# Chebyshev reproducing kernel method: application to two-point boundary value problems 

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#### Abstract

In this paper, a new implementation of the reproducing kernel method is proposed in order to obtain the accurate numerical solution of two-point boundary value problems with Dirichlet boundary conditions. Based on reproducing kernel theory, reproducing kernel functions with polynomial form will be constructed in the reproducing kernel spaces spanned by the Chebyshev basis polynomials. Convergence analysis and an error estimation for the present method in $L_{w}^{2}$ space is also discussed. The numerical solutions obtained by this method are compared with the exact solutions. The results reveal that the proposed method is quite efficient and accurate.


Keywords: two-point boundary value problem; Dirichlet boundary conditions; polynomial reproducing kernel; Chebyshev polynomials; convergence; error estimation

## 1 Introduction

Boundary value problems (BVPs) associated with different kinds of differential equations play important roles in modeling a wide variety of natural phenomena. Therefore, these problems have attracted much attention and have been fascinating to a number of researchers. Two-point boundary value problems associated with second order differential equations have been investigated in a wide variety of problems in science and engineering. Many approaches for solving ordinary boundary value problems numerically are available [1-12]. Recently, reproducing kernel methods (RKMs) were used to solving a variety of BVPs [13-24].

According to these references, we see that the implementation of the reproducing kernel method for solving a problem consists of four stages
First, we carefully identify a solution space. An inappropriate choice is an obstacle to achieve the desired solution.

Second, we construct the reproducing kernel function. In all of the above mentioned papers, this function is constructed by solving a boundary value problem and a subsequent linear system of equations. Explicit formulas for two kinds of reproducing kernel functions are introduced in [25].

Third, we produce a set of orthonormal basis functions for the space solution by using the kernel function, a boundary operator, a dense sequence of nodal points in the domain of solution space and Gram-Schmidt orthogonalization process.

Finally, we represent the exact solution of the problem by an infinite sum of orthonormal basis functions achieved from the last stage above. We use a truncated series of the exact solution series by N terms as an approximate solution.
Here, we consider the following second order two-point boundary value problems with the Dirichlet boundary conditions:

$$
\left\{\begin{array}{l}
u^{\prime \prime}+p(x) u^{\prime}+q(x) u=f(x), \quad a \leq x \leq b  \tag{1}\\
u(a)=\alpha \\
u(b)=\beta
\end{array}\right.
$$

where $p, q \in C^{2}(a, b)$ and $f \in L_{w}^{2}[a, b]$ are sufficiently regular given functions such that equation (1) satisfies the existence and uniqueness of the solution. $\alpha, \beta$ are finite constants. Without loss of generality, we can assume that the boundary conditions in equation (1) are homogeneous [13]. In this paper, based on reproducing kernel theory, reproducing kernels with polynomial form will be constructed and a computational method is described in order to obtain the accurate numerical solution with polynomial form of equation (1) in the reproducing kernel spaces spanned by the Chebyshev basis polynomials. The paper is organized as follows. In the following section, a proper closed form of the Chebyshev orthonormal basis polynomials which independently satisfy the homogeneous boundary conditions on $[a, b]$ will be introduced. In addition, a reproducing kernel with polynomial form will be constructed. In Section 3, our method as a Chebyshev reproducing kernel method (C-RKM) is introduced. A convergence analysis and an error estimation for the present method in $L_{w}^{2}$ space is also discussed. Examples are given to illustrate the applicability and accuracy in Section 4, and a few conclusions are presented in Section 5.

## 2 Basis functions and polynomial reproducing kernel function

### 2.1 Basis functions

The well-known shifted Chebyshev polynomials of the first kind in $x$ are defined on $[a, b]$ and can be determined with the aid of the following recurrence formula:

$$
\begin{aligned}
& T_{0}(x)=1, \quad T_{1}(x)=\frac{2 x-(a+b)}{b-a}, \\
& T_{n}(x)=2\left(\frac{2 x-(a+b)}{b-a}\right) T_{n-1}(x)-T_{n-2}(x), \quad n=2,3, \ldots
\end{aligned}
$$

The orthogonality condition is

$$
\left\langle T_{n}, T_{m}\right\rangle=\int_{a}^{b} w_{[a, b]}(x) T_{n}(x) T_{m}(x) d x= \begin{cases}0, & n \neq m,  \tag{2}\\ \frac{(b-a) \pi}{2}, & n=m=0, \\ \frac{(b-a) \pi}{4}, & n=m \neq 0\end{cases}
$$

where

$$
\begin{equation*}
w_{[a, b]}(x)=\frac{1}{\sqrt{1-\left(\frac{2 x-a-b}{b-a}\right)^{2}}} . \tag{3}
\end{equation*}
$$

In solving boundary value problems, use of basis functions that independently satisfy the boundary conditions are useful. So we construct Chebyshev basis functions that independently satisfy the homogeneous boundary conditions such as

$$
\begin{equation*}
u(a)=u(b)=0 . \tag{4}
\end{equation*}
$$

Lemma 2.1 ([26]) The functions defined by

$$
\varphi_{n}(x)=\left\{\begin{array}{ll}
T_{n}(x)-T_{0}(x), & n \text { is even },  \tag{5}\\
T_{n}(x)-T_{1}(x), & n \text { is odd, }
\end{array} \quad n \geq 2,\right.
$$

have the property

$$
\varphi_{n}(a)=\varphi_{n}(b)=0,
$$

for all $n$ and for the function space satisfying the boundary conditions equation (4), the basis functions defined by equation (5) are complete.

