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A stochastic differential equation model for pest management



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Abstract

In order to comprehend the effects of the duration of pesticide residual effectiveness on successful pest control, a stochastic integrated pest management (IPM) model with pesticides which have residual effects is proposed. Firstly, we show that our model has a global and positive solution and give its explicit expression when pest goes extinct. Then the sufficient conditions for pest extinction combined with the ones for the global attractivity of the pest solution only chemical control are established. Moreover, we also derive sufficient conditions for weak persistence which show that the solution of stochastic IPM models is stochastically ultimately bounded under some conditions.

Keywords: integrated pest management; residual effects; weakly persistence; ultimate boundedness

1 Introduction

Integrated pest management (IPM) was introduced and was widely practised recently [1–11]. IPM is a long time management strategy that uses a combination of cultural, biological and chemical tactics that reduce pests to tolerable levels with little cost to the grower and a minimal effect on the environment.

Especially, spraying of pesticides to crops is intended to reduce the population of pest, but can under some circumstances exacerbate a pest problem. This phenomenon, frequently called insecticide-induced resistance, has several possible mechanisms including reduction in herbivore-herbivore competition, physiological enhancement of pest fecundity, altered host plant nutrition, changes in pest behavior, and the killing of natural predators and parasites of the pest [12–18]. As a result, considerable emphasis has been placed on tactics other than chemical controls, including cultural, biological, and genetic methods and the deployment of crop varieties that are resistant to pests. Researchers have found that the cultural and biological pest controls are ecologically sound and could provide solutions that are sustainable in the long term [19, 20].

However, chemical pesticides may have long-term residual effects which reduce the populations of pest for several weeks, months or years. On the other hand, population dynamics in the real world is inevitably affected by environmental noises. So it is very important to study stochastic population systems to analyze the effect of environmental noises on population systems [21–27].



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Based on the above discussions, this paper is to construct a stochastic integrated pest management (IPM) model with pesticides that have residual effects firstly. In the first place, we derive that the model has a global positive solution by using the mathematical induction method. On the other hand, the explicit expression of the pest-eradication solution is given. Moreover, in order to show residual effects, the sufficient condition for pest extinction and the global attractivity of the pest solution when the natural enemy disappears are established. Furthermore, we establish sufficient conditions for weak persistence in the mean and also show that the solution of stochastic IPM models is stochastically ultimately bounded under some conditions. The methods may have applications for a wider range of aspects of theoretical biology.

2 The killing efficiency rate with pulses of chemical control

It is universally acknowledged that the residual effects of pesticides exert desirable impacts on pest control. Therefore, a more realistic and appropriate method for modeling chemical control in such a case is to use continuous or piecewise-continuous periodic functions which affect the growth rate in the logistic model [1–3]. Such periodic functions make the growth rate fluctuate so that it decreases significantly, or even takes on negative values when the effects of pesticides have disappeared, but increases again during the recovery stage.

As mentioned above, more and more pesticides have a residual effect, which decays with time because of the degradation of pesticide and natural clearance [4, 5]. In general, the killing efficiency rate h(t) can take on various periodic (period *T*) forms including the step function of the form [5]

$$h(t) = \begin{cases} m, & nT \le t \le nT + \tau, \\ 0, & nT + \tau \le t \le (n+1)T, \end{cases}$$
(2.1)

where τ is the duration of pesticide residues. For simplicity, we will focus on the step function h(t) of the form defined by (2.1) throughout this paper (see Figure 1).

3 The stochastic IPM model with residual effects of pesticides

The complex interactions amongst pests, natural enemies and pesticides can be enhanced with mathematical modeling [4, 5]. Modeling advances regarding IPM strategies include analyses of continuous and discrete predator-prey models [6–10]. In addition, discrete



host-parasitoid models have been used to study four cases involving the timing of pesticide applications when these also led to the death of the parasitoids [16].

