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Space-time fractional Rosenou-Haynam equation: Lie symmetry analysis, explicit solutions and conservation laws

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Abstract

This article uses the extension of the Lie symmetry analysis (LSA) and conservation laws (CLs) (Singla et al. in *Nonlinear Dyn.* 89(1):321-331, 2017; Singla et al. in *J. Math. Phys.* 58:051503, 2017) for the space-time fractional partial differential equations (STFPDEs) to analyze the space-time fractional Rosenou-Haynam equation (STFRHE) with Riemann-Liouville (RL) derivative. We transform the space-time fractional RHE to a nonlinear ordinary differential equation (ODE) of fractional order using its Lie point symmetries. The reduced equation's derivative is in Erdelyi-Kober (EK) sense. We use the power series (PS) technique to derive explicit solutions for the reduced ODE for the first time. The CLs for the governing equation are constructed using a new conservation theorem.

Keywords: space-time fractional RHE; Lie symmetry analysis; RL fractional derivative; explicit solutions; CLs

1 Introduction

Fractional differential equations (FDEs) are generalizations of classical differential equations of integer order. FDEs have been studied nowadays to describe several physical aspects and procedure in natural conditions [3–19]. However, fractional partial differential equations (FPDEs) having only time derivative have been analyzed via the Lie symmetry method [20–26]. Recently, the Lie method has been developed to the systems of time FPDEs [27]. More recently, the Lie method has been extended for the first time to the analysis of FPDEs having space and time derivative with fractional order and the systems of space and time FPDEs in [1, 2]. To the best of our knowledge, application of the Lie method to the space-time FPDEs and the systems of space-time FPDEs appeared only in [1, 2]. Therefore, applying this new approach to more space-time FPDEs in order to obtain lots of solutions will be remarkable contribution to the literature.

The LSA and CLs supply lots of ideas on the systems modeled by the differential equations. Lie symmetries are a very significant tool in determining exact solutions and CLs of differential equations. In spite of the significance of CLs in analyzing the integrability and internal properties and in proving the existence and uniqueness of solutions of differential equations [28–30], the CLs for PDEs having fractional-order are not investigated in detail. The generalization for investigating CLs for FDEs was presented in [31, 32]. In recent time,

the fractional generalized Noether operators have been introduced [30] for FPDEs that do not have a Lagrangian in order to find CIs using a new conservation theorem [33]. Even though very few works [34–36] that have to do with CIs of FPDEs can be found, the analysis of CIs for the STFPDEs has entirely not been investigated in more detail.

In this study, we consider STFRHE given by

$$\frac{\partial^\alpha u}{\partial t^\alpha} + u \frac{\partial^\beta u}{\partial x^\beta} + uu_{xxx} + 3u_x u_{xx} = 0, \tag{1}$$

where $0 < \alpha \leq 1$ and $\beta < 2$. In Eq. (1), $\frac{\partial^\alpha u}{\partial t^\alpha}$ and $\frac{\partial^\beta u}{\partial x^\beta}$ are the RL fractional derivatives of order $\alpha, \beta > 0$, respectively. If $\beta = 1$, Eq. (1) becomes

$$\frac{\partial^\alpha u}{\partial t^\alpha} + u \frac{\partial u}{\partial x} + uu_{xxx} + 3u_x u_{xx} = 0. \tag{2}$$

The invariance properties for Eq. (2) that can be used to interpret the formation of patterns in liquid drops were analyzed and investigated in [37]. If $\alpha = 1$ and $\beta = 1$, Eq. (1) becomes

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + uu_{xxx} + 3u_x u_{xx} = 0. \tag{3}$$

Some approximate analytical solutions for Eq. (3) were presented in [38, 39]. Many methods have been applied to reach analytical solutions for PDEs [40–47].

The aim of this study is to analyze and investigate the LSA, explicit solution via the power series technique and CIs for Eq. (1).

The outline of the paper is presented in the following way: In Section 2 we present some preliminaries; in Section 3 we present symmetry analysis and reduction; in Section 4 we analyze explicit solution for the reduced equation; in Section 5 we construct CIs for the underlying equation. Finally, concluding remarks are given in Section 6.

2 Preliminaries

Herein, we present some preliminaries. The RL fractional derivative [19, 27] is defined by

$$D^\alpha f(t) = \begin{cases} \frac{d^n f}{dt^n}, & \alpha = n, \\ \frac{d}{dt} I^{n-\alpha} f(t), & 0 \leq n - 1 < \alpha < n, \end{cases} \tag{4}$$

where n is a natural number and $I^\mu f(t)$ is given by

$$I^\mu f(t) = \frac{1}{\Gamma(\mu)} \int_0^t (t-s)^{\mu-1} f(s) ds, \quad \mu > 0, \tag{5}$$

$$I^\mu f(t) = f(t), \tag{6}$$

and $\Gamma(z)$ represents the gamma function.