Proposition 2.1 Let $\left\{\varphi_{n}\right\}_{n=2}^{\infty}$ be the basis functions defined by equation (5), then the GramSchmidt process gives a corresponding orthonormal basisfunctions $\left\{h_{n}\right\}_{n=2}^{\infty}$ such that $h_{i}$, for $i=2,3, \ldots$, has the following closed form:

$$
h_{i}(x)=2 \sqrt{\frac{(i-1)}{(i+1)(b-a) \pi}} \begin{cases}T_{i}(x)-\frac{2}{i-1} \sum_{k=1}^{\frac{i-2}{2}} T_{2 k}(x)-\frac{1}{i-1}, & \text { i is even },  \tag{6}\\ T_{i}(x)-\frac{2}{i-1} \sum_{k=1}^{\frac{i-1}{2}} T_{2 k-1}(x), & \text { i is odd }\end{cases}
$$

Proof Use Lemma 2.1 and induction on $i$, which completes the proof.

### 2.2 Polynomial reproducing kernel function

Definition 2.1 ( $[13,27])$ For a nonempty set $\mathcal{X}$, let $\left(\mathcal{H},\langle\cdot, \cdot\rangle_{\mathcal{H}}\right)$ be a Hilbert space of realvalued functions on some set $\mathcal{X}$. A function $R: \mathcal{X} \times \mathcal{X} \longrightarrow \mathbb{R}$ is said to be the reproducing kernel function of $\mathcal{H}$ if and only if

1. $R(x, \cdot) \in \mathcal{H}, \forall x \in \mathcal{X}$,
2. $\langle\varphi(\cdot), R(x, \cdot)\rangle_{\mathcal{H}}=\varphi(x), \forall \varphi \in \mathcal{H}, \forall x \in \mathcal{X}$ (reproducing property).

Also, a Hilbert space of functions $\left(\mathcal{H},\langle\cdot, \cdot\rangle_{\mathcal{H}}\right)$ that possesses a reproducing kernel $R$ is a reproducing kernel Hilbert space (RKHS); we denote it by $\left(\mathcal{H},\langle\cdot, \cdot\rangle_{\mathcal{H}}, R\right)$. In the following we often denote by $R_{y}$ the function $R(y, \cdot): t \longmapsto R(y, t)$.

Theorem 2.1 ([28], Theorem 3.7) Every finite-dimensional inner product space is complete. Let $M$ be a finite-dimensional subspace of the inner product space $V$ where:

1. each bounded sequence in $M$ has a subsequence that converges to a point in $M$;
2. $M$ is closed;
3. $M$ is complete;
4. suppose $\left\{x_{1}, x_{2}, \ldots, x_{n}\right\}$ is a basis for $M, y_{k}=\sum_{i=1}^{n} \alpha_{k i} x_{i}$, and $y=\sum_{1}^{n} \alpha_{i} x_{i}$. Then $y_{k} \rightarrow y$ if and only if $\alpha_{k i} \rightarrow \alpha_{i}$ for $i=1,2, \ldots, n$.

Theorem 2.2 ([13], Theorem 1.1.2) If $\mathcal{H}$ is an n-dimensional Hilbert space, $\left\{e_{i}\right\}_{i=1}^{n}$ is an orthonormal basis, $x \in X$, and $X$ is an abstract set, then, for any fixed $y \in X$,

$$
\begin{equation*}
R_{y}(x)=\sum_{i=1}^{n} e_{i}(x) \bar{e}_{i}(y) \tag{7}
\end{equation*}
$$

is the reproducing kernel function of $\mathcal{H}$.

Let $\Pi_{w}^{m}[a, b]$ be the weighted inner product space of polynomials on $[a, b]$ with real coefficients and degree less than or equal to $m$ with inner product

$$
\langle u, v\rangle_{\Pi_{w}^{m}}=\int_{a}^{b} w_{[a, b]}(x) u(x) v(x) d x, \quad \forall u, v \in \Pi_{w}^{m}[a, b],
$$

with $w_{[a, b]}(x)$ defined by equation (3), and the norm

$$
\|u\|_{\Pi_{w}^{m}}=\sqrt{\langle u, u\rangle_{\Pi_{w}^{m}}}, \quad \forall u \in \Pi_{w}^{m}[a, b] .
$$

Since $L_{w}^{2}[a, b]=\left\{\left.f\left|\int_{a}^{b} w_{[a, b]}(x)\right| f(x)\right|^{2} d x<\infty\right\}$ it can easily be shown that for any fixed $m$ $\Pi_{w}^{m}[a, b]$ is a subspace of $L_{w}^{2}[a, b]$ and $\forall u, v \in \Pi_{w}^{m}[a, b],\langle u, v\rangle_{\Pi_{w}^{m}}=\langle u, v\rangle_{L_{w}^{2}}$.

Theorem 2.3 The function space $\Pi_{w}^{m}[a, b]$ by its inner product and norm (mentioned above) is a reproducing kernel Hilbert space.

Proof It is clear that $\Pi_{w}^{m}[a, b]$ is a finite-dimensional inner product space, so by Theorems 2.1 and 2.2, $\Pi_{w}^{m}[a, b]$ is a RKHS, which completes the proof.

For practical use of the RKM method, it is necessary to define a closed subspace of $\Pi_{w}^{m}[a, b]$ by imposing required homogeneous boundary conditions on it.