In [18], they first take into account the simplest case where in each impulsive period T there is a pesticide application, so the killing efficiency rate function can be formulated by the exponentially decaying piecewise periodic function. Further, in each impulsive period T, there is an introduction constant R for the natural enemies which does not depend on the size of the populations. These assumptions result in the following pest-natural enemy model:

$$\begin{cases} \frac{dP(t)}{dt} = P(t)(r - bP(t)) - h(t)P(t) - \beta P(t)N(t),\\ \frac{dN(t)}{dt} = \lambda \beta P(t)N(t) - dN(t),\\ N(nT^+) = N(nT) + R, \quad t = nT, \end{cases} t \neq nT,$$

$$(3.1)$$

where P(t) and N(t) are the population density of the pest and the natural enemy at time t, respectively, and the function h(t) is defined by (2.1), r represents the intrinsic growth rate and r/b is the carrying capacity parameter, β denotes the attack rate of the predator, λ represents conversion efficiency and d is the predator mortality rate. The same model (3.1) but without any residual effects of the pesticides on the pest (i.e., only an instantaneous killing efficiency was considered) has been investigated, see [4, 5] for details.

On the other hand, in the real world, the growth of species usually suffers some discrete changes of relatively short time interval at some fixed times with some natural and man-made factors, such as drought, harvesting, fire, earthquake, flooding, deforestation, hunting and so on. These phenomena cannot be considered with certainty, so in this case, the determined model (3.1) cannot be applicable. In order to describe these phenomena more accurately, some authors considered the stability of stochastic differential equation (SDE) [21]. However, as far as our knowledge is concerned, there is very little amount of work on the impulsive stochastic population model. By now, there have been no results related to the stochastic IPM model with residual effects of pesticides with impulsive effects.

Inspired by the above discussions, we develop the following stochastic IPM model with residual effects of pesticides with impulsive effects:

$$\begin{cases} dP(t) = [P(t)(r - bP(t)) - h(t)P(t) - \beta P(t)N(t)] dt + \alpha_1 P(t) dB_1(t), \\ dN(t) = \lambda \beta P(t)N(t) dt - dN(t) dt + \alpha_2 N(t) dB_2(t), \\ N(nT^+) = N(nT)(1 + q(nT)), \quad t = nT, \end{cases}$$
(3.2)

where α_1 and α_2 are the coefficients of the effects of environmental stochastic perturbations on the pest and the natural enemy, $B_i(t)$, i = 1, 2, are the standard Brownian motions independent of each other and with the initial condition $B_i(0) = 0$, i = 1, 2, q(nT) represents the proportion of releasing natural enemies at time nT, the other parameters are the same as in model (3.1).

3.1 Mathematical analysis of the pest-free solution

One of the main purposes of investigating model (3.2) is to determine how to implement an IPM strategy so that the population goes extinct eventually. To do this, we first need to consider the following subsystem:

$$\begin{cases} dN(t) = -dN(t) dt + \alpha_2 N(t) dB_2(t), & t \neq nT, \\ N(nT^+) = N(nT)(1 + q(nT)), & t = nT, \\ N(0^+) = N(0). \end{cases}$$
(3.3)

In order obtain the globally positive pest-free solution, we will give a solution of the definition of an impulsive stochastic differential equation.

Throughout this paper, let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t\geq 0}, \mathcal{P})$ be a complete probability space with a filtration $\{\mathcal{F}_t\}_{t\geq 0}$ satisfying the usual conditions. Let B(t) denote a standard Brownian motion defined on this probability space. Moreover, we always assume that a product equals unity if the number of factors is zero.

Definition 1 ([21]) Consider the following ISDE:

$$\begin{cases} dX(t) = f(t, X(t)) dt + \sigma(t, X(t)) dB(t), & t \neq nT, \\ X(nT^{+}) = (1 + q(nT))X(nT), & t = nT, \end{cases}$$
(3.4)

with the initial condition X(0). A stochastic process $X(t) = (X_1(t), X_2(t), \dots, X_n(t))^{\tau}$, $t \in R_+$, is said to be s solution of ISDE (3.4) if:

- (i) X(t) is \mathscr{F}_t -adapted and continuous on (0, T) and each interval $(nT, (n + 1)T) \subset R_+$, $n \in \mathcal{N}; f(t, X(t)) \in \mathscr{L}^1(R_+; R_n), \sigma(t, X(t)) \in \mathscr{L}^2(R_+; R_n)$, where $\mathscr{L}^n(R_+; R_n)$ is all R^n -valued measurable \mathscr{F}_t -adapted processes g(t) satisfying $\int_0^{\zeta} |g(t)|^n dt < \infty$ a.s. (almost surely) for every $\zeta > 0$;
- (ii) for each nT, $n \in \mathcal{N}$, $X(nT^+) = \lim_{t \to nT^+} X(t)$ and $X(nT^-) = \lim_{t \to nT^-} X(t)$ exist and $X(nT) = X(nT^-)$ with probability one;
- (iii) for almost all $t \in (0, T]$, P(t) obeys the integral equation

