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Positive solutions to singular Dirichlet-type boundary value problems of nonlinear fractional differential equations

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Abstract

In this paper, by using the properties of the Green function, u_0 -positive operator and Gelfand's formula, some properties of the first eigenvalue corresponding to the relevant operator are obtained. Based on these properties, the fixed point index of the nonlinear operator is calculated explicitly and some sufficient conditions for the existence and uniqueness results of positive solution are established.

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Keywords: Positive solutions; First eigenvalue; u_0 -positive operator; Singularity; Fixed point index

1 Introduction

The boundary value problems (BVPs) for fractional differential equations arise from the studies of models of aerodynamics, fluid flows, electrodynamics of complex medium, electrical networks, rheology, polymer rheology, economics, biology chemical physics, control theory, signal and image processing. Recently, the study of such kind of problems has received considerable attention both in theory and applications, see [1–30] and the references therein, such as resonant BVP [3, 18, 25], singular BVP [7, 15, 20, 30], nonlocal BVP [8, 14, 17, 29] and semipositone BVP [11, 16, 24, 28].

Specially, there are a few papers considering the Dirichlet-type problem for ordinary differential equations of fractional order; see [1, 4, 6, 10, 13, 27]. Bai and Lü [4] have investigated the following BVP:

$$\begin{cases} D_{0+}^{\alpha} x(t) + f(t, x(t)) = 0, & 0 < t < 1, \\ x(0) = 0, & x(1) = 0, \end{cases} \quad (1.1)$$

where $1 < \alpha \leq 2$ and $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ continuous, by means of the Krasnosel'skii fixed point theorem and the Leggett–Williams fixed point theorem, the existence and multiplicity of positive solutions for BVP (1.1) are obtained. By using the Krasnosel'skii fixed point theorem, Jiang and Yuan [13] studied the existence and multiplicity of positive solutions of BVP (1.1). By using the Leray–Schauder nonlinear alternative and a fixed point theorem on cones, BVP (1.1) are also studied in [27], the authors establish the exis-

tence of multiple positive solutions to positone and semipositone Dirichlet-type BVP (1.1). In [10], the authors investigated problems (1.1) with $f(t, x(t))$ replaced by $\lambda a(t)f(t, x(t))$, the existence of positive solutions are obtained by means of the fixed point theory in cones.

Recently, in [26], the authors investigated the existence and uniqueness of the positive solutions for the two-term fractional differential equations of the type:

$$\begin{cases} -D_{0+}^\alpha x(t) + bx(t) = f(t, x(t)), & 0 < t < 1, \\ x(0) = 0, & x(1) = 0, \end{cases}$$

where $1 < \alpha < 2, b > 0, D_{0+}^\alpha$ is the Riemann–Liouville fractional derivative. They derived the corresponding Green function called the fractional Green function and obtained some properties. By means of the mixed monotone operator theorem, the existence and uniqueness of positive solution are obtained under the singular conditions.

Inspired by the above work, we study the existence and uniqueness of the positive solutions for the following two-term fractional differential equations BVP:

$$\begin{cases} -D_{0+}^\alpha x(t) + bx(t) = a(t)f(t, x(t)), & 0 < t < 1, \\ x(0) = 0, & x(1) = 0, \end{cases} \tag{1.2}$$

where $1 < \alpha < 2, b > 0, D_{0+}^\alpha$ is the Riemann–Liouville fractional derivative, $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ is continuous, $a(t)$ is continuous and may be singular at $t = 0, 1$. Under some certain conditions, by use of u_0 -positive operator and the fixed point index theorem, we obtain some existence and unique results of positive solutions.

Our work presented in this paper has the following features. First of all, we discuss the equation contain two term, i.e., $-D_{0+}^\alpha x(t) + bx(t) = f(t, x(t))$, this is different from [4, 10], in other words, Ref. [4, 10] and this article discuss different problems. The second new feature is that BVP (1.2) possesses a singularity, that is, the nonlinear term may be singular at $t = 0, 1$; this is different from [4, 10]. Thirdly, we discuss BVP (1.2), by using the properties of the Green function, u_0 -positive operator and Gelfand’s formula, some sufficient conditions for the existence and uniqueness results of positive solution are established. The method used differs significantly from [4, 10, 26]. So our results are new and meaningful.