Consider the following space-time FPDEs:

$$\Delta = F(x, t, u, \partial_t^\alpha, \partial_x^\beta, u_{xx}, u_{xxx}, \dots). \tag{7}$$

Suppose that a one-parameter group of transformations is given by

$$\begin{aligned}
 \bar{t} &= t + \epsilon \xi^2(t, x, u) + O(\epsilon^2), \\
 \bar{x} &= x + \epsilon \xi^1(t, x, u) + O(\epsilon^2), \\
 \bar{u} &= u + \epsilon \eta(t, x, u) + O(\epsilon^2), \\
 \frac{\partial^\alpha \bar{u}}{\partial \bar{t}} &= \frac{\partial^\alpha u}{\partial t^\alpha} + \epsilon \eta^{\alpha,t}(t, x, u) + O(\epsilon^2), \\
 \frac{\partial^\beta \bar{u}}{\partial \bar{x}^\beta} &= \frac{\partial^\beta u}{\partial x^\beta} + \epsilon \eta^{\beta,x}(t, x, u) + O(\epsilon^2), \\
 \frac{\partial \bar{u}}{\partial \bar{x}} &= \frac{\partial u}{\partial x} + \epsilon \eta^x(t, x, u) + O(\epsilon^2), \\
 \frac{\partial^2 \bar{u}}{\partial \bar{x}^2} &= \frac{\partial^2 u}{\partial x^2} + \epsilon \eta^{xx}(t, x, u) + O(\epsilon^2), \\
 \frac{\partial^3 \bar{u}}{\partial \bar{x}^3} &= \frac{\partial^3 u}{\partial x^3} + \epsilon \eta^{xxx}(t, x, u) + O(\epsilon^2),
 \end{aligned} \tag{8}$$

where

$$\begin{aligned}
 \eta^{\alpha,t} &= D_t^\alpha(\eta) + \xi^1 D_t^\alpha(u_x) - D_t^\alpha(\xi^1 u_x) + D_t^\alpha(u(D_t \xi^2)) - D_t^{\alpha+1}(\xi u) + \xi^2 D_t^{\alpha+1}(u), \\
 \eta^{\beta,t} &= D_x^\beta(\eta) + D_x^\beta(u(D_x \xi^1)) - D_x^{\beta+1}(\xi^1 u) + \xi D_x^{\beta+1}(u) + \xi^2 D_t^\beta(u_t) - D_x^\beta(\xi^2 u_t), \\
 \eta^x &= D_x(\eta) - u_x D_x(\xi^1) - u_t D_t(\xi^2), \\
 \eta^{xx} &= D_x(\eta^x) - u_{xt} D_x(\xi^1) - u_{xx} D_t(\xi^2), \\
 \eta^{xxx} &= D_x(\eta^{xx}) - u_{xxt} D_x(\xi^1) - u_{xxx} D_t(\xi^2), \\
 &\dots
 \end{aligned} \tag{9}$$

In Eq. (7), D_x and D_t represent the total differential operators defined by

$$D_x = \frac{\partial}{\partial x} + u_x \frac{\partial}{\partial u} + u_{xx} \frac{\partial}{\partial u_x} + \dots, \tag{10}$$

$$D_t = \frac{\partial}{\partial t} + u_t \frac{\partial}{\partial u} + u_{tt} \frac{\partial}{\partial u_t} + \dots. \tag{11}$$

The corresponding Lie algebra of symmetries consists of the following vector fields:

$$X = \xi^1 \frac{\partial}{\partial x} + \xi^2 \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial u}. \tag{12}$$

The vector field Eq. (12) is a Lie point symmetry of Eq. (7) provided

$$P^{\alpha,\beta,3} r X(\Delta)|_{\Delta=0} = 0. \tag{13}$$

Also, the invariance condition [48] yields

$$\xi^1(t, x, u)|_{x=0} = 0, \quad \xi^2(t, x, u)|_{t=0} = 0, \tag{14}$$

and the α th and β th extended infinitesimals with Eq. (10) are given as in [19, 27].

3 Lie symmetries and reduction for Eq. (1)

Suppose that Eq. (1) is an invariant under Eq. (8), we have that

$$\frac{\partial^\alpha \bar{u}}{\partial \bar{t}^\alpha} + u \frac{\partial^\beta \bar{u}}{\partial \bar{x}^\beta} + \bar{u} \bar{u}_{\bar{x}\bar{x}\bar{x}} + 3\bar{u}_{\bar{x}} \bar{u}_{\bar{x}\bar{x}} = 0 \tag{15}$$

so that $u = u(x, t)$ satisfies Eq. (1). Using Eq. (8) in Eq. (15), we get the invariant equation

$$\eta^{\alpha,t} + u\eta^{\beta,x} + u_{xxx}\eta + 3u_{xx}\eta^x + 3u_x\eta^{xx} + u\eta^{xxx} = 0. \tag{16}$$