$$X(t) = X(0) + \int_0^t f(s, X(s)) ds + \int_0^t \sigma(s, X(s)) dB(s).$$

And for almost all $t \in (nT, (n + 1)T]$, $n \in \mathcal{N}$, X(t) obeys the integral equation

$$X(t) = X(nT^{+}) + \int_{nT}^{t} f(s, X(s)) ds + \int_{nT}^{t} \sigma(s, X(s)) dB(s).$$

Moreover, X(t) satisfies the impulsive conditions at each t = nT, $n \in \mathcal{N}$ with probability one.

Let us state and prove the following result.

Theorem 1 For any initial value $N(0^+) = N(0)$, there exists a unique positive solution N(t) to ISDE (3.3) a.s., which is global and explicit

$$N(t) = \prod_{0 < nT < t} (1 + q(nT)) N(0) \exp\{(-d - 0.5\alpha_2^2)t + \alpha_2 B(t)\}.$$

Proof Consider a Lyapunov function V(t) defined by

$$V(N(t),t) = \ln N(t), \quad t \ge 0.$$

Making use of Itô's formula

$$dV(N(t),t) = \frac{dN(t)}{N(t)} - \frac{1}{2} \frac{(dN(t))^2}{N^2(t)},$$

we can obtain that

$$d\left(\ln N(t)\right) = \left(-d - 0.5\alpha_2^2\right)dt + \alpha_2 dB_2(t).$$

Suppose $t \in (nT, (n + 1)T], n \in \mathcal{N}$. Integrating both sides from nT to t, one can see that

$$\ln N(t) - \ln N(nT) = \left(-d - 0.5\alpha_2^2\right)(t - nT) + \alpha_2 \left(B(t) - B(nT)\right).$$

Applying the impulse condition $N(nT^+) = (1 + q(nT))N(nT)$, we can obtain that

$$N(t) = (1 + q(nT))N(nT)\exp\{(-d - 0.5\alpha_2^2)(t - nT) + \alpha_2(B(t) - B(nT))\}.$$

Applying the mathematical induction method, we get

$$N(t) = \prod_{0 < nT < t} (1 + q(nT)) N(0) \exp\{(-d - 0.5\alpha_2^2)t + \alpha_2 B(t)\}.$$

3.2 Mathematical analysis of chemical control only

As the natural enemy disappeared, one of the main purposes of investigating model (3.2) is to determine under what circumstances the pest goes extinct eventually. To do this, we first need to consider the following subsystem:

$$dP(t) = \left[P(t)(r - bP(t)) - h(t)P(t) \right] dt + \alpha_1 P(t) dB_1(t).$$
(3.5)

In order to establish a sufficient condition for pest extinction and prove the global attractivity of solution of model (3.5), we introduce some useful definitions and lemmas.

Definition 2 If $N_1(t)$, $N_2(t)$ are two arbitrary solutions of model (3.3) with the initial values $N_1(0)$, $N_2(0)>0$, respectively. If $\lim_{t\to\infty} |N_1(t) - N_2(t)| = 0$ a.s., then Eq. (3.3) is globally attractive.

Lemma 1 If N(t) is a solution of (3.3) without impulsive effects for any initial value $N(0) = N_0 > 0$. If Assumption 1 holds, then almost every sample path of N(t) is uniformly continuous for $t \ge 0$.

Lemma 2 If f is a non-negative function defined on R_+ such that f is integrable on R_+ and is uniformly continuous on R_+ , then $\lim_{t\to\infty} f(t) = 0$.

In the following, we will give our main result.

Theorem 2 If $r - 0.5\alpha_1^2 - \frac{m\tau}{T} < 0$, then the solution P(t) of SDE (3.5) with any positive initial value has $\lim_{t\to\infty} P(t) = 0$.