The rest of this paper is organized as follows. In Sect. 2, we present some lemmas that are used to prove our main results. In Sect. 3, under the assumption that $f(t, y)$ is a Lipschitz continuous function, by use of u_0 -positive operator, the uniqueness of positive solutions is established. The interesting point is that the Lipschitz constant is related to the first eigenvalues corresponding to the relevant operators. In Sect. 4, the existence results of positive solutions are obtained by use of the fixed point index and spectral radius of some related linear operator.

2 Basic definitions and preliminaries

For the convenience of the reader, we present here some notation and lemmas which will be used in the proofs of our results.

Definition 2.1 The Riemann–Liouville fractional integral of order $\alpha > 0$ of a function $u : (0, \infty) \rightarrow \mathbb{R}$ is given by

$$I_{0+}^\alpha u(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} u(s) ds,$$

provided that the right-hand side is pointwise defined on $(0, \infty)$.

Definition 2.2 The Riemann–Liouville fractional derivative of order $\alpha > 0$ of a function $u : (0, \infty) \rightarrow \mathbb{R}$ is given by

$$D_{0+}^\alpha u(t) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dt}\right)^n \int_0^t (t-s)^{n-\alpha-1} u(s) ds,$$

where $n = [\alpha] + 1$, $[\alpha]$ denotes the integer part of number α , provided that the right-hand side is pointwise defined on $(0, \infty)$.

Set

$$G(t, s) = \frac{1}{H(1)} \begin{cases} H(t)H(1-s), & 0 \leq t \leq s \leq 1, \\ H(t)H(1-s) - H(t-s)H(1), & 0 \leq s \leq t \leq 1, \end{cases} \tag{2.1}$$

where $H(t) = t^{\alpha-1} E_{\alpha,\alpha}(bt^\alpha)$, and

$$E_{\alpha,\alpha}(y) = \sum_{k=0}^{+\infty} \frac{y^k}{\Gamma((k+1)\alpha)},$$

is the Mittag-Leffler function [19, 21]. Denote

$$h(y) = \frac{\alpha-2}{\Gamma(\alpha-1)} + \sum_{k=1}^{+\infty} \frac{y^k}{\Gamma((k+1)\alpha-2)}, \quad y \in [0, \infty).$$

It is easy to verify that there exists a unique $\tilde{b} > 0$ such that $h(\tilde{b}) = 0$. We list the following assumptions adopted in this paper.

- (H₀) $b \in (0, \tilde{b}]$.
- (H₁) $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ is continuous.
- (H₂) $a : (0, 1) \rightarrow [0, \infty)$ is continuous and not identical zero on any closed subinterval of $(0, 1)$ with

$$0 < \int_0^1 s^{\alpha-j} (1-s)^{\alpha-j} a(s) ds < +\infty, \quad j = 1, 2.$$

The following three lemmas can be found in [26].

Lemma 2.3 *Suppose that (H₀) holds and $\omega \in L[0, 1]$. Then the problem*

$$\begin{cases} -D_{0+}^\alpha x(t) + bx(t) = \omega(t), & 0 < t < 1, \\ x(0) = 0, & x(1) = 0, \end{cases}$$

has a unique solution

$$x(t) = \int_0^1 G(t,s)\omega(s) ds.$$

Lemma 2.4 Suppose that (H_0) holds, then the function $G(t,s)$ has the following properties:

- (1) $G(t,s) > 0, \forall t,s \in (0,1)$;
- (2) $G(t,s) = G(1-s,1-t), \forall t,s \in [0,1]$;
- (3) $G(t,s) \leq H(1)s(1-s)^{\alpha-1}t^{\alpha-2}, \forall t,s \in [0,1]$;
- (4) $G(t,s) \geq \Lambda s(1-s)^{\alpha-1}(1-t)t^{\alpha-1}, \forall t,s \in [0,1]$, where

$$\Lambda = \min \left\{ (\alpha - 1)^2 H(1), \frac{1}{H(1)(\Gamma(\alpha))^2} \right\}.$$

Lemma 2.5 The function $K(t,s) =: t^{2-\alpha}G(t,s)$ has the following properties:

- (1) $K(t,s) > 0, \forall t,s \in (0,1)$;
- (2) $K(t,s) \leq H(1)(1-s)^{\alpha-2}t(1-t), \forall t,s \in [0,1]$;
- (3) $K(t,s) \leq H(1)s(1-s)^{\alpha-1}, \forall t,s \in [0,1]$;
- (4) $K(t,s) \geq \Lambda s(1-s)^{\alpha-1}t(1-t), \forall t,s \in [0,1]$.