Putting the values of $\eta^{\alpha,t}$, $\eta^{\beta,x}$, η^x , η^{xx} and η^{xxx} into Eq. (16) and isolating coefficients, we have

$$\begin{aligned} &\partial_t^\alpha \eta - u \partial_t^\alpha \eta_u + u \partial_x^\beta \eta - u^2 \partial_x^\beta \eta_u + u \eta_{xxx} = 0, \\ &\binom{\alpha}{n} \partial_t^n(\eta) - \binom{\alpha}{n+1} D_t^{n+1}(\xi^2) = 0, \quad n = 1, 2, \dots, \\ &\binom{\beta}{n} \partial_x^n(\eta) - \binom{\beta}{n+1} D_x^{n+1}(\xi^1) = 0, \quad n = 1, 2, \dots, \\ &\xi_u^1 = \xi_u^2 = \xi_t^1 = \xi_x^2 = \eta_{uu} = 0, \\ &u\beta\xi_x^1 - \alpha\xi_t^2 = 0. \end{aligned}$$

Solving these equations, we obtain

$$\xi^1 = c_1 + \alpha c_2, \quad \xi^2 = t\beta c_2, \quad \eta = \alpha u c_2(3 - \beta),$$

where c_1, c_2 represent arbitrary constants. Thus infinitesimal symmetry group for Eq. (1) is as follows:

$$X_1 = \frac{\partial}{\partial x}, \quad X_2 = \alpha x \frac{\partial}{\partial x} + \beta t \frac{\partial}{\partial t} + \alpha u(3 - \beta) \frac{\partial}{\partial u}. \tag{17}$$

In particular, for the symmetry X_2 , we obtain the following similarity transformation and similarity variable:

$$\frac{dx}{\alpha x} = \frac{dt}{t\beta} = \frac{du}{\alpha u(3 - \beta)}.$$

Solving the above equations, we get

$$z_1 = xt^{-\frac{\alpha}{\beta}}, \quad z_2 = ut^{-\frac{\alpha(3-\beta)}{\beta}}. \tag{18}$$

Hence, from the symmetry X_2 , we get the group-invariant solution

$$u = t^{\frac{\alpha(3-\beta)}{\beta}} f(\xi), \quad \xi = xt^{-\frac{\alpha}{\beta}}, \tag{19}$$

where f is an arbitrary function of ξ .

Theorem By the similarity transformation, Eq. (19) reduces Eq. (1) to the following:

$$\left(P_{\frac{\beta}{\alpha}}^{1-\alpha+\frac{\alpha}{\beta}(3-\beta),\alpha} f\right)(\xi) + f\xi^{-\beta} \left(Q_1^{-\beta,\beta} f\right)(\xi) + \text{ff}_{\xi\xi\xi} + 3f_{\xi}f_{\xi\xi} = 0 \tag{20}$$

with the left-hand-sided EK fractional differential operator [49, 50]

$$\left(K_{\delta}^{\xi^2,\alpha} f\right) = \prod_{j=0}^{n-1} \left(\xi^2 + j - \frac{1}{\delta} \frac{d}{d\xi}\right) \left(K_{\delta}^{\xi^2+\alpha,n-\alpha} f\right)(\xi), \tag{21}$$

$$n = \begin{cases} [\alpha] + 1, & \alpha \notin \mathbf{N}, \\ \alpha, & \alpha \in \mathbf{N}, \end{cases} \tag{22}$$

where

$$\left(K_{\delta}^{\xi^2,\alpha} f\right)(\xi) = \begin{cases} \frac{1}{\Gamma(\alpha)} \int_1^{\infty} (u-1)^{\alpha-1} u^{-(\xi^2+\alpha)} f(\xi u^{\frac{1}{\delta}}) du, & \alpha > 0, \\ f(\xi), & \alpha = 0. \end{cases} \tag{23}$$

The right-hand-sided EK fractional differential operator is given by

$$\left(Q_{\delta}^{\xi^2,\beta} f\right) = \prod_{j=0}^{n-1} \left(\xi^2 + j - \frac{1}{\delta} \frac{d}{d\xi}\right) \left(L_{\delta}^{\xi^2+\beta,n-\beta} f\right)(\xi), \tag{24}$$

$$n = \begin{cases} [\beta] + 1, & \beta \notin \mathbf{N}, \\ \beta, & \beta \in \mathbf{N}, \end{cases} \tag{25}$$

where

$$\left(L_{\delta}^{\xi^2,\beta} f\right)(\xi) = \begin{cases} \frac{1}{\Gamma(\beta)} \int_0^1 (1-u)^{\beta-1} u^{\xi^2} f(\xi u^{\frac{1}{\delta}}) du, & \beta > 0, \\ f(\xi), & \beta = 0. \end{cases} \tag{26}$$

Proof Let $n - 1 < \alpha < 1, n = 1, 2, 3, \dots$. In accordance with the RL fractional derivative in Eq. (15), we get

$$\frac{\partial^{\alpha} u}{\partial t^{\alpha}} = \frac{\partial^n}{\partial t^n} \left[\frac{1}{\Gamma(n-\alpha)} \int_1^t (t-s)^{n-\alpha-1} s^{\frac{\alpha(3-\beta)}{\beta}} f(xs^{-\frac{\alpha}{\beta}}) ds \right]. \tag{27}$$

Let $v = \frac{t}{s}, ds = -\frac{t}{v^2} dv$. Thus, Eq. (27) becomes

$$\frac{\partial^{\alpha} u}{\partial t^{\alpha}} = \frac{\partial^n}{\partial t^n} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \frac{1}{\Gamma(n-\alpha)} \int_1^{\infty} (v-1)^{n-\alpha-1} v^{-(n-\alpha+1+\frac{\alpha(3-\beta)}{\beta})} f(\xi v^{\frac{\alpha}{\beta}}) dv \right]. \tag{28}$$

