**Example 4.1** Consider the following boundary value problem:

$$\left(D_{\frac{1}{2}}^{\frac{3}{2}}u\right)(x) + \lambda u^{2} = 0, \quad 0 < t < 1,$$
(4.1)

$$u(0) = D_{\frac{1}{2}}(0) = D_{\frac{1}{2}}(1) = 0.$$
(4.2)

Let  $q = \tau = \frac{1}{2}$ ,  $\alpha = \frac{5}{2}$  and  $f(u) = u^2$ . Then

$$f_{\infty} = +\infty, \qquad F_0 = 0, \qquad C_1 = \int_0^1 G(1,qt) \, d_q t, \qquad C_2 = \int_{\tau}^1 \tau^{2\alpha-2} G(1,qt) \, d_q t,$$

and so  $f_{\infty}C_2 > F_0C_1$ . By Theorem 3.1, boundary value problem (4.1)-(4.2) has a positive solution for each  $\lambda \in (0, +\infty)$ .

**Example 4.2** Consider the following boundary value problem:

$$\left(D_{\frac{1}{2}}^{\frac{3}{2}}u\right)(x) + \lambda(2 + \sin u) = 0, \quad 0 < t < 1,$$
(4.3)

$$u(0) = D_{\frac{1}{2}}(0) = D_{\frac{1}{2}}(1) = 0.$$
(4.4)

Let  $q = \frac{1}{2}$ ,  $\alpha = \frac{5}{2}$  and  $f(u) = 2 + \sin u$ . Then  $f_0 = \infty$ ,  $F_{\infty} = 0$ ,

$$C_1 = \int_0^1 G(1,qt) \, d_q t, \qquad C_2 = \int_\tau^1 \tau^{2\alpha-2} G(1,qt) \, d_q t.$$

It is clear that  $F_{\infty}C_1 < f_0C_2$ . By Theorem 3.2, boundary value problem (4.3)-(4.4) has a positive solution for each  $\lambda \in (0, +\infty)$ .

**Example 4.3** We can still consider the example that has been given in Example 4.2,

$$\left(D_{\frac{1}{2}}^{\frac{3}{2}}u\right)(x) + \lambda(2 + \sin u) = 0, \quad 0 < t < 1,$$
(4.5)

$$u(0) = D_{\frac{1}{2}}(0) = D_{\frac{1}{2}}(1) = 0.$$
(4.6)

Here  $q = \frac{1}{2}$ ,  $\alpha = \frac{5}{2}$ ,  $f(u) = 2 + \sin u$ . Take  $0 < \tau < 1$ . Then

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$$C_1 = \int_0^1 G(1,qt) \, d_q t, \qquad C_2 = \int_\tau^1 \tau^{2\alpha-2} G(1,qt) \, d_q t$$

Set  $k_1 = 3\lambda C_1$ ,  $k_2 = \lambda C_2$  with  $\lambda > \frac{\tau}{c_2}$ . Then  $k_1 > k_2$ , and

$$\max_{0 \leq u \leq k_1} f(u) \leq 3 \leq \frac{k_1}{\lambda C_1}, \qquad \min_{\tau \leq u \leq k_2} f(u) \geq 1 \geq \frac{k_2}{\lambda C_2}.$$

Thus all the conditions in Theorem 3.3 hold. Hence, by Theorem 3.3, boundary value problem (4.5)-(4.6) has a positive solution with  $k_2 \le ||u|| \le k_1$ .

### **Competing interests**

The authors declare that they have no competing interests.

### Authors' contributions

The authors declare that the study was realized in collaboration with the same responsibility. All authors read and approved the final manuscript.

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