Let $E = C[0,1]$, then E is a Banach space with the norm $\|x\| = \max_{0 \leq t \leq 1} |x(t)|$, for any $x \in E$. Set $P = \{x \in E : x(t) \geq 0 \text{ for } t \in [0,1]\}$. P is a positive cone in E .

Define a nonlinear operator T and a linear operator L as follows:

$$(Tx)(t) = \int_0^1 K(t,s)a(s)f(s,s^{\alpha-2}x(s)) ds, \quad x \in C[0,1], \tag{2.2}$$

$$(Lx)(t) = \int_0^1 K(t,s)a(s)s^{\alpha-2}x(s) ds, \quad x \in C[0,1]. \tag{2.3}$$

It is not difficult to verify that $L : E \rightarrow E$ is linear completely continuous and $L(P) \subset P$.

The following concept is due to Krasnosel'skii [31].

Definition 2.6 We say that a bounded linear operator $L : E \rightarrow E$ is u_0 -positive on the cone P if there exists $u_0 \in P \setminus \{\theta\}$ such that for every $x \in P \setminus \{\theta\}$ there exist a natural number n and positive constants $\beta(x), \gamma(x)$ such that

$$\beta(x)u_0 \leq L^n x \leq \gamma(x)u_0.$$

Lemma 2.7 L is u_0 -positive operator with $u_0(t) = t(1-t)$.

Proof For any $x \in P \setminus \{\theta\}$, it follows from Lemma 2.5 that

$$(Lx)(t) = \int_0^1 K(t,s)a(s)s^{\alpha-2}x(s) ds \leq H(1)t(1-t) \int_0^1 (1-s)^{\alpha-2}a(s)s^{\alpha-2}x(s) ds.$$

On the other hand, by Lemma 2.5, we also have

$$(Lx)(t) = \int_0^1 K(t,s)a(s)s^{\alpha-2}x(s) ds \geq \Lambda t(1-t) \int_0^1 s^{\alpha-1}(1-s)^{\alpha-1}a(s)x(s) ds.$$

The above inequalities show that L is u_0 -positive operator with $u_0(t) = t(1-t)$. □

Lemma 2.8 (Krein–Rutmann [32]) *Let $L : E \rightarrow E$ be a continuous linear operator, P be a total cone and $L(P) \subset P$. If there exist $\psi \in E \setminus (-P)$ and a positive constant c such that $cL(\psi) \geq \psi$, then the spectral radius $r(L) \neq 0$ and L has a positive eigenfunction corresponding to its first eigenvalue $\lambda = (r(L))^{-1}$.*

It follows from Lemma 2.7 and Lemma 2.8 that the spectral radius $r(L) \neq 0$, moreover L has a positive eigenfunction $\varphi^*(t)$ corresponding to its first eigenvalue $\lambda_1 = (r(L))^{-1}$.

Remark 2.9 Let φ^* be the positive eigenfunction of L corresponding to λ_1 , i.e., $\lambda_1 L\varphi^* = \varphi^*$. Then, by Definition 2.6 and Lemma 2.7, there exist $\delta_1(\varphi^*), \delta_2(\varphi^*) > 0$ such that

$$\delta_1(\varphi^*)u_0 \leq L\varphi^* = \frac{1}{\lambda_1}\varphi^* \leq \delta_2(\varphi^*)u_0.$$

Thus we found that L is φ^* -positive operator.

Lemma 2.10 ([31]) *Let L be a completely continuous u_0 -bounded operator, $\lambda_1 > 0$ is the first eigenvalue of L , y_0 is a positive eigenfunction which belongs to $P \setminus \{\theta\}$. Then, for any $y \in P \setminus \{\theta\}$ with $y \neq \mu y_0$ ($\mu \geq 0$), $\lambda_1 Ly \not\leq y$ and $\lambda_1 Ly \not\geq y$.*

3 Uniqueness of positive solution

We now wish to show that under certain conditions, BVP (1.2) has a unique positive solution.