Applying EK fractional integral operator Eq. (23) to Eq. (28), we get

$$\frac{\partial^{\alpha} u}{\partial t^{\alpha}} = \frac{\partial^n}{\partial t^n} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta},n-\alpha} f\right)(\xi) \right]. \tag{29}$$

We simplify the right-hand side of Eq. (29). Considering $\xi = xt^{-\frac{\alpha}{\beta}}, \phi \in (0, \infty)$, we acquire

$$t \frac{\partial}{\partial t} \phi(\xi) = tx \left(-\frac{\alpha}{\beta}\right) t^{-\frac{\alpha}{\beta}-1} \phi'(\xi) = -\frac{\alpha}{\beta} \xi \frac{\partial}{\partial \xi} \phi(\xi). \tag{30}$$

Hence,

$$\begin{aligned} & \frac{\partial^n}{\partial t^n} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right] \\ &= \frac{\partial^{n-1}}{\partial t^{n-1}} \left[\frac{\partial}{\partial t} \left(t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right) \right] \\ &= \frac{\partial^{n-1}}{\partial t^{n-1}} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}-1} \left(n - \frac{\alpha}{\beta} - \frac{\alpha}{\beta} \xi \frac{\partial}{\partial \xi} \right) \right. \\ & \quad \left. \times \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right]. \end{aligned} \tag{31}$$

Repeating $(n - 1)$ -times, we have

$$\begin{aligned} & \frac{\partial^n}{\partial t^n} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right] \\ &= \frac{\partial^{n-1}}{\partial t^{n-1}} \left[\frac{\partial}{\partial t} \left(t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right) \right] \\ &= \frac{\partial^{n-1}}{\partial t^{n-1}} \left[t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}-1} \left(n - \frac{\alpha}{\beta} - \frac{\alpha}{\beta} \xi \frac{\partial}{\partial \xi} \right) \right. \\ & \quad \left. \times \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right] \\ & \quad \vdots \\ &= t^{-\alpha+\frac{\alpha(3-\beta)}{\beta}} \prod_{j=0}^{n-1} \left[\left(1 - \alpha + \frac{\alpha(3-\beta)}{\beta} + j - \frac{\alpha}{\beta} \xi \frac{\partial}{\partial \xi} \right) \right. \\ & \quad \left. \times \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right]. \end{aligned} \tag{32}$$

Applying EK fractional differential operator Eq. (21) to Eq. (33), we obtain that

$$\frac{\partial^n u}{\partial t^n} \left[\left(t^{n-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(K_{\frac{\beta}{\alpha}}^{1+\frac{\alpha(3-\beta)}{\beta}, n-\alpha} f \right) (\xi) \right) \right] = t^{-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(P_{\frac{\beta}{\alpha}}^{1-\alpha+\frac{\alpha(3-\beta)}{\beta}, \alpha} f \right) (\xi). \tag{34}$$

Substituting Eq. (34) into Eq. (29), we have

$$\frac{\partial^\alpha u}{\partial t^\alpha} = t^{-\alpha+\frac{\alpha(3-\beta)}{\beta}} \left(P_{\frac{\beta}{\alpha}}^{1-\alpha+\frac{\alpha(3-\beta)}{\beta}, \alpha} f \right) (\xi). \tag{35}$$

Comparably, β th-order with respect to x can be derived to be the following:

$$\frac{\partial^\beta u}{\partial x^\beta} = t^{\frac{\alpha(3-\beta)}{\beta}} \xi^{-\beta} \left(Q_1^{-\beta, \beta} f \right) (\xi). \tag{36}$$

Thus, using Eqs. (35) and (36), we obtain

$$\left(P_{\frac{\beta}{\alpha}}^{1-\alpha+\frac{\alpha(3-\beta)}{\beta}, \alpha} f \right) (\xi) + f \xi^{-\beta} \left(Q_1^{-\beta, \beta} f \right) (\xi) + f f_{\xi\xi\xi} + 3f_\xi f_{\xi\xi} = 0. \tag{37}$$

The proof of the theorem is completed. □

4 Explicit power series solutions for Eq. (37)

We investigate the explicit solutions via the PS method [51, 52]. Let

$$f(\xi) = \sum_{n=0}^{\infty} a_n \xi^n. \tag{38}$$

From Eq. (38), we can have

$$f' = \sum_{n=0}^{\infty} n a_n \xi^{n-1}, \quad f'' = \sum_{n=0}^{\infty} n(n-1) a_n \xi^{n-2}, \quad f''' = \sum_{n=0}^{\infty} n(n-1)(n-2) a_n \xi^{n-3}. \tag{39}$$