Proof Making use of Itô's formula, we derive the following form in model (3.5):

$$d\left(\log P(t)\right) = \left[r - 0.5\alpha_1^2 - h(t) - bP(t)\right]dt + \alpha_1 dB(t).$$

Integrating both sides from 0 to *t*, we have

$$\log P(t) = \log P_0 + \int_0^t \left[r - 0.5\alpha_1^2 - h(t) \right] ds - b \int_0^t P(s) \, ds + \alpha_1 \int_0^t \, dB(s)$$

$$\leq \log P_0 + \int_0^t \left[r - 0.5\alpha_1^2 - h(t) \right] ds + M_1(t),$$

where $M_1(t)$ is a martingale defined by

$$M_1(t) = \alpha_1 \int_0^t dB(s).$$

The quadratic variation of this martingale is

$$\langle M_1(t), M_1(t) \rangle = \alpha_1^2 t.$$

Making use of the strong law of large numbers for local martingales (see [23], p.26) leads to

$$\lim_{t\to\infty}M_1(t)/t=0.$$

According to the hypothesis,

$$\lim_{t\to\infty}\sup\frac{\log P(t)}{t}\leq \lim_{t\to\infty}\sup\frac{\int_0^t [r-0.5\alpha_1^2-\frac{m\tau}{T}]\,ds}{t}\doteq\lambda^*<0,$$

hence, we can derive that

$$\lim_{t\to\infty}P(t)=0.$$

Theorem 3 *The solution of model* (3.5) *is globally attractive.*

Proof Let $P_1(t)$, $P_2(t)$ be two arbitrary solutions of model (3.5) with the initial values $P_1(0)$, $P_2(0) > 0$, respectively. Suppose that the solution of the equation

$$dP(t) = [P(t)(r - bP(t)) - h(t)P(t)]dt + \alpha_1 P(t) dB_1(t) \text{ with } P(0) = P_1(0)$$

is $P_1(t)$ and the solution of the equation

$$dP(t) = \left[P(t)(r - bP(t)) - h(t)P(t)\right]dt + \alpha_1 P(t) dB_1(t) \quad \text{with } P(0) = P_2(0)$$

is $P_2(t)$. Consider a Lyapunov function V(t) defined by

$$V(t) = \left| \ln P_1(t) - \ln P_2(t) \right|, \quad t \ge 0.$$

Then V(t) is continuous. So a direct calculation of the right differential $d^+V(t)$ of V(t)

along the solutions leads to

$$d^{+}V(t) = \operatorname{sgn}(P_{1}(t) - P_{2}(t))d(\ln P_{1}(t) - \ln P_{2}(t))$$

= sgn(P_{1}(t) - P_{2}(t))[-b(P_{1}(t) - P_{2}(t))]dt
= -b|P_{1}(t) - P_{2}(t)|dt.

Integrating both sides and then taking the expectation, we have that

$$V(t) - V(0) = -b \int_0^t |P_1(s) - P_2(s)| \, ds.$$

Consequently, it gives that

$$V(t) + b \int_0^t |P_1(s) - P_2(s)| \, ds = V(0) < \infty.$$

Then it follows from $V(t) \ge 0$ that $|P_1(s) - P_2(s)| \in L^1[0, \infty)$. Combining Lemma 1 with Lemma 2 can derive that

$$\lim_{t \to \infty} \left| P_1(t) - P_2(t) \right| = 0.$$

3.3 The persistence and stochastically ultimate boundedness

In order to investigate the persistence and stochastically ultimate boundedness, we need to guarantee the existence and uniqueness of the positive solution. In the following, we illustrate the definitions of solutions of system (3.2).

Theorem 4 Model (3.2) has a unique solution (P(t), N(t)) on t > 0 for any given initial value $(P(0), N(0)) \in R^2_+ = \{(P(t), N(t)) \in R^2_+ | P(t) > 0, N(t) > 0\}$ and the solution will remain in R^2_+ a.s.

Proof According to [21], consider the following SDE without impulse effects:

$$\begin{cases} dP_1(t) = [P_1(t)(r - bP_1(t)) - h(t)P_1(t) - \beta \prod_{0 < nT < t} (1 + q(nT))P_1(t)N_1(t)] dt \\ + \alpha_1 P_1(t) dB_1(t), \\ dN_1(t) = \lambda \beta P_1(t)N_1(t) dt - dN_1(t) dt + \alpha_2 N_1(t) dB_2(t) \end{cases}$$
(3.6)

