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# On oscillation of second-order neutral dynamic equations

Tao Ji<sup>1</sup>, Shuhong Tang<sup>1\*</sup> and Ethiraju Thandapani<sup>2</sup>

\*Correspondence: wfxytang@163.com  
<sup>1</sup>School of Information and Control Engineering, Weifang University, Weifang, Shandong 261061, P.R. China  
Full list of author information is available at the end of the article

## Abstract

Assuming

$$\int_{t_0}^{\infty} \frac{\Delta t}{r^{1/\gamma}(t)} < \infty,$$

a new oscillation criterion for a half-linear second-order neutral dynamic equation

$$(r(t)((x(t) + p(t)x(t - \tau))^{\Delta})^{\gamma})^{\Delta} + q(t)|x(t - \delta)|^{\gamma-1}x(t - \delta) = 0$$

is presented. An interesting example is provided to show that the delayed function  $\delta(t) = t - \delta$  plays an important role in the oscillatory behavior.

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**Keywords:** oscillation; neutral dynamic equation; time scale

## 1 Introduction

This work is concerned with the oscillatory behavior of solutions to a second-order half-linear neutral delay dynamic equation

$$(r(t)((x(t) + p(t)x(t - \tau))^{\Delta})^{\gamma})^{\Delta} + q(t)|x(t - \delta)|^{\gamma-1}x(t - \delta) = 0 \quad (1.1)$$

on a time scale  $\mathbb{T}$ , where  $t \in [t_0, \infty)_{\mathbb{T}} := [t_0, \infty) \cap \mathbb{T}$ . In what follows, we assume that  $\gamma \geq 1$  is a quotient of odd positive integers,  $\tau \geq 0, \delta \geq 0, t - \tau : \mathbb{T} \rightarrow \mathbb{T}, t - \delta : \mathbb{T} \rightarrow \mathbb{T}, r, p$ , and  $q$  are real-valued rd-continuous functions defined on  $\mathbb{T}$  such that  $r(t) > 0, \int_{t_0}^{\infty} r^{-1/\gamma}(t)\Delta t < \infty, 0 \leq p(t) \leq p_0 < \infty$ , and  $q(t) > 0$  for  $t \in [t_0, \infty)_{\mathbb{T}}$ .

By a solution of (1.1) we mean a nontrivial real-valued function  $x$  which has the properties  $x(t) + p(t)x(t - \tau) \in C_{\text{rd}}^1[t_x, \infty)_{\mathbb{T}}$  and  $r(t)((x(t) + p(t)x(t - \tau))^{\Delta})^{\gamma} \in C_{\text{rd}}^1[t_x, \infty)_{\mathbb{T}}, t_x \in [t_0, \infty)_{\mathbb{T}}$  and satisfying (1.1) for all  $t \in [t_x, \infty)_{\mathbb{T}}$ . Our attention is restricted to those solutions of (1.1) which exist on some half-line  $[t_x, \infty)_{\mathbb{T}}$  and satisfy  $\sup\{|x(t)| : t \in [t_1, \infty)_{\mathbb{T}}\} > 0$  for any  $t_1 \in [t_x, \infty)_{\mathbb{T}}$ . A solution  $x$  of (1.1) is said to be oscillatory if it is neither eventually positive nor eventually negative; otherwise, it is called nonoscillatory. Equation (1.1) is said to be oscillatory if all its solutions are oscillatory.

The theory of time scales, which has recently received a lot of attention, was introduced by Hilger in order to unify continuous and discrete analysis (see Hilger [1]). Several authors have expounded on various aspects of this new theory; see the survey paper by Agarwal

et al. [2] and the references cited therein. The books on the subject of time scales, by Bohner and Peterson [3, 4], summarize and organize much of time scale calculus and some applications of dynamic equations on time scales.