Putting Eqs. (38) and (39) in Eq. (37), one obtains

$$\begin{aligned} & \sum_{n=0}^{\infty} \frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta} - \frac{n\alpha}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta} - \frac{n\alpha}{\beta})} a_n \xi^n + \sum_{n=0}^{\infty} a_n \xi^n \sum_{n=0}^{\infty} \frac{\Gamma(1-n)}{\Gamma(1-n+\beta)} a_n \xi^n \\ & + \sum_{n=0}^{\infty} a_n \xi^n \sum_{n=0}^{\infty} (n+3)(n+2)(n+1) a_{n+3} \xi^n \\ & + 3 \sum_{n=0}^{\infty} (n+1) a_{n+1} \xi^n \sum_{n=0}^{\infty} (n+2)(n+1) a_{n+2} \xi^n = 0. \end{aligned} \tag{40}$$

Comparing coefficients in Eq. (40) when $n = 0$, we get

$$a_3 = \frac{1}{6a_0} \left(\frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta})} a_0 + \frac{a_0^2}{\Gamma(1+\beta)} - 6a_1 a_2 \right), \tag{41}$$

when $n \geq 1$, we have

$$\begin{aligned} a_{n+3} = & \frac{1}{(n+3)(n+2)(n+1)} \left\{ \frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta} + \frac{n\alpha}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta} - \frac{n\alpha}{\beta})} a_n \right. \\ & \left. + \sum_{k=0}^n \frac{\Gamma(1-n-k)}{\Gamma(1-n-k+\beta)} a_k a_{n-k} \right. \end{aligned} \tag{42}$$

$$\left. - 3 \sum_{k=0}^n (n-k+2)(n-k+1) a_k a_{n-k+2} \right\}. \tag{43}$$

Thus, each coefficient a_n ($n \geq 1$) for Eq. (38) is found by the arbitrary constants a_i ($i = 0, 1, 2$). This means that the explicit PS solution for Eq. (37) exists, and its coefficients depend on Eqs. (41) and (42). Therefore, the PS solution for Eq. (37) can be represented in the form:

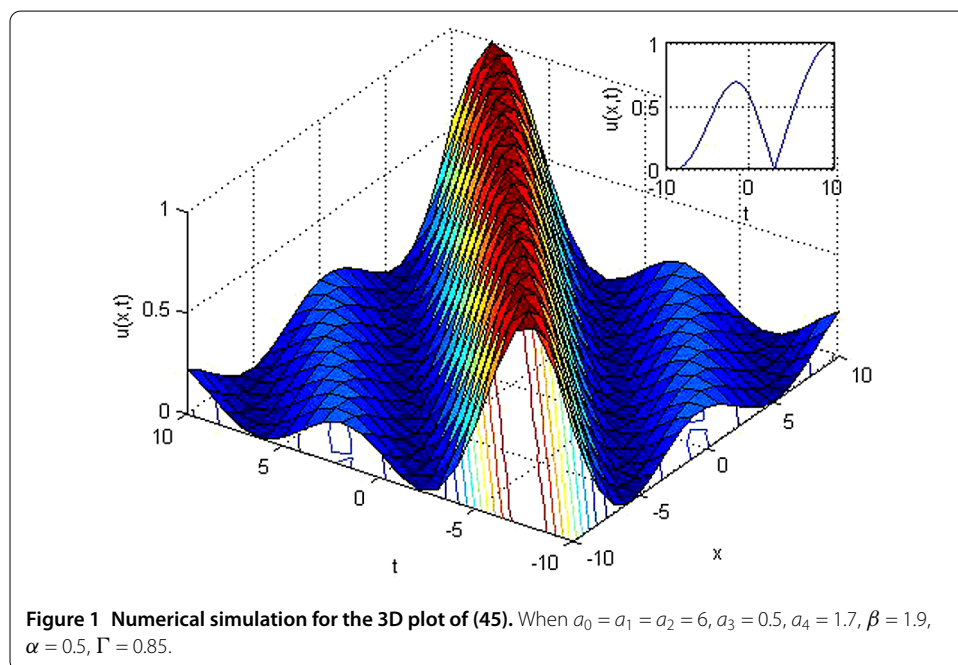
$$\begin{aligned} f(\xi) &= a_0 + a_1 \xi + a_2 \xi^2 + a_3 \xi^3 + \sum_{n=1}^{\infty} a_{n+3} \xi^{n+3} \\ &= a_0 + a_1 \xi + a_2 \xi^2 + \frac{1}{6a_0} \left(\frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta})} a_0 + \frac{a_0^2}{\Gamma(1+\beta)} - 6a_1 a_2 \right) \xi^3 \end{aligned}$$