Theorem 3.1 *Suppose that (H_0) , (H_1) and (H_2) hold and there exists $\kappa \in [0, 1)$ such that*

$$|f(t, u) - f(t, v)| \leq \kappa \lambda_1 |u - v|, \quad \forall t \in [0, 1], u, v \in [0, \infty),$$

where λ_1 is the first eigenvalue of L defined by (2.3). Then BVP (1.2) has a unique positive solution $\bar{x} = t^{\alpha-2}x^*$ in P , and for any $x_0 \in P \setminus \{\theta\}$, the iterative sequence $x_n = Tx_{n-1}$ ($n = 1, 2, \dots$) converges to x^* .

Proof It is not difficult to prove that $T : P \rightarrow P$ is completely continuous and the existence of positive solution $t^{\alpha-2}x$ for BVP (1.2) is equivalent to that of fixed point x of T in P .

For any given $x_0 \in P \setminus \{\theta\}$, let $x_n = Tx_{n-1}$ ($n = 1, 2, \dots$). By Remark 2.9, there exists $\delta = \delta(|x_1 - x_0|) > 0$ such that

$$(L|x_1 - x_0|)(t) \leq \delta\varphi^*(t), \quad t \in [0, 1].$$

For $m \in \mathbb{N}$,

$$\begin{aligned} &|x_{m+1}(t) - x_m(t)| \\ &= |(Tx_m)(t) - (Tx_{m-1})(t)| \\ &= \left| \int_0^1 K(t, s)a(s)f(s, s^{\alpha-2}x_m(s)) ds - \int_0^1 K(t, s)a(s)f(s, s^{\alpha-2}x_{m-1}(s)) ds \right| \\ &\leq \int_0^1 K(t, s)a(s)|f(s, s^{\alpha-2}x_m(s)) - f(s, s^{\alpha-2}x_{m-1}(s))| ds \end{aligned}$$

$$\begin{aligned} &\leq \kappa \lambda_1 L(|x_m - x_{m-1}|)(t) \leq \dots \leq \lambda_1^m \kappa^m L^m(|x_1 - x_0|)(t) \\ &\leq \lambda_1^m \kappa^m L^{m-1}(\delta \varphi^*(t)) = \lambda_1^m \kappa^m \delta L^{m-1}(\varphi^*(t)) \\ &= \lambda_1 \delta \kappa^m \varphi^*(t), \quad t \in [0, 1]. \end{aligned}$$

So, for any $n, m \in \mathbb{N}$, we have

$$\begin{aligned} |x_{n+m+1}(t) - x_n(t)| &= |x_{n+m+1}(t) - x_{n+m}(t) + \dots + x_{n+1}(t) - x_n(t)| \\ &\leq |x_{n+m+1}(t) - x_{n+m}(t)| + \dots + |x_{n+1}(t) - x_n(t)| \\ &\leq \lambda_1 \delta (\kappa^{m+n} + \dots + \kappa^n) \varphi^*(t) \\ &= \lambda_1 \delta \frac{\kappa^n (1 - \kappa^{m+1})}{1 - \kappa} \varphi^*(t), \quad t \in [0, 1]. \end{aligned} \tag{3.1}$$

Consequently,

$$\|x_{n+m+1} - x_n\| \leq \lambda_1 \delta \frac{\kappa^n (1 - \kappa^{m+1})}{1 - \kappa} \|\varphi^*\| \rightarrow 0, \quad \text{as } n, m \rightarrow \infty.$$

By the completeness of P , there exists a $x^* \in P$ such that $\lim_{n \rightarrow \infty} x_n = x^*$. Passing to the limit into $x_{n+1} = Tx_n$ and using the fact that T is continuous, it follows that x^* is a fixed point of T in P .

Now we show that T has at most one fixed point in P . Suppose there exist two elements $x, y \in P$ with $x = Tx$ and $y = Ty$. By Lemma 2.7, there exists $\delta = \delta(|x - y|) > 0$ such that

$$(L|x - y|)(t) \leq \delta \varphi^*(t), \quad t \in [0, 1].$$

Then, for any $n \in \mathbb{N}$, we have

$$|x(t) - y(t)| = |(T^n x)(t) - (T^n y)(t)| \leq \kappa^n \delta \lambda_1 \varphi^*(t)$$

which can happen only if $x = y$. This implies that T has at most one fixed point.