with the initial value $(P_1(0), N_1(0)) = (P(0), N(0))$. Model (3.6) has a unique global positive solution $(P_1(t), N_1(t))$. Let $N(t) = \prod_{0 < nT < t} (1 + q(nT))N_1(t)$, we may prove that (P(t), N(t)) is the solution to model (3.2) with the initial value (P(0), N(0)). Because of the first equation of (3.2), we only consider the second equation of model (3.2), by the fact that N(t) is continuous on (0, T] and each interval $t \in (nT, (n + 1)T] \subset [0, \infty)$, $n \in \mathcal{N}$ and for $t \neq nT$

$$dN(t) = d\left[\prod_{0 < nT < t} (1 + q(nT))N_1(t)\right] = \prod_{0 < nT < t} (1 + q(nT)) dN_1(t)$$
$$= \lambda \beta \prod_{0 < nT < t} (1 + q(nT))P_1(t)N_1(t) dt - d \prod_{0 < nT < t} (1 + q(nT))N_1(t) dt$$

$$+ \alpha_2 \prod_{0 < nT < t} (1 + q(nT)) N_1(t) dB_2(t)$$
$$= \lambda \beta P(t) N(t) dt - dN(t) dt + \alpha_2 N(t) dB_2(t).$$

Moreover, for every $n \in \mathcal{N}$ and $t \neq nT$,

$$\begin{split} N(nT^{+}) &= \lim_{t \to nT^{+}} N(t) \\ &= \lim_{t \to nT^{+}} \prod_{0 < iT < t} (1 + q(iT)) N_{1}(t) \\ &= \lim_{t \to nT^{+}} \prod_{0 < iT \le nT} (1 + q(iT)) N_{1}(nT^{+}) \\ &= (1 + q(nT)) \prod_{0 < iT < nT} (1 + q(iT)) N_{1}(nT) \\ &= (1 + q(nT)) N(nT). \end{split}$$

On the other hand,

$$\begin{split} N(nT^{-}) &= \lim_{t \to nT^{-}} N(t) \\ &= \lim_{t \to nT^{-}} \prod_{0 < iT < nT} (1 + q(iT)) N_{1}(t) \\ &= \lim_{t \to nT^{+}} \prod_{0 < iT < nT} (1 + q(iT)) N_{1}(nT^{-}) \\ &= \prod_{0 < iT < nT} (1 + q(iT)) N_{1}(nT) = (1 + q(nT)) N(nT). \end{split}$$

Theorem 4 indicates that model (3.2) has a unique global positive solution. This main result allows us to further examine how the solution varies in R_+^2 in more detail. Now let us further examine how this solution pathwisely moves in R_+ .

Assumption 1 There are two positive constants L and U such that $L \leq \prod_{0 < nT < t} (1 + q(nT)) \leq U$.

Theorem 5 Under Assumption 1, the solution (P(t), N(t)) of model (3.2) satisfies the following inequalities:

$$\lim_{t\to\infty}\sup E\Big[\sqrt{\left(P_1^2(s)+N_1^2(s)\right)}\Big]\leq \mathcal{K}\quad \left(\mathcal{K}\in R^+\right).$$

Proof According to model (3.6), we define

$$A = \begin{bmatrix} -b & -\beta \prod_{0 < nT < t} (1 + q(nT)) \\ \lambda \beta & 0 \end{bmatrix},$$
(3.7)

then there exist two constants ν_1 and ν_2 (see) such that

$$\lambda_{\max}(\widetilde{C}A + A^T \widetilde{C}) < 0, \tag{3.8}$$

where $\widetilde{C} = \text{diag}(c_1, c_2)$, and $\lambda_{\max}(\widetilde{C}A + A^T \widetilde{C})$ is the largest eigenvalue of $\widetilde{C}A + A^T \widetilde{C}$. In order to show this statement, define a C^2 -function V: $R_+^2 \to R_+$ by

$$V(P_1(t), N_1(t)) = c_1 P_1(t) + c_2 N_1(t).$$

In view of Itô's formula, we get

$$dV(P_1(t), N_1(t)) = LV(P_1(t), N_1(t)) dt + c_1 \alpha_1 P_1(t) dB_1(t) c_2 \alpha_2 N_1(t) dB_2(t),$$
(3.9)

where $LV(P_1(t), N_1(t)): \mathbb{R}^2_+ \to \mathbb{R}_+$ is defined by

$$LV(P_{1}(t), N_{1}(t))$$

$$= c_{1}P_{1}(t) \left[r - bP_{1}(t) - h(t) - \beta \prod_{0 < nT < t} (1 + q(nT))N_{1}(t) \right]$$