In recent years, there has been much research activity concerning the oscillatory and nonoscillatory behavior of solutions to various classes of differential, difference, and dynamic equations. We refer the reader to [5–28] and the references therein. If  $\mathbb{T} = \mathbb{R}$ , then  $\sigma(t) = t$ ,  $\mu(t) = 0$ ,  $x^\Delta(t) = x'(t)$ ,  $\int_a^b f(t)\Delta t = \int_a^b f(t) dt$ , and equation (1.1) becomes a second-order neutral delay differential equation

$$(r(t)((x(t) + p(t)x(t - \tau)))^\gamma)' + q(t)|x(t - \delta)|^{\gamma-1}x(t - \delta) = 0. \tag{1.2}$$

If  $\mathbb{T} = \mathbb{Z}$ , then  $\sigma(t) = t + 1$ ,  $\mu(t) = 1$ ,  $x^\Delta(t) = x(t + 1) - x(t)$ ,  $\int_a^b f(t)\Delta t = \sum_{t=a}^{b-1} f(t)$ , and equation (1.1) reduces to a second-order neutral delay difference equation

$$\Delta(r(t)(\Delta(x(t) + p(t)x(t - \tau)))^\gamma) + q(t)|x(t - \delta)|^{\gamma-1}x(t - \delta) = 0. \tag{1.3}$$

If  $\mathbb{T} = h\mathbb{Z}$  where  $h > 0$ , then  $\sigma(t) = t + h$ ,  $\mu(t) = h$ ,  $x^\Delta(t) = \Delta_h x(t) = (x(t + h) - x(t))/h$ ,  $\int_a^b f(t)\Delta t = \sum_{k=0}^{(b-a)/h-1} f(a + kh)h$ , and equation (1.1) becomes a second-order neutral delay difference equation

$$\Delta_h(r(t)(\Delta_h(x(t) + p(t)x(t - \tau)))^\gamma) + q(t)|x(t - \delta)|^{\gamma-1}x(t - \delta) = 0. \tag{1.4}$$

In what follows, we present some background details that motivate the contents of this note. Jiang and Li [5] studied oscillatory properties of equation (1.2) in the case  $\int_{t_0}^\infty r^{-1/\gamma}(t) dt = \infty$ . Saker [6] and Sun and Saker [7] considered oscillation of equation (1.3) and established some criteria under the assumption that  $\sum_{t=t_0}^\infty r^{-1/\gamma}(t) = \infty$ . To the best of our knowledge, there are few results for oscillation of equation (1.3) in the case where  $\sum_{i=t_0/h}^\infty r^{-1/\gamma}(ih) < \infty$ . Agarwal et al. [9], Saker [12], and Tripathy [15] studied oscillatory behavior of (1.1) in the case where  $\int_{t_0}^\infty r^{-1/\gamma}(t)\Delta t = \infty$ . In particular, Tripathy [15] established some oscillation tests for (1.1) assuming that  $0 \leq p(t) \leq p_0 < \infty$ .

The purpose of this paper is to obtain a new sufficient condition for oscillation of (1.1). The result obtained is essentially new for equations (1.2)-(1.4). This paper is organized as follows. In Section 2, we use the Riccati transformation technique to prove the main results. In Section 3, we apply our criterion in equations (1.2)-(1.4) to establish some new oscillation criteria.

## 2 Oscillation results

To prove the main results, we use the formula

$$(y^\gamma)^\Delta(t) = \gamma \int_0^1 [hy^\sigma(t) + (1-h)y(t)]^{\gamma-1} y^\Delta(t) dh, \tag{2.1}$$

which is a simple consequence of Keller's chain rule (see [3, Theorem 1.90]). We also need the following lemma.

**Lemma 2.1** (See [22, Lemma 1]) *Assume  $\gamma \geq 1$  and  $a, b \in \mathbb{R}$ . If  $a \geq 0$ ,  $b \geq 0$ , then*

$$a^\gamma + b^\gamma \geq \frac{(a+b)^\gamma}{2^{\gamma-1}}. \tag{2.2}$$

In what follows, all functional inequalities are assumed to be satisfied for all sufficiently large  $t$ .

**Theorem 2.2** Let  $\tilde{\mathbb{T}} := \{t - \tau : t \in \mathbb{T}\}$ . Suppose also that

$$\int_{t_0}^{\infty} Q(t) \Delta t = \infty \tag{2.3}$$

and

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left[ \frac{f^\gamma(\sigma(s))Q(s)}{2^{\gamma-1}} - (1 + p_0^\gamma) \left( \frac{\gamma}{\gamma + 1} \right)^{\gamma+1} \frac{(f(s))^{\gamma^2-1}}{f^{\gamma^2}(\sigma(s))r^{1/\gamma}(s)} \right] \Delta s = \infty, \tag{2.4}$$

where

$$Q(t) := \min\{q(t), q(t - \tau)\} \quad \text{and} \quad f(t) := \int_t^{\infty} \frac{\Delta s}{r^{1/\gamma}(s)}.$$

Then equation (1.1) is oscillatory.