Then x^* is the unique fixed point of T in P and $\bar{x} = t^{\alpha-2} x^*$ is the unique positive solution of BVP (1.2). The proof is completed. □

Remark 3.2 Let $m \rightarrow +\infty$ in (3.1), we have error estimation

$$\|x_n - x^*\| \leq \lambda_1 \delta \frac{\kappa^n}{1 - \kappa} \|\varphi^*\|,$$

and with the rate of convergence

$$\|x_n - x^*\| = O(\kappa^n).$$

Remark 3.3 In Theorem 3.1 and Remark 3.2, we not only give the condition of the existence of a unique positive solution, but also establish an iterative sequence of solution and error estimation. In particular, since $u_0(t) = t(1 - t) \in P$, and the initial value of the iterative sequence can begin from $x_0 = u_0 = t(1 - t)$, this is simpler and helpful for computation.

4 Existence of a positive solution

In this section we wish to deduce the existence of at least one positive solution to BVP (1.2). To accomplish this, we shall construct a subcone of P as follows:

$$Q = \left\{ x \in P : x(t) \geq \frac{\Lambda}{H(1)} t(1-t) \|x\| \text{ for } t \in [0, 1] \right\}.$$

For any $r > 0$, let $Q_r = \{x \in Q : \|x\| < r\}$, $\partial Q_r = \{x \in Q : \|x\| = r\}$, $\overline{Q}_r = \{x \in Q : \|x\| \leq r\}$.

Lemma 4.1 ([33]) *Let Q be a cone in Banach space E . Suppose that $T : \overline{Q}_r \rightarrow Q$ is a completely continuous operator.*

- (i) *If there exists $y_0 \in Q \setminus \{\theta\}$ such that $y - Ty \neq \mu y_0$ for any $y \in \partial Q_r$ and $\mu \geq 0$, then $i(T, Q_r, Q) = 0$.*
- (ii) *If $Ty \neq \mu y$ for any $y \in \partial Q_r$ and $\mu \geq 1$, then $i(T, Q_r, Q) = 1$.*

Lemma 4.2 ([33]) *Let Ω_1 and Ω_2 be two bounded open sets in Banach space E such that $\theta \in \Omega_1$ and $\overline{\Omega}_1 \subset \Omega_2$. Let operator $T : (\overline{\Omega}_2 \setminus \Omega_1) \cap Q \rightarrow Q$ is a completely continuous. Suppose that one of the two conditions*

- (i) *if $Ty \not\leq y, \forall y \in \partial Q \cap \Omega_1; Ty \not\leq y, \forall y \in \partial Q \cap \Omega_2$ and*
- (ii) *if $Ty \not\leq y, \forall y \in \partial Q \cap \Omega_1; Ty \not\geq y, \forall y \in \partial Q \cap \Omega_2$ is satisfied.*

Then T has at least one fixed point in $(\Omega_2 \setminus \overline{\Omega}_1) \cap Q$.

Lemma 4.3 *Assume that $(H_0), (H_1)$ and (H_2) hold, then $T : Q \rightarrow Q$ is completely continuous.*

Proof For any $x \in Q, t \in [0, 1]$, by Lemma 2.5, we have

$$\begin{aligned} (Tx)(t) &= \int_0^1 K(t,s)a(s)f(s,s^{\alpha-2}x(s)) ds \\ &\leq H(1) \int_0^1 s(1-s)^{\alpha-1}a(s)f(s,s^{\alpha-2}x(s)) ds. \end{aligned}$$

That is,

$$\|Tx\| \leq H(1) \int_0^1 s(1-s)^{\alpha-1}a(s)f(s,s^{\alpha-2}x(s)) ds.$$

On the other hand, by Lemma 2.5, we also have

$$\begin{aligned} (Tx)(t) &= \int_0^1 K(t,s)a(s)f(s,s^{\alpha-2}x(s)) ds \\ &\geq \Lambda t(1-t) \int_0^1 s(1-s)^{\alpha-1}a(s)f(s,s^{\alpha-2}x(s)) ds \\ &\geq \frac{\Lambda}{H(1)} t(1-t) \|Tx\|. \end{aligned}$$