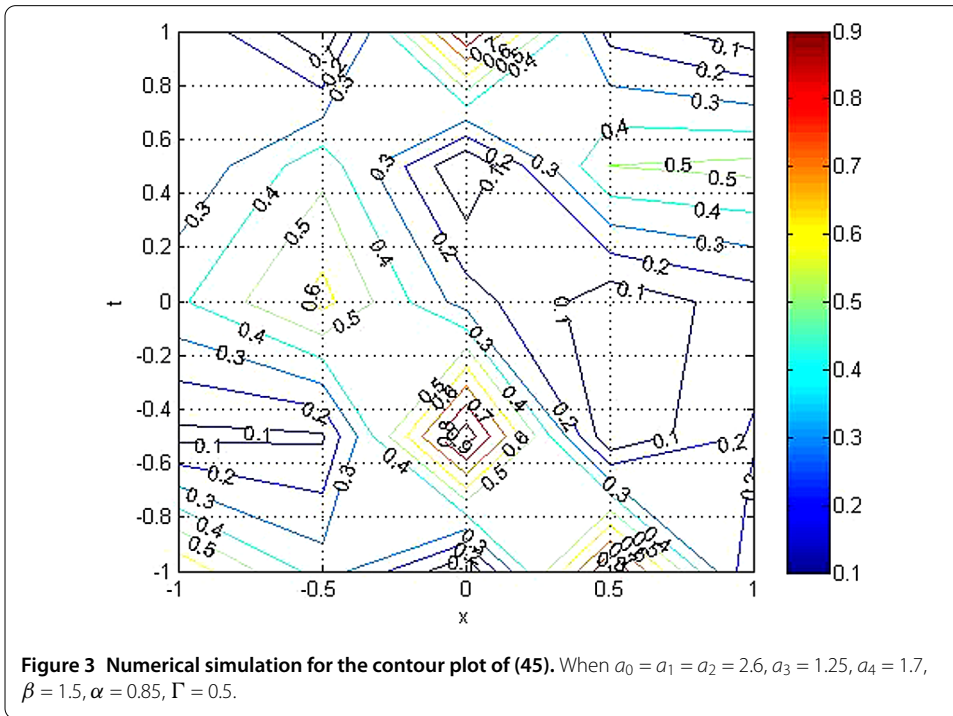
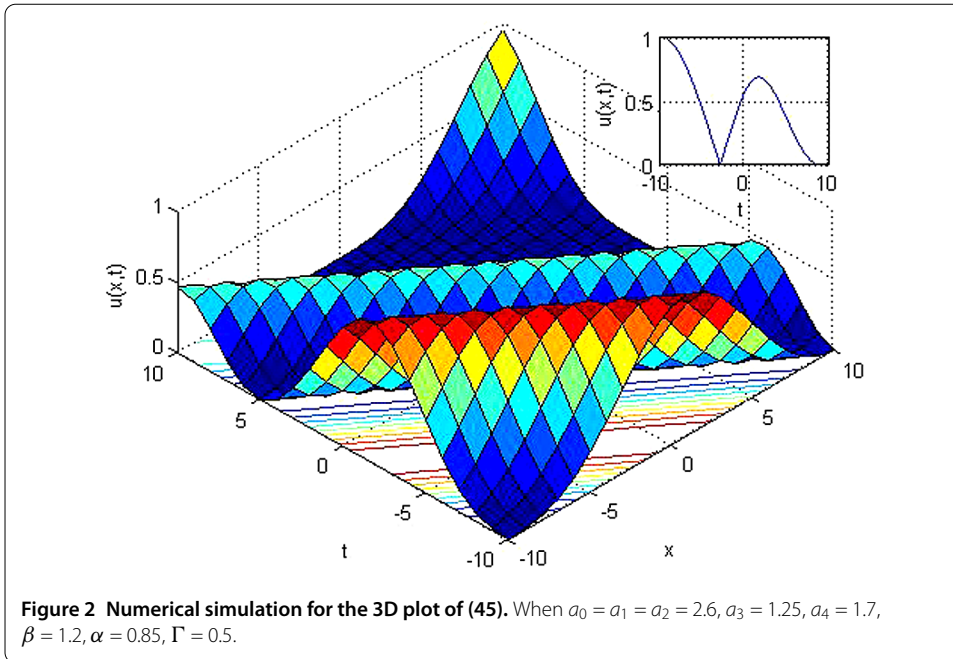
$$\begin{aligned}
 & + \sum_{n=1}^{\infty} \frac{1}{(n+3)(n+2)(n+1)} \left\{ \frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta} + \frac{n\alpha}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta} - \frac{n\alpha}{\beta})} a_n \right. \\
 & + \sum_{k=0}^n \frac{\Gamma(1-n-k)}{\Gamma(1-n-k+\beta)} a_k a_{n-k} \\
 & \left. - 3 \sum_{k=0}^n (n-k+2)(n-k+1) a_k a_{n-k} a_{n-k+2} \right\} \xi^{n+3}. \tag{44}
 \end{aligned}$$