*Proof* Suppose to the contrary that (1.1) has a nonoscillatory solution  $x$ . Without loss of generality, we may assume that there exists  $t_1 \in [t_0, \infty)_{\mathbb{T}}$  such that  $x(t - N) > 0$  for all  $t \in [t_1, \infty)_{\mathbb{T}}$ , where  $N := \max\{\tau, \delta\}$ . Set

$$z(t) := x(t) + p(t)x(t - \tau).$$

Then  $z(t) > 0$  and

$$(r(t)(z^\Delta(t))^\gamma)^\Delta = -q(t)x^\gamma(t - \delta) < 0$$

for  $t \in [t_1, \infty)_{\mathbb{T}}$ . Hence,  $r(z^\Delta)^\gamma$  is of one sign. On the other hand, we have by (1.1) and [3, Theorem 1.93] that

$$\begin{aligned} &(r(t)(z^\Delta(t))^\gamma)^\Delta + q(t)x^\gamma(t - \delta) + p_0^\gamma q(t - \tau)x^\gamma(t - \tau - \delta) \\ &+ p_0^\gamma (r(t - \tau)(z^\Delta(t - \tau))^\gamma)^\Delta = 0. \end{aligned}$$

Thus, we get by (2.2) that

$$(r(t)(z^\Delta(t))^\gamma)^\Delta + p_0^\gamma (r(t - \tau)(z^\Delta(t - \tau))^\gamma)^\Delta + \frac{Q(t)}{2^{\gamma-1}} z^\gamma(t - \delta) \leq 0. \tag{2.5}$$

If  $z^\Delta > 0$ , then by (2.5) there exist a constant  $k > 0$  and  $t_2 \in [t_1, \infty)_{\mathbb{T}}$  such that for  $t \in [t_2, \infty)_{\mathbb{T}}$ ,

$$Q(t) \leq -k(r(t)(z^\Delta(t))^\gamma)^\Delta - kp_0^\gamma (r(t - \tau)(z^\Delta(t - \tau))^\gamma)^\Delta.$$

Integrating the latter inequality from  $t_2$  to  $t$ , we have

$$\begin{aligned} \int_{t_2}^t Q(s)\Delta s &\leq k(r(t_2)(z^\Delta(t_2))^\gamma - r(t)(z^\Delta(t))^\gamma) \\ &\quad + kp_0^\gamma(r(t_2 - \tau)(z^\Delta(t_2 - \tau))^\gamma - r(t - \tau)(z^\Delta(t - \tau))^\gamma) \\ &\leq kr(t_2)(z^\Delta(t_2))^\gamma + kp_0^\gamma r(t_2 - \tau)(z^\Delta(t_2 - \tau))^\gamma, \end{aligned}$$

which contradicts (2.3).

Assume now that  $z^\Delta < 0$ . Define a Riccati substitution

$$\omega(t) := \frac{r(t)(z^\Delta(t))^\gamma}{z^\gamma(t)}. \tag{2.6}$$

Then  $\omega(t) < 0$ . Noticing that  $r(z^\Delta)^\gamma$  is decreasing, we have

$$(r(s))^{1/\gamma} z^\Delta(s) \leq (r(t))^{1/\gamma} z^\Delta(t), \quad s \geq t.$$

Dividing the latter inequality by  $(r(s))^{1/\gamma}$  and integrating the resulting inequality from  $t$  to  $l$ , we get

$$z(l) \leq z(t) + (r(t))^{1/\gamma} z^\Delta(t) \int_t^l \left(\frac{1}{r(s)}\right)^{1/\gamma} \Delta s.$$

Note that  $\lim_{l \rightarrow \infty} z(l) \geq 0$ . Letting  $l \rightarrow \infty$  in the above inequality, we obtain  $0 \leq z(t) + (r(t))^{1/\gamma} z^\Delta(t)f(t)$ , which implies that

$$\frac{(r(t))^{1/\gamma} z^\Delta(t)}{z(t)} f(t) \geq -1.$$

Then we have by (2.6) that

$$-1 \leq \omega(t)f^\gamma(t) \leq 0. \tag{2.7}$$

Similarly, we define another Riccati transformation

$$u(t) := \frac{r(t - \tau)(z^\Delta(t - \tau))^\gamma}{z^\gamma(t)}. \tag{2.8}$$