Definition 2.2 Let

$$
{ }^{o} \Pi_{w}^{m}[a, b]=\left\{u \mid u \in \Pi_{w}^{m}[a, b], u(a)=u(b)=0\right\} .
$$

So similar to the proof of Theorem 2.3, by using equation (5), we can prove that the function space ${ }^{o} \Pi_{w}^{m}[a, b]$ is a reproducing kernel Hilbert space.
According to the Theorem 2.2 and Proposition 2.1, the polynomial reproducing kernel function $R_{y}^{m}(x)$ of ${ }^{o} \Pi_{w}^{m}[a, b]$ obeys the expression

$$
\begin{equation*}
R_{y}^{m}(x)=\sum_{i=2}^{m} h_{i}(x) h_{i}(y) . \tag{8}
\end{equation*}
$$

Equation (8) shows that the polynomial reproducing kernel function $R_{y}^{m}(x)$ not only can easily be constructed by a finite sum of basis functions, also this kernel function and the associated reproducing kernel Hilbert space $\Pi_{w}^{m}[a, b]$ can easily be updated by increasing $m$.

Theorem 2.4 ([13], Theorem 1.3.5) The reproducing kernel space ${ }^{o} \Pi_{w}^{m}[a, b]$ is a closed subspace of $\Pi_{w}^{m}[a, b]$.

## 3 The Chebyshev reproducing kernel method (C-RKM)

### 3.1 Representation of exact solution in ${ }^{\circ} \Pi_{w}^{m}[a, b]$

Here, we develop a polynomial reproducing kernel computational method for solving equation (1). We assume that the solution of the problem exists and is unique. Also let the problem be transformed into the following operator form:

$$
\left\{\begin{array}{l}
(\mathbb{L} u)(x)=f(x), \quad a \leq x \leq b  \tag{9}\\
u(a)=u(b)=0
\end{array}\right.
$$

where

$$
\begin{aligned}
& \mathbb{L}:=\frac{d^{2}}{d x^{2}}+p(x) \frac{d}{d x}+q(x), \\
& \mathbb{L}:{ }^{o} \Pi_{w}^{m}[a, b] \longrightarrow L_{w}^{2}[a, b],
\end{aligned}
$$

is a bounded linear operator. We shall give the representation of an analytical solution of equation (9) in the space ${ }^{o} \Pi_{w}^{m}[a, b]$. Let $R_{y}^{m}(x)$ be the polynomial reproducing kernel function of ${ }^{o} \Pi_{w}^{m}[a, b]$. For any fixed $x_{i} \in[a, b]$, put

$$
\begin{equation*}
\psi_{i}^{m}(x)=\mathbb{L}^{*} R_{x_{i}}^{m}(x)=\left.\mathbb{L}_{y} R_{y}^{m}(x)\right|_{y=x_{i}}, \tag{10}
\end{equation*}
$$

where $\mathbb{L}^{*}$ is the adjoint operator of $\mathbb{L}$ and the subscript $y$ in the operator $\mathbb{L}$ indicates that the operator $\mathbb{L}$ applies to the function $y$. It is clear that, for any fixed $m$ and $x_{i} \in[a, b]$, $\psi_{i}^{m} \in{ }^{o} \Pi_{w}^{m}[a, b]$.

Theorem 3.1 For $m \geq 2$, let $\left\{x_{i}\right\}_{i=0}^{m-2}$ be any $(m-1)$-distinct points in $(a, b)$, then $\left\{\psi_{i}^{m}\right\}_{i=0}^{m-2}$ is a basis for ${ }^{o} \Pi_{w}^{m}[a, b]$.

Proof For each fixed $u \in{ }^{o} \Pi_{w}^{m}[a, b]$, let

$$
\left\langle u(\cdot), \psi_{i}^{m}(\cdot)\right\rangle_{o \Pi_{w}^{m}}=0, \quad i=0,1, \ldots, m-2,
$$

which means that, for $i=0,1,2, \ldots, m-2$,

$$
0=\left\langle u(\cdot),\left.\mathbb{L}_{y} R_{y}^{m}(\cdot)\right|_{y=x_{i}}\right\rangle_{o_{w}^{m}}=\left.\mathbb{L}_{y}\left(u(\cdot), R_{y}^{m}(\cdot)\right\rangle_{o_{\Pi_{w}^{m}}^{m}}\right|_{y=x_{i}}=\mathbb{L} u\left(x_{i}\right) .
$$

So from the existence of $\mathbb{L}^{-1}$,

$$
u\left(x_{i}\right)=0, \quad i=0,1,2, \ldots, m-2 .
$$

Since $u(a)=u(b)=0$ we have $u \equiv 0$. Therefore, $\left\{\psi_{i}^{m}\right\}_{i=0}^{m-2}$ is a complete system for ${ }^{o} \Pi_{w}^{m}[a, b]$, which completes the proof.

Theorem 3.1 shows that, in our method (C-RKM), use of a finite sequence of nodal points is sufficient. So, implementation of C-RKM for solving problems does not need a dense sequence of nodal points.

The orthonormal system $\left\{\bar{\psi}_{i}^{m}\right\}_{i=0}^{m-2}$ of ${ }^{o} \prod_{w}^{m}[a, b]$ can be deduced from the Gram-Schmidt orthogonalization process using $\left\{\psi_{i}^{m}\right\}_{i=0}^{m-2}$,

$$
\begin{equation*}
\bar{\psi}_{i}^{m}(x)=\sum_{k=0}^{i} \beta_{i k}^{m} \psi_{k}^{m}(x) \tag{11}
\end{equation*}
$$

where $\beta_{i k}^{m}$ are orthogonalization coefficients.