Consequently, we acquire the explicit power series given by

$$\begin{aligned}
 u(x,t) & = a_0 t^{\frac{\alpha(3-\beta)}{\beta}} + a_1 x t^{\frac{\alpha(2-\beta)}{\beta}} + a_2 x t^{\frac{\alpha(1-\beta)}{\beta}} + a_3 x t^{-\alpha} + \sum_{n=1}^{\infty} a_{n+3} x t^{-\frac{\alpha(n+\beta)}{\beta}} \\
 & = a_0 t^{\frac{\alpha(3-\beta)}{\beta}} + a_1 x t^{\frac{\alpha(2-\beta)}{\beta}} + a_2 x t^{\frac{\alpha(1-\beta)}{\beta}} \\
 & + \frac{1}{6a_0} \left(\frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta})} a_0 + a_0^2 \xi^{-\beta} \Gamma(1-\beta) - 6a_1 a_2 \right) x t^{-\alpha} \\
 & + \sum_{n=1}^{\infty} \frac{1}{(n+3)(n+2)(n+1)} \left\{ \frac{\Gamma(2-\alpha + \frac{\alpha(3-\beta)}{\beta} + \frac{n\alpha}{\beta})}{\Gamma(2 + \frac{\alpha(3-\beta)}{\beta} - \frac{n\alpha}{\beta})} a_n \right. \\
 & + \xi^{-\beta} \sum_{k=0}^n \frac{\Gamma(1-\beta+n-k)}{1-n-k} a_k a_{n-k} \\
 & \left. - 3 \sum_{k=0}^n (n-k+2)(n-k+1) a_k a_{n-k} a_{n-k+2} \right\} x t^{-\frac{(n+3)\alpha}{\beta}}. \tag{45}
 \end{aligned}$$

In Figures 1-3, we have illustrated the physical features for Eq. (45) with different parameter values.





5 Conservation laws

More details about the description of Cls can be found in [1, 27, 33, 52]. The Lagrangian is presented by

$$L = v(x, t) \left(\frac{\partial^\alpha u}{\partial t^\alpha} + u \frac{\partial^\beta u}{\partial t^\beta} + uu_{xxx} + 3u_x u_{xx} \right). \tag{46}$$

In Eq. (46) $v(x, t)$ is another dependent variable. The Euler-Lagrange operator [33] is

$$\frac{\delta}{\delta u} = \frac{\partial}{\partial u} + (D_t^\alpha)^* \frac{\partial}{\partial D_t^\alpha u} + (D_x^\beta)^* \frac{\partial}{\partial D_x^\beta u} - D_x \frac{\partial}{\partial u_x} + D_{xx}^2 \frac{\partial}{\partial u_{xx}} - D_{xxx}^3 \frac{\partial}{\partial u_{xxx}}, \tag{47}$$

where $(D_t^\alpha)^*$ and $(D_x^\beta)^*$ are the adjoint operators of (D_t^α) and (D_x^β) , respectively. The adjoint equation is given by [33]

$$F^* = \frac{\delta L}{\delta u} = 0. \tag{48}$$

So, we can have

$$\bar{X} + D_t(\xi^2)l + D_x(\xi^1)l = W \frac{\delta}{\delta u} + D_t N^t + D_x N^x. \tag{49}$$

In Eq. (49) l represents the identity operator, $\frac{\delta}{\delta u}$ is the Euler-Lagrangian operator, N^t and N^x represent the Noether operators, \bar{X} is defined by

$$\begin{aligned} \bar{X} = & \xi^2 \frac{\partial}{\partial t} + \xi^1 \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial u} + \eta^{\alpha,t} \frac{\partial}{\partial D_t^\alpha u} + \eta^{\beta,x} \frac{\partial}{\partial D_x^\beta u} \\ & + \eta^x \frac{\partial}{\partial u_x} + \eta^{xx} \frac{\partial}{\partial u_{xx}} + \eta^{xxx} \frac{\partial}{\partial u_{xxx}}. \end{aligned} \tag{50}$$

With the help of Eqs. (46) and (48), we can write the adjoint equation to Eq. (1) as follows:

$$F^* = (D_t^\alpha)^* v + u(D_x^\beta)^* v + u(v_x + v_{xxx}) = 0. \tag{51}$$

Next, we look for the differential substitution for nonlinear self-adjointness. Let

$$v = \phi(x, t, u), \quad \text{such that } \phi(x, t, u) \neq 0. \tag{52}$$

Thus, taking the derivatives of Eq. (52), we have

$$\begin{aligned} v_x &= \phi_x + \phi_u u_x, \\ v_{xx} &= \phi_{xx} + 2\phi_{xu} u_x + \phi_u u_{xx} + \phi_{uu} u_x^2, \\ v_{xxx} &= \phi_{xxx} + 3\phi_{xxu} u_x + 3\phi_{xuu} u_x^2 + 3\phi_{xu} u_{xx} + 3\phi_{uu} u_x u_{xx} + \phi_u u_{xxx} + \phi_{uuu} u_x^3. \end{aligned} \tag{53}$$

Inserting Eqs. (52) and (53) into Eq. (51) and solving the results, we obtain

$$\phi(x, t, u) = A_1 x + A_2. \tag{54}$$

Therefore, the variable $v(x, t) = A_1 x + A_2$, and it will be used for the analysis of the Cls.