Then  $u(t) < 0$ . Noting that  $r(z^\Delta)^\gamma$  is decreasing, we have  $r(t - \tau)(z^\Delta(t - \tau))^\gamma \geq r(t)(z^\Delta(t))^\gamma$ , and so  $u(t) \geq \omega(t)$ . From (2.7), we have

$$-1 \leq u(t)f^\gamma(t) \leq 0. \tag{2.9}$$

Differentiating (2.6), we get

$$\omega^\Delta(t) = \frac{(r(t)(z^\Delta(t))^\gamma)^\Delta z^\gamma(t) - r(t)(z^\Delta(t))^\gamma (z^\gamma(t))^\Delta}{z^\gamma(t)z^\gamma(\sigma(t))}. \tag{2.10}$$

By virtue of (2.1), we obtain

$$(z^\gamma(t))^\Delta \leq \gamma z^\Delta(t)(z^\sigma(t))^{\gamma-1}. \tag{2.11}$$

Using (2.11) in (2.10), we have

$$\omega^\Delta(t) \leq \frac{(r(t)(z^\Delta(t))^\gamma)^\Delta}{z^\gamma(\sigma(t))} - \gamma \frac{r(t)(z^\Delta(t))^{\gamma+1}}{z^\gamma(t)z(\sigma(t))}.$$

By (2.6) and the latter inequality, we find

$$\omega^\Delta(t) \leq \frac{(r(t)(z^\Delta(t))^\gamma)^\Delta}{z^\gamma(\sigma(t))} - \gamma \frac{(\omega(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}} \tag{2.12}$$

due to  $z(t) \geq z(\sigma(t))$ . Differentiating (2.8), we obtain

$$u^\Delta(t) = \frac{(r(t-\tau)(z^\Delta(t-\tau))^\gamma)^\Delta z^\gamma(t) - r(t-\tau)(z^\Delta(t-\tau))^\gamma (z^\gamma(t))^\Delta}{z^\gamma(t)z^\gamma(\sigma(t))}. \tag{2.13}$$

Using (2.11) in (2.13), we have

$$u^\Delta(t) \leq \frac{(r(t-\tau)(z^\Delta(t-\tau))^\gamma)^\Delta}{z^\gamma(\sigma(t))} - \gamma \frac{r(t-\tau)(z^\Delta(t-\tau))^\gamma z^\Delta(t)}{z^\gamma(t)z(\sigma(t))}. \tag{2.14}$$

From (2.8), (2.14), and the fact that  $r(t)(z^\Delta(t))^\gamma \leq r(t-\tau)(z^\Delta(t-\tau))^\gamma$ , we get

$$u^\Delta(t) \leq \frac{(r(t-\tau)(z^\Delta(t-\tau))^\gamma)^\Delta}{z^\gamma(\sigma(t))} - \gamma \frac{(u(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}}. \tag{2.15}$$

Thus, by (2.12) and (2.15), we have

$$\begin{aligned} \omega^\Delta(t) + p_0^\gamma u^\Delta(t) &\leq \frac{(r(t)(z^\Delta(t))^\gamma)^\Delta + p_0^\gamma (r(t-\tau)(z^\Delta(t-\tau))^\gamma)^\Delta}{z^\gamma(\sigma(t))} \\ &\quad - \gamma \frac{(\omega(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}} - p_0^\gamma \gamma \frac{(u(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}}. \end{aligned}$$

Using  $z(t-\delta) \geq z(\sigma(t))$  and (2.5) yields

$$\omega^\Delta(t) + p_0^\gamma u^\Delta(t) \leq -\frac{Q(t)}{2^{\gamma-1}} - \gamma \frac{(\omega(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}} - p_0^\gamma \gamma \frac{(u(t))^{\gamma+1}/\gamma}{(r(t))^{1/\gamma}}.$$