$$+ c_{2}N_{1}(t) (\lambda\beta P_{1}(t) - d)$$

$$= rc_{1}P_{1}(t) - dc_{2}N_{1}(t) + \frac{1}{2} (P_{1}(t), N_{1}(t)) (\widetilde{C}A + A^{T}\widetilde{C}) (P_{1}(t), N_{1}(t))^{T}$$

$$\leq rc_{1}P_{1}(t) - dc_{2}N_{1}(t) + \frac{1}{2} \lambda_{\max} (\widetilde{C}A + A^{T}\widetilde{C}) (P_{1}^{2}(t) + N_{1}^{2}(t)). \qquad (3.10)$$

In the following, consider a Lyapunov function $V_1(t)$ defined by

$$V_1(t) = e^t V(P_1(t), N_1(t)), \quad t \ge 0.$$

Making use of Itô's formula, we get

$$d[e^{t}V(P_{1}(t), N_{1}(t))] = e^{t}V(P_{1}(t), N_{1}(t)) dt + e^{t}V(P_{1}(t), N_{1}(t))$$

$$= (c_{1}P_{1}(t) - c_{2}N_{1}(t))e^{t} dt + e^{t}(LV(P_{1}(t), N_{1}(t))) dt$$

$$+ c_{1}\alpha_{1}P_{1}(t) dB_{1}(t) - c_{2}\alpha_{2}N_{1}(t) dB_{2}(t)$$

$$\leq e^{t} \bigg[c_{1}P_{1}(t) - c_{2}N_{1}(t) + rc_{1}P_{1}(t) - dc_{2}N_{1}(t)$$

$$+ \frac{1}{2}\lambda_{\max}(\widetilde{C}A + A^{T}\widetilde{C})(P_{1}^{2}(t) + N_{1}^{2}(t)) \bigg] dt$$

$$+ e^{t} \big[c_{1}\alpha_{1}P_{1}(t) dB_{1}(t) - c_{2}\alpha_{2}N_{1}(t) dB_{2}(t) \big].$$

Let

$$g(P_1(t), N_1(t)) \doteq c_1 P_1(t) - c_2 N_1(t) + rc_1 P_1(t) - dc_2 N_1(t) + \frac{1}{2} \lambda_{\max} (\widetilde{C}A + A^T \widetilde{C}) (P_1^2(t) + N_1^2(t)).$$

It is easy to see that there exists a constant $\mathcal{K}_1 > 0$ such that $g(P_1(t), N_1(t)) \leq \mathcal{K}_1$, so we have that

$$d\left[e^{t}V(P_{1}(t),N_{1}(t))\right] \leq \mathcal{K}_{1}e^{t}\,dt + e^{t}\left[c_{1}\alpha_{1}P_{1}(t)\,dB_{1}(t) - c_{2}\alpha_{2}N_{1}(t)\,dB_{2}(t)\right].$$

Integrating from 0 to *t* and then taking expectations, one can get

$$e^{t}E[V(P_{1}(t), N_{1}(t))] \leq V(P_{1}(0), N_{1}(0)) + \mathcal{K}_{1}(e^{t} - 1).$$

Taking superior limit of both sides, we get

$$\lim_{t \to \infty} \sup E[V(P_1(t), N_1(t))] \le \mathcal{K}_1.$$
(3.11)

On the other hand,

$$\sqrt{\left(P_1^2(t) + N_1^2(t)\right)} \le P_1(t) + N_1(t) \le V\left(P_1(t), N_1(t)\right) / \min\{c_1, c_2\}.$$

Consequently,

$$\lim_{t \to \infty} \sup E\left[\sqrt{\left(P_1^2(t) + N_1^2(t)\right)}\right] \le \lim_{t \to \infty} \sup E\left[V\left(P_1(t), N_1(t)\right)\right] / \min\{c_1, c_2\}$$
$$\le \mathcal{K}_1 / \min\{c_1, c_2\} \doteq \mathcal{K}.$$
(3.12)

For better discussion later, we give several definitions, then try to explore sufficient conditions for them.

Definition 3 If $\lim_{t\to\infty} \sup \frac{\int_0^t P(s) ds}{t} > 0$ a.s., then the species P(t) is weakly persistent in the mean.