Therefore, $T(Q) \subset Q$. And, by a standard argument, we know that $T : Q \rightarrow Q$ is completely continuous. The proof is completed. □

Theorem 4.4 *Suppose that the conditions (H₀), (H₁) and (H₂) are satisfied, and*

$$\liminf_{y \rightarrow 0^+} \frac{f(t, y)}{y} > \lambda_1, \quad \text{uniformly on } t \in [0, 1], \tag{4.1}$$

$$\limsup_{y \rightarrow +\infty} \frac{f(t, y)}{y} < \lambda_1, \quad \text{uniformly on } t \in [0, 1], \tag{4.2}$$

where λ_1 is the first eigenvalue of L defined by (2.3). Then BVP (1.2) has at least one positive solution.

Proof It follows from (4.1) that there exist $r > 0$ and $\varepsilon_1 > 0$, such that

$$f(t, y) \geq (\lambda_1 + \varepsilon_1)y, \quad 0 \leq y \leq r, t \in [0, 1]. \tag{4.3}$$

Let φ^* be the positive eigenfunction of L corresponding to λ_1 , thus $\varphi^* = \lambda_1 L\varphi^*$. For any $x \in \partial Q_r$, by virtue of (2.2) and (4.3), we have

$$(Tx)(t) \geq (\lambda_1 + \varepsilon_1) \int_0^1 K(t, s)a(s)s^{\alpha-2}x(s) ds = (\lambda_1 + \varepsilon_1)(Lx)(t), \quad t \in [0, 1]. \tag{4.4}$$

We may suppose that T has no fixed point on ∂Q_r (otherwise, the proof is finished). Now we show that

$$x - Tx \neq \mu\varphi^*, \quad x \in \partial Q_r, \mu \geq 0. \tag{4.5}$$

If otherwise, there exist $x_0 \in \partial Q_r$ and $\mu_0 \geq 0$ such that $x_0 - Tx_0 = \mu_0\varphi^*$. Obviously, $\mu_0 > 0$ and $x_0 = Tx_0 + \mu_0\varphi^* \geq \mu_0\varphi^*$. Let $\bar{\mu} = \sup\{\mu | x_0 \geq \mu\varphi^*\}$, then $\bar{\mu} \geq \mu_0 > 0$ and $x_0 \geq \bar{\mu}\varphi^*$. Since $L(Q) \subset Q$, we have $(\lambda_1 + \varepsilon_1)Lx_0 \geq \lambda_1 Lx_0 \geq \lambda_1 \bar{\mu}L\varphi^* = \bar{\mu}\varphi^*$. Therefore, using (4.4), we have

$$x_0 = Tx_0 + \mu_0\varphi^* \geq \lambda_1 Lx_0 + \mu_0\varphi^* \geq \bar{\mu}\varphi^* + \mu_0\varphi^* = (\bar{\mu} + \mu_0)\varphi^*,$$

which contradicts the definition of $\bar{\mu}$. Hence (4.5) is true and it follows from Lemma 4.1 that

$$i(T, Q_r, Q) = 0. \tag{4.6}$$

Considering (4.2), there exist $R_0 > r$ and ε_2 ($0 < \varepsilon_2 < \lambda_1$) such that

$$f(t, y) \leq (\lambda_1 - \varepsilon_2)y, \quad \forall y \geq R_0, t \in [0, 1]. \tag{4.7}$$

By the hypothesis (H₁), we have

$$M_0 = \max\{f(t, y) | t \in [0, 1], 0 \leq y \leq R_0\} < +\infty.$$

Hence

$$f(t, y) \leq (\lambda_1 - \varepsilon_2)y + M_0, \quad \text{for any } y \geq 0, t \in [0, 1]. \tag{4.8}$$