Multiplying the latter inequality by  $f^\gamma(\sigma(t))$  and integrating the resulting inequality on  $[t_2, t]_{\mathbb{T}}$  ( $t_2 \in [t_1, \infty)_{\mathbb{T}}$  sufficiently large), we obtain

$$\begin{aligned} \omega(t)f^\gamma(t) - \omega(t_2)f^\gamma(t_2) - \int_{t_2}^t (f^\gamma(s))^\Delta \omega(s)\Delta s + p_0^\gamma u(t)f^\gamma(t) \\ - p_0^\gamma u(t_2)f^\gamma(t_2) - p_0^\gamma \int_{t_2}^t (f^\gamma(s))^\Delta u(s)\Delta s \end{aligned}$$

$$\begin{aligned} &\leq - \int_{t_2}^t \frac{f^\gamma(\sigma(s))Q(s)}{2^{\gamma-1}} \Delta s - \gamma \int_{t_2}^t \frac{(\omega(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s \\ &\quad - \gamma p_0^\gamma \int_{t_2}^t \frac{(u(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s. \end{aligned} \tag{2.16}$$

Hence, by (2.1) and  $f^\Delta = -r^{-1/\gamma} < 0$ , we get

$$\int_{t_2}^t (f^\gamma(s))^\Delta \omega(s) \Delta s \leq -\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{\omega(s)}{(r(s))^{1/\gamma}} \Delta s.$$

Similarly, we have

$$\int_{t_2}^t (f^\gamma(s))^\Delta u(s) \Delta s \leq -\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{u(s)}{(r(s))^{1/\gamma}} \Delta s.$$

Therefore, we obtain by (2.16) that

$$\begin{aligned} &\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{\omega(s)}{(r(s))^{1/\gamma}} \Delta s + \gamma \int_{t_2}^t \frac{(\omega(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s \\ &\quad + \gamma p_0^\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{u(s)}{(r(s))^{1/\gamma}} \Delta s + \gamma p_0^\gamma \int_{t_2}^t \frac{(u(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s \\ &\quad + \int_{t_2}^t \frac{f^\gamma(\sigma(s))Q(s)}{2^{\gamma-1}} \Delta s \\ &\leq -\omega(t)f^\gamma(t) + \omega(t_2)f^\gamma(t_2) - p_0^\gamma u(t)f^\gamma(t) + p_0^\gamma u(t_2)f^\gamma(t_2). \end{aligned} \tag{2.17}$$

Let  $\chi = -\omega(t)$ ,

$$A = \frac{\gamma f^\gamma(\sigma(s))}{(r(s))^{1/\gamma}}, \quad \text{and} \quad B = \frac{\gamma (f(s))^{\gamma-1}}{(r(s))^{1/\gamma}}.$$

Using the inequality

$$A\chi^{(\gamma+1)/\gamma} - B\chi \geq -\frac{\gamma^\gamma}{(\gamma+1)^{\gamma+1}} \frac{B^{\gamma+1}}{A^\gamma},$$

where  $A > 0$  is a constant, we get

$$\begin{aligned} &\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{\omega(s)}{(r(s))^{1/\gamma}} \Delta s + \gamma \int_{t_2}^t \frac{(\omega(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s \\ &\geq -\left(\frac{\gamma}{\gamma+1}\right)^{\gamma+1} \int_{t_2}^t \frac{(f(s))^{\gamma^2-1}}{f^{\gamma^2}(\sigma(s))r^{1/\gamma}(s)} \Delta s. \end{aligned}$$

Similarly, we have

$$\begin{aligned} &\gamma \int_{t_2}^t (f(s))^{\gamma-1} \frac{u(s)}{(r(s))^{1/\gamma}} \Delta s + \gamma \int_{t_2}^t \frac{(u(s))^{\gamma+1/\gamma}}{(r(s))^{1/\gamma}} f^\gamma(\sigma(s)) \Delta s \\ &\geq -\left(\frac{\gamma}{\gamma+1}\right)^{\gamma+1} \int_{t_2}^t \frac{(f(s))^{\gamma^2-1}}{f^{\gamma^2}(\sigma(s))r^{1/\gamma}(s)} \Delta s. \end{aligned}$$

Therefore, (2.17) implies that

$$\int_{t_2}^t \left[ \frac{f^\gamma(\sigma(s))Q(s)}{2^{\gamma-1}} - (1+p_0^\gamma) \left( \frac{\gamma}{\gamma+1} \right)^{\gamma+1} \frac{(f(s))^{\gamma^2-1}}{f^{\gamma^2}(\sigma(s))r^{1/\gamma}(s)} \right] \Delta s$$

$$\leq -\omega(t)f^\gamma(t) - p_0^\gamma u(t)f^\gamma(t) \leq 1 + p_0^\gamma$$

due to (2.7) and (2.9), which contradicts (2.4). The proof is complete.  $\square$

**Remark 2.3** Theorem 2.2 complements the results obtained in [23] since it can be applied in the case where  $\gamma > 1$ .