Theorem 3.2 Suppose that $u_{m}$ is the unique exact solution of equation (9) in ${ }^{o} \Pi_{w}^{m}[a, b]$ Let $\left\{x_{i}\right\}_{i=0}^{m-2}$ be any $(m-1)$-distinct points in $(a, b)$, then

$$
\begin{equation*}
u_{m}(x)=\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m} f\left(x_{k}\right) \bar{\psi}_{i}^{m}(x) . \tag{12}
\end{equation*}
$$

Proof Since $u_{m} \in{ }^{o} \Pi_{w}^{m}[a, b]$ by Theorem 3.1 we have

$$
u_{m}(x)=\sum_{i=0}^{m-2}\left\langle u_{m}(\cdot), \bar{\psi}_{i}^{m}(\cdot)\right\rangle_{o \Pi_{w}^{m}} \bar{\psi}_{i}^{m}(x) .
$$

On the other hand, using equations (10), (11), and this fact that $u_{m}$ is the unique exact solution of equation (9) in ${ }^{o} \Pi_{w}^{m}[a, b]$, we have

$$
\begin{aligned}
u_{m}(x) & =\sum_{i=0}^{m-2}\left\langle u_{m}(\cdot), \bar{\psi}_{i}^{m}(\cdot)\right\rangle_{{ }_{\Pi_{w}^{m}}^{m}} \bar{\psi}_{i}^{m}(x) \\
& =\sum_{i=0}^{m-2}\left\langle u_{m}(\cdot), \sum_{k=0}^{i} \beta_{i k}^{m} \psi_{k}^{m}(\cdot)\right\rangle_{o \Pi_{w}^{m}} \bar{\psi}_{i}^{m}(x) \\
& =\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m}\left\langle u_{m}(\cdot), \psi_{k}^{m}(\cdot)\right\rangle_{{ }_{o} \Pi_{w}^{m}} \bar{\psi}_{i}^{m}(x) \\
& =\left.\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m}\left\langle u_{m}(\cdot), \mathbb{L}_{y} R_{y}^{m}(\cdot)\right\rangle_{{ }_{o} \Pi_{w}^{m}}\right|_{y=x_{k}} \bar{\psi}_{i}^{m}(x) \\
& =\left.\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m} \mathbb{L}_{y}\left\langle u_{m}(\cdot), R_{y}^{m}(\cdot)\right\rangle_{o \Pi_{w}^{m}}\right|_{y=x_{k}} \bar{\psi}_{i}^{m}(x) \\
& =\left.\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m} \mathbb{L}_{y} u_{m}(y)\right|_{y=x_{k}} \bar{\psi}_{i}^{m}(x) \\
& =\sum_{i=0}^{m-2} \sum_{k=0}^{i} \beta_{i k}^{m} f\left(x_{k}\right) \bar{\psi}_{i}^{m}(x),
\end{aligned}
$$

which completes the proof.

Theorem 3.3 [24] If $u \in{ }^{o} \Pi_{w}^{m}[a, b]$, then $|u(x)| \leq C\|u\|_{o_{w}^{m}}$ and $\left|u^{(k)}(x)\right| \leq C\|u\|_{o_{\Pi_{w}^{m}}^{m}}$ for $1 \leq k \leq m-1$, where $C$ is a constant.

### 3.2 Convergence analysis and error estimation in ${ }^{\circ} L_{w}^{2}[a, b]$

### 3.2.1 Convergence analysis

Let, in equation (9), $\mathbb{L}:{ }^{o} L_{w}^{2}[a, b] \longrightarrow L_{w}^{2}[a, b]$, be a bounded linear operator where

$$
{ }^{\circ} L_{w}^{2}[a, b]=\left\{u \mid u \in L_{w}^{2}[a, b], u(a)=u(b)=0\right\} .
$$

We assume that, for any integer $m \geq 2,\left\{x_{i}\right\}_{i=0}^{m-2}$ are any $(m-1)$-distinct points in $(a, b)$. Let $u \in{ }^{o} L_{w}^{2}[a, b]$ and $u_{m} \in{ }^{o} \Pi_{w}^{m}[a, b]$ be the exact and approximate solutions of the problem, respectively. We discuss the convergence of the approximate solutions constructed in equation (12).

Theorem 3.4 Let $u \in{ }^{o} L_{w}^{2}[a, b]$ be the exact solution of equation (1) and $u_{m} \in{ }^{o} \Pi_{w}^{m}[a, b]$ in equation (12) be the approximation of $u$, then

$$
\left\|u_{m}-u\right\|_{o_{W}^{2}} \longrightarrow 0, \quad m \longrightarrow \infty
$$

Moreover, the sequence $\left\|u_{m}-u\right\|_{o_{w}^{2}}$ is monotonically decreasing in m.
Proof From Lemma 2.1, Proposition 2.1, and equation (10), it follows that

$$
u(x)=\sum_{i=2}^{\infty}\left\langle u, h_{i}\right\rangle_{o}{ }_{L_{W}^{2}}^{2} h_{i}(x),
$$

and, for any integer $m$,

$$
\left\langle h_{j}, \psi_{i}^{m}\right\rangle_{o_{L_{w}^{2}}^{2}}=0, \quad i=0,1, \ldots, m-2, j=m+1, m+2, \ldots
$$

We have

$$
\begin{aligned}
\left\langle h_{j}, \psi_{i}^{m}\right\rangle_{o L_{w}^{2}} & =\left\langle h_{j}(\cdot),\left.\mathbb{L} y R_{y}^{m}(\cdot)\right|_{y=x_{i}}\right\rangle_{o L_{w}^{2}} \\
& =\left\langle h_{j}(\cdot),\left.\sum_{k=2}^{m} h_{k}(\cdot) \mathbb{L} y h_{k}(y)\right|_{y=x_{i}}\right\rangle_{o_{L_{w}}^{2}} \\
& =\left.\sum_{k=2}^{m}\left\langle h_{j}(\cdot), h_{k}(\cdot)\right\rangle_{o_{L_{w}}^{2}} \mathbb{L} y h_{k}(y)\right|_{y=x_{i}}=0, \quad j=m+1, m+2, \ldots
\end{aligned}
$$