Now we set

$$B = \{x \in Q, x = \mu Tx, 0 \leq \mu \leq 1\}.$$

In the following, we shall show that B is bounded. In fact, for any $x \in B, \mu \in [0, 1]$, by (4.8), we have

$$\begin{aligned} x(t) &= \mu(Tx)(t) \leq \int_0^1 K(t,s)a(s)f(s,s^{\alpha-2}x(s)) ds \\ &\leq \int_0^1 K(t,s)a(s)[(\lambda_1 - \varepsilon_2)s^{\alpha-2}x(s) + M_0] ds \\ &= (\lambda_1 - \varepsilon_2)(Lx)(t) + M, \end{aligned} \tag{4.9}$$

where $M = M_0 \sup_{t \in [0,1]} \int_0^1 K(t,s)a(s) ds$. Since $r((\lambda_1 - \varepsilon_2)L) < 1$, so $I - (\lambda_1 - \varepsilon_2)L$ is reversible and

$$(I - (\lambda_1 - \varepsilon_2)L)^{-1} = I + (\lambda_1 - \varepsilon_2)L + ((\lambda_1 - \varepsilon_2)L)^2 + \dots + ((\lambda_1 - \varepsilon_2)L)^n + \dots$$

From $L : P \rightarrow P$ we have $(I - (\lambda_1 - \varepsilon_2)L)^{-1}(P) \subset P$. This together with (4.9) implies that

$$x(t) \leq (I - (\lambda_1 - \varepsilon_2)L)^{-1}M, \quad t \in [0, 1],$$

which shows that B is bounded.

Take $R > \max\{R_0, \sup B\}$, we can easily obtain

$$x \neq \mu Tx, \quad x \in \partial Q_R, \mu \in [0, 1].$$

This together with Lemma 4.1 yields

$$i(T, Q_R, Q) = 1. \tag{4.10}$$

It follows from (4.6) and (4.10) that

$$i(T, Q_R \setminus \overline{Q_r}, Q) = i(T, Q_R, Q) - i(T, Q_r, Q) = 1.$$

Then T has at least one fixed point on $Q_R \setminus \overline{Q_r}$, which implies that BVP (1.2) has at least one positive solution. The proof is completed. \square

Now we consider another case of the problem (1.2). For this purpose, we define a linear operator L_τ for any sufficiently small $0 < \tau < \frac{1}{2}$ as follows:

$$(L_\tau x)(t) = \int_\tau^{1-\tau} K(t,s)a(s)s^{\alpha-2}x(s) ds, \quad t \in [0, 1].$$

Obviously, from Lemma 2.7 we know that $L_\tau : E \rightarrow E$ is a u_0 -bounded and positive operator with $r(L_\tau) > 0$. Moreover L_τ has a positive eigenfunction x_τ corresponding to its first eigenvalue $\lambda_\tau = (r(L_\tau))^{-1}$.

Lemma 4.5 *Suppose that (H₀) and (H₁) hold, there exists an eigenvalue $\tilde{\lambda}_1$ of L such that*

$$\lim_{\tau \rightarrow 0^+} \lambda_\tau = \tilde{\lambda}_1.$$

Proof Take $\tau_n \in (0, \frac{1}{2})$ ($n = 1, 2, \dots$) such that $\tau_1 \geq \tau_2 \geq \dots \geq \tau_n \geq \dots$ and $\tau_n \rightarrow 0$ ($n \rightarrow \infty$). So for any $m > n$ and $x \geq \theta$, we have

$$(L_{\tau_n}x)(t) \leq (L_{\tau_m}x)(t) \leq (Lx)(t), \quad t \in [0, 1],$$

and

$$(L_{\tau_n}^k x)(t) \leq (L_{\tau_m}^k x)(t) \leq (L^k x)(t), \quad t \in [0, 1], k = 2, 3, \dots,$$

where $L_{\tau_n}^k = L(L_{\tau_n}^{k-1})$, $k = 2, 3, \dots$. Consequently, $\|L_{\tau_n}^k\| \leq \|L_{\tau_m}^k\| \leq \|L^k\|$, $k = 1, 2, \dots$. From Gelfand’s formula, we get $\lambda_1 \leq \lambda_{\tau_m} \leq \lambda_{\tau_n}$, where λ_1 is the first eigenvalue of L . Since $\{\lambda_{\tau_n}\}$ is monotonous with lower boundedness λ_1 , let

$$\lim_{n \rightarrow \infty} \lambda_{\tau_n} = \tilde{\lambda}_1.$$

Now we shall show that $\tilde{\lambda}_1$ is an eigenvalue of L . Suppose x_{τ_n} is a positive eigenfunction of L_{τ_n} corresponding to λ_{τ_n} with $\|x_{\tau_n}\| = 1$, $n = 1, 2, \dots$, i.e.,

$$x_{\tau_n}(t) = \lambda_{\tau_n} \int_{\tau_n}^{1-\tau_n} K(t, s)a(s)s^{\alpha-2}x_{\tau_n}(s) ds = \lambda_{\tau_n} L_{\tau_n}x_{\tau_n}(t), \quad t \in [0, 1]. \tag{4.11}$$