### 3 Applications

Due to Theorem 2.2, we present the following results for oscillation of equations (1.2)-(1.4).

**Corollary 3.1** Assume  $\mathbb{T} = \mathbb{R}$  and let

$$\int_{t_0}^{\infty} Q(t) dt = \infty$$

and

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left[ \frac{\theta^\gamma(s)Q(s)}{2^{\gamma-1}} - (1+p_0^\gamma) \left( \frac{\gamma}{\gamma+1} \right)^{\gamma+1} \frac{1}{\theta(s)r^{1/\gamma}(s)} \right] ds = \infty,$$

where  $Q$  is defined as in Theorem 2.2 and

$$\theta(t) := \int_t^{\infty} \frac{ds}{r^{1/\gamma}(s)}.$$

Then equation (1.2) oscillates.

**Corollary 3.2** Assume  $\mathbb{T} = \mathbb{Z}$  and let

$$\sum_{t=t_0}^{\infty} Q(t) = \infty$$

and

$$\limsup_{t \rightarrow \infty} \sum_{s=t_0}^{t-1} \left[ \frac{\beta^\gamma(s+1)Q(s)}{2^{\gamma-1}} - (1+p_0^\gamma) \left( \frac{\gamma}{\gamma+1} \right)^{\gamma+1} \frac{(\beta(s))^{\gamma^2-1}}{\beta^{\gamma^2}(s+1)r^{1/\gamma}(s)} \right] = \infty,$$

where  $Q$  is defined as in Theorem 2.2 and

$$\beta(t) := \sum_{s=t}^{\infty} \frac{1}{r^{1/\gamma}(s)}.$$

Then equation (1.3) oscillates.

**Corollary 3.3** Assume  $\mathbb{T} = h\mathbb{Z}$ ,  $h > 0$ , and let

$$\sum_{i=\frac{t_0}{h}}^{\infty} Q(ih) = \infty$$

and

$$\limsup_{t \rightarrow \infty} \sum_{i=\frac{t_0}{h}}^{\frac{t}{h}-1} \left[ \frac{\xi^\gamma((i+1)h)Q(ih)}{2^{\gamma-1}} - (1+p_0^\gamma) \left( \frac{\gamma}{\gamma+1} \right)^{\gamma+1} \frac{(\xi(ih))^{\gamma^2-1}}{\xi^{\gamma^2}((i+1)h)r^{1/\gamma}(ih)} \right] = \infty,$$

where  $Q$  is defined as in Theorem 2.2 and

$$\xi(t) := \sum_{i=\frac{t}{h}}^{\infty} \frac{1}{r^{1/\gamma}(ih)}.$$

Then equation (1.4) oscillates.

**Example 3.4** For  $t \geq 1$ , consider a second-order neutral delay differential equation

$$\left( e^{2t} \left( x(t) + \frac{1}{2}x(t-2) \right) \right)' + \left( e^{2t} + \frac{1}{2}e^{2t+2} \right) x(t-3) = 0. \tag{3.1}$$

It is not difficult to verify that all conditions of Theorem 2.2 are satisfied. Hence, equation (3.1) is oscillatory. However, the equation

$$\left( e^{2t} \left( x(t) + \frac{1}{2}x(t-2) \right) \right)' + \left( e^{2t} + \frac{1}{2}e^{2t+2} \right) x(t) = 0$$

has a nonoscillatory solution  $x(t) = e^{-t}$ . Therefore, the delayed argument  $\delta(t) = t - \delta$  plays an important role in oscillation of equation (1.1).

**Remark 3.5** It would be of interest to find another method to study the equation

$$(r(t)((x(t) + p(t)x(\tau(t)))^\Delta)^\gamma)^\Delta + q(t)|x(\delta(t))|^{\gamma-1}x(\delta(t)) = 0,$$

where  $p(t) < 0$  or  $p(t) > 0$ .

**Competing interests**

The authors declare that they have no competing interests.

**Authors' contributions**

All authors contributed equally to this paper and also read and approved the final manuscript.

**Author details**

<sup>1</sup>School of Information and Control Engineering, Weifang University, Weifang, Shandong 261061, P.R. China. <sup>2</sup>Ramanujan Institute for Advanced Study in Mathematics, University of Madras, Chennai, 600 005, India.

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