Definition 4 A solution $\mathscr{Z}(t) = (P(t), N(t))$ of Eq. (3.2) is said to be stochastically ultimately bounded if $\forall \epsilon \in (0, 1), \exists \delta = \delta^* > 0$ such that

$$\lim_{t\to\infty}\sup\mathscr{P}\big[\big|\mathscr{Z}(t)\big|>\delta\big]<\epsilon$$

for any initial value $(P(0), N(0)) \in \mathbb{R}^2_+$.

We are now in a position to prove persistence. For the pest P(t) and the natural enemy N(t), we have the following results.

Theorem 6

- (i) If $r 0.5\alpha_1^2 \frac{m\tau}{T} > 0$, $\lim_{t \to \infty} \sup \frac{\sum_{0 < nT < t} \ln(1+q(nT))}{t} < -d + 0.5\alpha_2^2$, then the pest P(t) is weakly persistent in the mean.
- (ii) If $\lambda\beta(r-0.5\alpha_1^2-\frac{m\tau}{T})+b\lim_{t\to\infty}\sup\frac{\sum_{0\le nT\le t}\ln(1+q(nT))}{t}+d-0.5\alpha_2^2>0$, and $\lim_{t\to\infty}\sup\frac{\sum_{0\le nT\le t}\ln(1+q(nT))}{\ln t}<\infty$, then the natural enemy N(t) will be weakly persistent in the mean.

Proof For the pest P(t), consider a Lyapunov function V(t) defined by

$$V(t) = \ln P(t), \quad t \ge 0.$$

Applying Itô's formula to the first equation of Eq. (3.2) yields

$$d\ln P(t) = \frac{dP(t)}{P(t)} - \frac{(dP(t))^2}{2P^2(t)} = r - h(t) - 0.5\alpha_1^2 - bP(t) - \beta N(t) + \alpha_1 dB_1(t).$$

Integrating both sides from 0 to *t* and both dividing by *t*, one can see that

$$\frac{\ln[P(t)/P(0)]}{t} = r - 0.5\alpha_1^2 - \frac{m\tau}{T} - \frac{b\int_0^t P(s)\,ds}{t} - \frac{\beta\int_0^t N(s)\,ds}{t} + \frac{M_1(t)}{t}.$$
(3.13)

In the same way,

$$\frac{\ln[N(t)/N(0)]}{t} = \frac{\sum_{0 < nT < t} \ln(1 + q(nT))}{t} + d - 0.5\alpha_2^2 + \frac{\lambda\beta \int_0^t P(s) \, ds}{t} + \frac{M_2(t)}{t}, \qquad (3.14)$$

where $M_i(t) = \int_0^t \alpha_i dB_i(s)$, i = 1, 2. Then $M_i(t)$ is a local martingale whose quadratic variation $\langle M_i(t), M_i(t) \rangle = \int_0^t \alpha_i^2 d(s)$. Making use of the strong law of large numbers for local martingales ([23], p.26) leads to

$$\lim_{t \to \infty} \frac{M_i(t)}{t} = 0, \quad \text{a.s. } i = 1, 2.$$
(3.15)

Case (i). By Theorem 5, we have that $\lim_{t\to\infty} \sup \frac{P(t)}{t} < 0$ a.s. Then taking the superior limit for (3.7) leads to

$$\lim_{t \to \infty} \sup\left(\frac{b\int_0^t P(s)\,ds}{t} - \frac{\beta\int_0^t N(s)\,ds}{t}\right) > r - 0.5\alpha_1^2 - \frac{m\tau}{T} \quad \text{a.s.}$$
(3.16)

There $\lim_{t\to\infty} \sup \frac{\int_0^t P(s) ds}{t} > 0$ a.s. In fact, for $\forall \omega \in \{\lim_{t\to\infty} \sup \frac{P(t,\omega)}{t} = 0\}$, it follows from (3.10) that $\lim_{t\to\infty} \sup \frac{N(t,\omega)}{t} > 0$. On the other hand, taking the superior limit for (3.8) and using $\lim_{t\to\infty} \sup \frac{P(t,\omega)}{t} = 0$ a.s., according to the hypothesis (i), lead to

$$\lim_{t\to\infty}\sup\frac{\ln N(t,\omega)}{t}\leq \lim_{t\to\infty}\sup\frac{\sum_{0< nT< t}\ln(1+q(nT))}{t}+d-0.5\alpha_2^2<0.$$

This is to say $\lim_{t\to\infty} N(t,\omega) = 0$, which is a contraction. So we have $\lim_{t\to\infty} \sup \frac{P(t,\omega)}{t} > 0$ a.s.