The Lie characteristic function W is given by

$$W = \eta - \xi^2 u_t - \xi^1 u_x. \tag{55}$$

The t component of the conserved vectors is defined by [33, 52]

$$N^t = \xi^2 l + \sum_{k=0}^{n-1} (-1)^k {}_oD^{\alpha-1-k}(W) D_t^k \frac{\partial}{\partial {}_oD_t^\alpha u} - (-1)^n J \left(W, D_t^n \frac{\partial}{\partial {}_oD_t^\alpha u} \right), \tag{56}$$

where $n = [\alpha] + 1$ and J is given by

$$J(f, g) = \frac{1}{\Gamma(n - \alpha)} \int_0^t \int_t^p \frac{f(\xi^2, x) g(x, \mu)}{(\mu - \xi^2)^{\alpha+1-n}} d\mu dt. \tag{57}$$

Equivalently, the x component of the conserved vectors (CV) can be expressed as

$$N^x = \xi^1 l + \sum_{k=0}^{m-1} (-1)^k {}_oD^{\beta-1-k}(W) D_x^k \frac{\partial}{\partial {}_oD_x^\beta u} - (-1)^m J_1 \left(W, D_x^m \frac{\partial}{\partial {}_oD_x^\beta u} \right), \tag{58}$$

where $m = [\beta] + 1$ and J_1 is given by

$$J_1(f, g) = \frac{1}{\Gamma(n - \beta)} \int_0^x \int_t^q \frac{f(\xi^1, t) g(\mu, t)}{(\mu - \xi^1)^{\beta+1-m}} d\mu dt. \tag{59}$$

The invariance condition for any given generator X of Eq. (1) and its solutions reads as follows:

$$(\bar{X}L + D_t(\xi^2)L + D_x(\xi^1)L)|_{\text{Eq. (1)}} = 0; \tag{60}$$

and consequently, the Cls of Eq. (1) can be written as

$$D_t(N^t L) + D_x(N^x L) = 0. \tag{61}$$

Now, we present the Cls for Eq. (1) using the basic definitions presented above. Consider the following cases.

Case 1. For $\alpha \in (0, 1)$, the t components of the CV are

$$\begin{aligned} C_1^t &= {}_oD_t^{\alpha-1}(W_i)(A_1x + A_2) + J(W_i, v_i), \\ C_2^t &= W_i(3u_{xx}(A_1x + A_2) - 3D_t(u_x(A_1x + A_2)) + D_t^2(u(A_1x + A_2))) \\ &\quad + D_t(W_i)(3u_x - D_t(u(A_1x + A_2))) + D_t^2(W_i u(A_1x + A_2)), \end{aligned}$$

where $i = 1, 2$ and the functions W_i are given by

$$W_1 = u_x, \quad W_2 = \alpha u(3 - \beta) - \beta t u_t + \alpha x u_x.$$

Case 2. For $\alpha \in (1, 2)$, the t components of the CV are

$$\begin{aligned} C_3^t &= {}_oD_t^{\alpha-1}(W_i)(A_1x + A_2) + J(W_i, v_i) - v_i {}_oD_t^{\alpha-2}(W_i) - J(W_i, v_{tt}), \\ C_4^t &= W_i(3u_{xx}v - 3D_t u_x(A_1x + A_2) + D_t^2(u(A_1x + A_2))) \\ &\quad + D_t(W_i)(3u_x - D_t(uv)) + D_t^2(W_i)u(A_1x + A_2), \end{aligned}$$

where $i = 1, 2$ and the functions W_i are given by

$$W_1 = u_x, \quad W_2 = \alpha u(3 - \beta) - \beta t u_t + \alpha x u_x.$$

Case 3. For $\beta \in (0, 1)$, the x components of the CV are

$$\begin{aligned} C_1^x &= {}_0D_x^{\beta-1}(W_i)(A_1x + A_2) + J(W_i, v_i), \\ C_2^x &= W_i(3u_{xx}(A_1x + A_2) - 3D_x u_x(A_1x + A_2) + D_x^2 u(A_1x + A_2)) \\ &\quad + D_x(W_i)(3u_x - D_x u(A_1x + A_2)) + D_x^2(W_i)u(A_1x + A_2), \end{aligned}$$

where $i = 1, 2$ and the functions W_i are given by

$$W_1 = u_x, \quad W_2 = \alpha u(3 - \beta) - \beta t u_t + \alpha x u_x.$$

Case 4. For $\beta \in (1, 2)$, the x components of the CV are

$$\begin{aligned} C_3^x &= {}_0D_x^{\beta-1}(W_i)(A_1x + A_2) + J(W_i, v_i) - v_t {}_0D_x^{\beta-2}(W_i) - J(W_i, v_{tt}), \\ C_4^x &= W_i(3u_{xx}(A_1x + A_2) - 3D_x u_x(A_1x + A_2) + D_x^2 u(A_1x + A_2)) \\ &\quad + D_x(W_i)(3u_x - D_x u(A_1x + A_2)) + D_x^2(W_i)u(A_1x + A_2), \end{aligned}$$

where $i = 1, 2$ and the functions W_i are given by

$$W_1 = u_x, \quad W_2 = \alpha u(3 - \beta) - \beta t u_t + \alpha x u_x.$$

6 Concluding remarks

This work used the extension presented in [1, 2] to examine the LSA and CIs for the space-time fractional Rosenou-Haynam equation (RHE) with RL derivative. The space-time fractional RHE was reduced to space-time ODE of fractional order using its Lie point symmetries with a new dependent variable. We solved the reduced space-time ODE using the power series method for the first time. Moreover, we constructed CIs for the governing equation using a new conservation theorem.

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Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally to the writing of this paper. All authors read and approved the manuscript.

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