Let $\Psi_{m}^{\perp}=\overline{\operatorname{Span}\left\{h_{i}\right\}_{i=m+1}^{\infty}}$. So

$$
u_{m}-u \in \Psi_{m}^{\perp},
$$

and we have

$$
\left\|u_{m}-u\right\|_{o L_{w}^{2}}=\left\|\sum_{i=m+1}^{\infty}\left\langle u_{m}-u, h_{i}\right\rangle_{o L_{w}^{2}} h_{i}\right\|_{o L_{w}^{2}} .
$$

Thus

$$
\left\|u_{m}-u\right\|_{o_{W}^{2}} \longrightarrow 0, \quad m \longrightarrow \infty
$$

In addition

$$
\begin{aligned}
\left\|u_{m}-u\right\|_{o_{L_{w}^{2}}^{2}}^{2} & =\left\|\sum_{i=m+1}^{\infty}\left\langle u_{m}-u, h_{i}\right\rangle_{o_{L_{w}}^{2}} h_{i}\right\|_{o_{L_{w}^{2}}^{2}}^{2} \\
& =\sum_{i=m+1}^{\infty}\left(\left\langle u_{m}-u, h_{i}\right\rangle_{o_{L_{w}^{2}}^{2}}\right)^{2} .
\end{aligned}
$$

Clearly, $\left\|u_{m}-u\right\|_{o L_{w}^{2}}$ is monotonically decreasing in $m$, which completes the proof.
Theorem 3.5 ([13], Theorem 1.3.4) If $u_{m}(x)$ converges to $u(x)$ in the sense of $\|\cdot\|_{o_{w}^{2}}$, then $u_{m}^{(k)}(x)$ converges to $u^{(k)}(x)$ uniformly for $0 \leq k \leq m-1$.

### 3.2.2 Error analysis

Theorem 3.6 For $m \geq 2$, let $x_{0}^{(m)}<x_{1}^{(m)}<\cdots<x_{m-2}^{(m)}$ be any $(m-1)$-distinct points in $(a, b)$, $u_{m} \in{ }^{o} \Pi_{w}^{m}[a, b]$ in equation (12) and $u \in{ }^{o} L_{w}^{2}[a, b]$ be the approximate and the exact solution of equation (1), respectively. If p, $q$ and $f \in C^{m-1}[a, b]$ and $\lim _{m \rightarrow \infty} x_{0}^{(m)}=a, \lim _{m \rightarrow \infty} x_{m-2}^{(m)}=$ $b$ then

$$
\left\|\varepsilon_{m}\right\|_{L_{L_{w}^{2}}^{2}}=\left\|u-u_{m}\right\|_{o L_{w}^{2}} \leq \bar{C} \sqrt{\frac{(b-a) \pi}{2}} \hbar_{m}^{m-1}
$$

where $\bar{C}$ is a constant and $\hbar_{m}=\max _{0 \leq i \leq m-3}\left\{\left|x_{i+1}^{(m)}-x_{i}^{(m)}\right|\right\}$.
Proof Let, in equation (12), $A_{i}^{m}=\sum_{k=0}^{i} \beta_{i k}^{m} f\left(x_{k}^{(m)}\right)$. Note here that

$$
\mathbb{L} u_{m}(x)=\sum_{i=0}^{m-2} A_{i}^{m} \mathbb{L} \bar{\psi}_{i}^{m}(x)
$$

and

$$
\begin{aligned}
\left(\mathbb{L} u_{m}\right)\left(x_{j}^{(m)}\right) & =\sum_{i=0}^{m-2} A_{i}^{m}\left\langle\mathbb{L} \bar{\psi}_{i}^{m}, R_{x_{j}^{m}}^{m}\right\rangle_{\Pi_{w}^{m}} \\
& =\sum_{i=0}^{m-2} A_{i}^{m}\left\langle\bar{\psi}_{i}^{m}, \mathbb{L}^{*} R_{x_{j}^{(m)}}^{m}\right\rangle_{L_{w}^{2}} \\
& =\sum_{i=0}^{m-2} A_{i}^{m}\left\langle\bar{\psi}_{i}^{m}, \psi_{j}^{m}\right\rangle_{\Pi_{w}^{m}} .
\end{aligned}
$$

Therefore,

$$
\begin{align*}
\sum_{j=0}^{n} \beta_{n j}^{m}\left(\mathbb{L} u_{m}\right)\left(x_{j}^{(m)}\right) & =\sum_{i=0}^{m-2} A_{i}^{m}\left\langle\bar{\psi}_{i}^{m}, \sum_{j=0}^{n} \beta_{n j}^{m} \psi_{j}^{m}\right\rangle_{\Pi_{w}^{m}} \\
& =\sum_{i=0}^{m-2} A_{i}^{m}\left\langle\bar{\psi}_{i}^{m}, \bar{\psi}_{n}^{m}\right\rangle_{\Pi_{w}^{m}} \\
& =A_{n}^{m} \tag{13}
\end{align*}
$$

In equation (13), by induction on $n$, we have

$$
\left(\mathbb{L} u_{m}\right)\left(x_{j}^{(m)}\right)=f\left(x_{j}^{(m)}\right), \quad j=0,1, \ldots, m-2 .
$$

Let

$$
r_{m}=f-\mathbb{L} u_{m} .
$$

Obviously,

$$
r_{m} \in C^{m-1}[a, b], \quad r_{m}\left(x_{j}^{(m)}\right)=0, \quad j=0,1, \ldots, m-2 .
$$