Case (ii). Multiplying (3.7) and (3.8) by $\lambda\beta$ and *b*, respectively, we find

$$\lambda \beta \frac{\ln[P(t)/P(0)]}{t} + b \frac{\ln[N(t)/N(0)]}{t}$$

$$= \lambda \beta \left(r - 0.5\alpha_1^2 - \frac{m\tau}{T} \right) + b \left(\frac{\sum_{0 < nT < t} \ln(1 + q(nT))}{t} + d - 0.5\alpha_2^2 \right)$$

$$- \frac{\lambda \beta^2 \int_0^t N(s) \, ds}{t} + \frac{\lambda \beta M_1(t)}{t} + \frac{b M_2(t)}{t}.$$
(3.17)

Using the strong law of large numbers for local martingales leads to

$$\lim_{t\to\infty}\frac{\lambda\beta M_1(t)}{t}=0,\qquad \lim_{t\to\infty}\frac{bM_2(t)}{t}=0.$$

Noting that $\lim_{t\to\infty} \frac{\ln P(t)}{t} \le 0$, $\lim_{t\to\infty} \frac{\ln N(t)}{t} \le 0$ a.s. and taking the superior limit for (3.11) lead to

$$\lim_{t \to \infty} \sup \frac{\lambda \beta^2 \int_0^t N(s) \, ds}{t}$$

$$\geq \lambda \beta \left(r - 0.5\alpha_1^2 - \frac{m\tau}{T} \right) + b \lim_{t \to \infty} \sup \frac{\sum_{0 < nT < t} \ln(1 + q(nT))}{t} + d - 0.5\alpha_2^2 > 0. \qquad \Box$$

Theorem 7 The solution (P(t), N(t)) of the equation system (3.2) is stochastically bounded.

Proof According to Theorem 5, we obtain

$$\begin{split} \lim_{t \to \infty} \sup E \sqrt{P^2(t) + N^2(t)} \\ &= \lim_{t \to \infty} \sup E \sqrt{P^2(t) + \left[\sum_{0 < nT < t} \ln(1 + q(nT)) N_1(t)\right]^2} \\ &\leq \sqrt{(1 + M^2)} \lim_{t \to \infty} \sup E \sqrt{P_1^2(t) + N_1^2(t)} \\ &= \sqrt{(1 + M^2)} \mathcal{K} \doteq U^*. \end{split}$$

Let $\delta = U^*/\epsilon$, by Chebyshev's inequality, we have

$$\mathscr{P}\left\{ \left| P(t) \right| > \delta \right\} \le \frac{E\sqrt{P^2(t) + N^2(t)}}{\delta}$$

Taking the superior limit for both sides, we get

$$\lim_{t \to \infty} \sup \mathscr{P}[|P(t)| > \delta] < \epsilon.$$

4 Discussion

In this paper, a simple stochastic mathematical model of IPM systems with pesticides that have residual effects is proposed and studied. Theorem 4 shows that our model has a global positive solution for any given positive initial value, and we obtain its explicit expression under the pest-eradication condition. Firstly, we consider chemical control only, with the other parameters left the same as in model (3.2). Secondly, under $r - 0.5\alpha_1^2 - \frac{m\tau}{T} < 0$, which implies that the pest will die out eventually, we also prove the global attractivity of the pest solution when the natural enemy disappears.

It follows from Theorem 6 that we prove the persistence of pest and natural enemy when they satisfy the conditions respectively. Fortunately, Theorem 7 proves that the solution of model (3.2) is stochastically bounded with $L \leq \prod_{0 < nT < t} (1 + q(nT)) \leq U$ (*L* and *U* are positive constants).

Integrated pest management is a complex process. In fact, farmers and other pest managers usually control pests so that they cannot exceed the economic injury level. How to model an IPM strategy with residual effects of pesticides, taking account of the economic injury level, will also be studied in future research to include analyses of dynamical behavior of the models and the biological implications of the results.

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Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally and significantly in this paper. All authors read and approved the final manuscript.

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