On the interval $\left[x_{i}^{(m)}, x_{i+1}^{(m)}\right]$ the application of Roll's theorem to $r_{m}(x)$ yields

$$
r_{m}^{\prime}\left(x_{i}^{(1)}\right)=0, \quad x_{i}^{(1)} \in\left(x_{i}^{(m)}, x_{i+1}^{(m)}\right), i=0, \ldots, m-3 .
$$

On the interval $\left[x_{i}^{(1)}, x_{i+1}^{(1)}\right]$ the application of Roll's theorem to $r_{m}^{\prime}(x)$ yields

$$
r_{m}^{\prime \prime}\left(x_{i}^{(2)}\right)=0, \quad x_{i}^{(2)} \in\left(x_{i}^{(1)}, x_{i+1}^{(1)}\right), i=0, \ldots, m-4 .
$$

By the following application of Roll's theorem to $r_{m}^{(j)}(x)$ we have

$$
r_{m}^{(j+1)}\left(x_{i}^{(j+1)}\right)=0, \quad x_{i}^{(j+1)} \in\left(x_{i}^{(j)}, x_{i+1}^{(j)}\right),
$$

for $j=2,3, \ldots, m-4, i=0,1, \ldots, m-j-3$.
Putting

$$
\hbar_{m}=\max _{0 \leq i \leq m-3}\left\{\left|x_{i+1}^{(m)}-x_{i}^{(m)}\right|\right\}, \quad \hbar_{m}^{(j)}=\max _{0 \leq i \leq m-j-3}\left\{\left|x_{i+1}^{(j)}-x_{i}^{(j)}\right|\right\},
$$

for $j=1,2, \ldots, m-3$, clearly, for $j=1,2, \ldots, m-3$, there exist constants $c_{j}$ such that

$$
\hbar^{(j)} \leq c_{j} \hbar_{m} \leq(b-a) .
$$

Suppose that $l(x)$ is a polynomial of degree $=1$ that interpolates the function $r_{m}^{(m-3)}(x)$ at $x_{0}^{(m-3)}, x_{1}^{(m-3)}$. It is clear that $l(x)=0$. Also, for $\forall x \in\left[x_{0}^{(m-3)}, x_{1}^{(m-3)}\right]$, there exist $\eta_{0} \in$ $\left[x_{0}^{(m-3)}, x_{1}^{(m-3)}\right]$ and a constant $d_{0}$ such that

$$
\begin{aligned}
& r_{m}^{(m-3)}(x)=r_{m}^{(m-3)}(x)-l(x)=\frac{r_{m}^{(m-1)}\left(\eta_{0}\right)}{2!}\left(x-x_{0}^{(m-3)}\right)\left(x-x_{1}^{(m-3)}\right), \\
& \left|r_{m}^{(m-3)}(x)\right| \leq d_{0} \hbar_{m}^{2} .
\end{aligned}
$$

On the interval $\left[x_{i}^{(m)}, x_{i+1}^{(m)}\right], i=0,1, \ldots, m-3$, noting that

$$
r_{m}^{(m-4)}(x)=\int_{x_{i}^{(m-4)}}^{x} r_{m}^{(m-3)}(s) d s
$$

there exist constants $a_{i}$ such that

$$
\left|r_{m}^{(m-4)}(x)\right| \leq\left\|r_{m}^{(m-3)}(x)\right\|_{\infty}\left|x-x_{i}^{(m-4)}\right| \leq a_{i} \hbar_{m}^{3}
$$

It turns out that

$$
\left\|r_{m}^{(m-4)}(x)\right\|_{\infty} \leq a_{0} \hbar_{m}^{3}, \quad x \in\left[x_{0}^{(m)}, x_{m-2}^{(m)}\right],
$$

where $a_{0}$ is a constant. By following the above process, there exists a real constant $C$ such that

$$
\begin{equation*}
\left\|r_{m}(x)\right\|_{\infty}=\max _{x \in[a, b]}\left|r_{m}(x)\right| \leq C \hbar_{m}^{m-1}, \tag{14}
\end{equation*}
$$

because $\lim _{m \rightarrow \infty} x_{0}^{(m)}=a, \lim _{m \rightarrow \infty} x_{m-2}^{(m)}=b$.
According to equations (14) and (2), we have

$$
\left\|r_{m}\right\|_{L_{w}^{2}}=\sqrt{\int_{a}^{b} w_{[a, b]}(x)\left|r_{m}(x)\right|^{2} d x} \leq C \sqrt{\frac{(b-a) \pi}{2}} \hbar_{m}^{m-1}
$$

Noting that

$$
\varepsilon_{m}=\mathbb{L}^{-1} r_{m},
$$

there exists a constant $d$ such that

$$
\left\|\varepsilon_{m}\right\|_{L_{w}^{2}}=\left\|\mathbb{L}^{-1} r_{m}\right\|_{L_{w}^{2}} \leq\left\|\mathbb{L}^{-1}\right\|_{L_{w}^{2}} \cdot\left\|r_{m}\right\|_{L_{w}^{2}} \leq d \sqrt{\frac{(b-a) \pi}{2}} \hbar_{m}^{m-1}
$$

The proof is completed by putting $\bar{C}=d \sqrt{\frac{(b-a) \pi}{2}}$.

Corollary 3.1 Let $\hbar_{m}=O\left(m^{-1}\right)$. The sequence $\left\|\varepsilon_{m}\right\|_{L_{w}^{2}}$ is monotonically decreasing in $m$,

$$
\left\|\varepsilon_{m}\right\|_{L_{w}^{2}}=O\left(m^{-m+1}\right)
$$

and

$$
\left\|\varepsilon_{m}\right\|_{L_{w}^{2}} \longrightarrow 0, \quad m \longrightarrow \infty .
$$

Corollary 3.2 If $\varepsilon_{m}^{(k)}(x)=u^{(k)}(x)-u_{m}^{(k)}(x), 1 \leq k \leq m-1$, then

$$
\left\|\varepsilon_{m}^{(k)}\right\|_{o_{L_{w}^{2}}}=\left\|u^{(k)}-u_{m}^{(k)}\right\|_{o_{L_{w}^{2}}^{2}} \leq \bar{D} \hbar_{m}^{m-1}
$$

where $\bar{D}$ is a constant.

## 4 Numerical examples

In this section, some numerical examples are considered to illustrate the performance and accuracy of the C-RKM. Results obtained by C-RKM are compared with the exact solution of each example and are found to be in good agreement with each other. In the process of computation, all the symbolic and numerical computations are performed by using Mathematica 10.

Example 4.1 [24] Consider the following two-point boundary value problem:

$$
\left\{\begin{array}{l}
u^{\prime \prime}+200 e^{x} u^{\prime}+300 \sin (x) u=f(x), \quad 0 \leq x \leq 1  \tag{15}\\
u(0)=0, \quad u(1)=\sinh (1)
\end{array}\right.
$$

where $f(x)$ is given such that the exact solution of this problem is $u(x)=\sinh (x)$. The CRKM on this example with $m=2,4,6,8,9$ and $x_{i}=\frac{(i+0.3)}{m}, i=0,1, \ldots, m-2$ is applied. The absolute errors $\left|u\left(t_{i}\right)-u_{m}\left(t_{i}\right)\right|, t_{i}=0.1 i, i=1,2, \ldots, 9$, and its $L_{w}^{2}$ norm $\left\|\varepsilon_{m}\right\|_{o L_{w}^{2}}$, can be found in Table 1. We see that the accuracies are $O\left(10^{-3}\right)$ for $m=2, O\left(10^{-5}\right)$ for $m=4, O\left(10^{-8}\right)$ for $m=6, O\left(10^{-11}\right)$ for $m=8$ and $O\left(10^{-12}\right)$ for $m=9$, which confirm the convergence of the C-RKM and the order of error is $O\left(m^{-m+1}\right)$.

The effect of the number of nodal points, $m-1$, on the numerical values of the absolute error functions $\left|u^{(i)}-u_{m}^{(i)}\right|, i=0,1,2$, of the C-RKM method are discussed next. Figures 112 give the relevant data for Example 4.1, where the number of nodal points is $2,4,6$, and 8. It is observed that the increase in $m$ results in a reduction in the numerical values of the absolute error function for the numerical solutions and all their numerical derivatives up to order two and correspondingly an improvement in the accuracy of the obtained numerical results. This is in agreement with the result of convergence and error analysis, the error is monotonically decreasing in $m$, where more accurate solutions are obtained using an increase in $m$. On the other hand, a rapid decline of absolute errors by increasing $m$ can easily be seen in these figures.
It is worth noting here that the obtained numerical solution in this example is very accurate, although the number of basis functions in the expansion of the obtained result is very low.

Table 1 Numerical results for Example 4.1

| $\boldsymbol{x}$ | Absolute errors: $\left\|\boldsymbol{u}-\boldsymbol{u}_{\boldsymbol{m}}\right\|$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $\boldsymbol{m}=\mathbf{2}$ | $\boldsymbol{m}=\mathbf{4}$ | $\boldsymbol{m}=\mathbf{6}$ | $\boldsymbol{m}=\mathbf{8}$ | $\boldsymbol{m}=\mathbf{9}$ |
| 0.1 | $3.7948 \mathrm{E}-03$ | $1.9500 \mathrm{E}-05$ | $4.2625 \mathrm{E}-08$ | $7.7160 \mathrm{E}-11$ | $8.3641 \mathrm{E}-13$ |
| 0.2 | $3.8926 \mathrm{E}-03$ | $3.1593 \mathrm{E}-06$ | $2.3047 \mathrm{E}-09$ | $4.0493 \mathrm{E}-11$ | $6.8001 \mathrm{E}-13$ |
| 0.3 | $1.3057 \mathrm{E}-03$ | $8.9693 \mathrm{E}-06$ | $1.0733 \mathrm{E}-08$ | $5.8828 \mathrm{E}-11$ | $7.2092 \mathrm{E}-13$ |
| 0.4 | $2.9333 \mathrm{E}-03$ | $5.7392 \mathrm{E}-06$ | $1.8736 \mathrm{E}-08$ | $4.3152 \mathrm{E}-11$ | $6.5603 \mathrm{E}-13$ |
| 0.5 | $7.7603 \mathrm{E}-03$ | $5.4270 \mathrm{E}-06$ | $7.8240 \mathrm{E}-09$ | $5.6790 \mathrm{E}-11$ | $6.6636 \mathrm{E}-13$ |
| 0.6 | $1.2072 \mathrm{E}-02$ | $9.1774 \mathrm{E}-06$ | $7.4446 \mathrm{E}-09$ | $8.4509 \mathrm{E}-11$ | $5.8942 \mathrm{E}-13$ |
| 0.7 | $1.4711 \mathrm{E}-02$ | $6.7151 \mathrm{E}-06$ | $2.4443 \mathrm{E}-08$ | $8.5180 \mathrm{E}-11$ | $6.4981 \mathrm{E}-13$ |
| 0.8 | $1.4458 \mathrm{E}-02$ | $3.9780 \mathrm{E}-05$ | $4.6549 \mathrm{E}-09$ | $8.4175 \mathrm{E}-11$ | $3.6804 \mathrm{E}-13$ |
| 0.9 | $1.0016 \mathrm{E}-02$ | $6.0631 \mathrm{E}-05$ | $1.2269 \mathrm{E}-07$ | $2.7533 \mathrm{E}-13$ | $2.0268 \mathrm{E}-12$ |
| $\left\\|\varepsilon_{m}\right\\|_{o L_{W}}^{2}$ | $9.6803 \mathrm{E}-03$ | $3.1956 \mathrm{E}-05$ | $7.0121 \mathrm{E}-08$ | $9.1748 \mathrm{E}-11$ | $1.9859 \mathrm{E}-12$ |



Figure 1 The absolute error of $u_{3}(x)$ for the solutions of Example 4.1.


Figure 2 The absolute error of $u_{5}(x)$ for the solutions of Example 4.1.

Example 4.2 ([7]) Consider the following nonhomogeneous two-point boundary value problem:

$$
\left\{\begin{array}{l}
u^{\prime \prime}+(1-x) u^{\prime}+2 u=\left(1+2 x-x^{2}\right) \sin (x), \quad 0 \leq x \leq 1,  \tag{16}\\
u(0)=1, \quad u(1)=0
\end{array}\right.
$$



Figure 3 The absolute error of $u_{7}(x)$ for the solutions of Example 4.1.

the exact solution of this problem is $u(x)=(1-x) \cos (x)$. It is solved by the spectral second kind Chebyshev wavelets (SSKCW) algorithm in [7]. Here, C-RKM on this problem with $m=5,6,7,9,11$ and $x_{i}=\frac{1}{2}\left(\cos \left(\frac{(i+1) \pi}{m}\right)+1\right), i=0,1, \ldots, m-2$, is applied. In solving this problem, one of the main advantages of these two algorithms is that highly accurate approximate solutions are obtained using a small number of basis functions, $n$, in the spectral expansion. In [7] $n=2^{k}(M+1)$, where $k$ is dilation parameter and $M$ is the order of second kind Chebyshev polynomials. In C-RKM $n=m-1$, where $m$ is the number of nodal


Figure 5 The absolute error of $u_{3}^{\prime}(x)$ for the solutions of Example 4.1.

points. The maximum absolute errors $E$ obtained by C-RKM and SSKCW [7] are given in Table 2. Now observe that, for the same $n$, the results of C-RKM are more accurate than the results of SSKCW. To illustrate the rate of convergence of C-RKM and SSKCW for Example 4.2, the maximum absolute errors are plotted in Figure 13, where $n$ is $4,5,6,8$, and 10. It can easily be seen that, by increasing $n$, both algorithms have convergence, but C-RKM is faster than SSKCW. Hence we can say that for this problem C-RKM gives a better accuracy in comparison to the SSKCW algorithm. Figure 14 gives the order of error


Figure 7 The absolute error of $u_{7}^{\prime}(x)$ for the solutions of Example 4.1.


Figure 8 The absolute error of $u_{9}^{\prime}(x)$ for the solutions of Example 4.1.
for Example 4.2, where the number of nodal points covers the range from 1 to 10 . This figure is in agreement with the results of convergence and error analysis.

Summarizing, RKM is proposed in order to obtain the accurate numerical solution of two-point boundary value problems with the Dirichlet boundary conditions. Chebyshev basis polynomials are used. A convergence analysis is discussed. The numerical solutions obtained by this method are compared with the exact solutions. The results reveal that the proposed method is quite efficient and accurate.


Figure 9 The absolute error of $u_{3}^{\prime \prime}(x)$ for the solutions of Example 4.1.



Figure 11 The absolute error of $u_{7}^{\prime \prime}(x)$ for the solutions of Example 4.1.


Figure 12 The absolute error of $u_{9}^{\prime \prime}(x)$ for the solutions of Example 4.1.

Table 2 Numerical results for Example 4.1

| Maximum absolute <br> error $\boldsymbol{E}$ | $\boldsymbol{n}$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{8}$ | $\mathbf{1 0}$ |
| $E[7]$ | $2.28 \mathrm{E}-03$ | $6.32 \mathrm{E}-05$ | $6.23 \mathrm{E}-06$ | $8.62 \mathrm{E}-08$ | $1.07 \mathrm{E}-09$ |
| $E(C-R K M)$ | $5.33 \mathrm{E}-06$ | $3.36 \mathrm{E}-07$ | $6.69 \mathrm{E}-09$ | $5.06 \mathrm{E}-12$ | $1.83 \mathrm{E}-14$ |



Figure 13 The maximum absolute error for Example 4.2.


Figure 14 The order error of $u_{m}(x), m=2,3, \ldots, 11$, for the Example 4.2.

## 5 Conclusions

In the method of this paper, retaining important property of the reproducing kernel we solved two-point boundary value problems. In fact, with increasing $m$ (the number of nodal points), the solution space and associated reproducing kernel function are improved. Also, the absolute error of the approximate solution is rapidly decreasing with $m$.

## This leads to using less nodal points and applying unstable Gram-Schmidt process a moderate number of times.

## Competing interests

The authors declare that they have no competing interests.

## Authors' contributions

All authors contributed extensively to the work presented in this paper. All authors read and approved the final manuscript.

## Acknowledgements

The authors would like to thank the referee for valuable comments and suggestions, which improved the paper in its present form.

Received: 29 September 2016 Accepted: 17 January 2017 Published online: 25 January 2017

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