It follows from the uniform continuity of the function $K(t, s)$ that $\{x_{\tau_n}\}$ is equicontinuous and uniformly bounded. By the Arzela–Ascoli theorem, $\{x_{\tau_n}\}$ has a subsequence which converges to some \tilde{x}_0 as $n \rightarrow \infty$. Without loss of generality, we may assume $x_{\tau_n} \rightarrow \tilde{x}_0$ as well. Obviously, $\tilde{x}_0 \geq \theta$ and $\|\tilde{x}_0\| = 1$.

By (4.11), we have

$$\tilde{x}_0(t) = \tilde{\lambda}_1 \int_0^1 K(t, s)a(s)s^{\alpha-2}\tilde{x}_0(s) ds, \quad t \in [0, 1],$$

that is, $\tilde{x}_0 = \tilde{\lambda}_1 L\tilde{x}_0$ and $\tilde{\lambda}_1$ is the eigenvalue of the operator L . The proof is completed. \square

Theorem 4.6 *Suppose that the conditions (H₀), (H₁) and (H₂) are satisfied, and*

$$\limsup_{y \rightarrow 0^+} \frac{f(t, y)}{y} < \lambda_1, \quad \text{uniformly on } t \in [0, 1], \tag{4.12}$$

$$\liminf_{y \rightarrow +\infty} \frac{f(t, y)}{y} > \tilde{\lambda}_1, \quad \text{uniformly on } t \in [0, 1], \tag{4.13}$$

where $\lambda_1, \tilde{\lambda}_1$ are the eigenvalues of L and λ_1 is the first eigenvalue of L . Then BVP (1.2) has at least one positive solution.

Proof It follows from (4.12) that there exist $\bar{r} > 0$ and ε_3 ($0 < \varepsilon_3 < \lambda_1$) such that

$$f(t, y) \leq (\lambda_1 - \varepsilon_3)y, \quad 0 \leq y \leq \bar{r}, t \in [0, 1]. \tag{4.14}$$

Now we show that

$$Tx \not\leq x, \quad x \in \partial Q_{\bar{r}}. \tag{4.15}$$

Otherwise, there exists $v_0 \in \partial Q_{\bar{r}}$ such that $v_0 \leq Tv_0$. Then we have

$$0 \leq v_0(t) \leq (Tv_0)(t), \quad \forall t \in [0, 1]. \tag{4.16}$$

By (4.16) and (4.14), we have

$$\begin{aligned} v_0(t) &\leq \int_0^1 K(t, s)a(s)f(s, s^{\alpha-2}v_0(s)) ds \\ &\leq (\lambda_1 - \varepsilon_3) \int_0^1 K(t, s)a(s)s^{\alpha-2}v_0(s) ds = (\lambda_1 - \varepsilon_3)(Lv_0)(t), \end{aligned}$$

i.e.

$$v_0 \leq (\lambda_1 - \varepsilon_3)(Lv_0). \tag{4.17}$$

Acting L on (4.17) $n - 1$ times, we obtain

$$v_0(t) \leq (\lambda_1 - \varepsilon_3)^n (L^n v_0)(t).$$

So we have

$$\|L^n\| \geq \frac{\|L^n v_0\|}{\|v_0\|} \geq \frac{1}{(\lambda_1 - \varepsilon_3)^n}, \quad n = 1, 2, \dots$$

By Gelfand’s formula, we know

$$r(L) = \lim_{n \rightarrow \infty} \|L^n\|^{\frac{1}{n}} \geq \lim_{n \rightarrow \infty} \left(\frac{1}{(\lambda_1 - \varepsilon_3)^n} \right)^{\frac{1}{n}} > \frac{1}{\lambda_1 - \varepsilon_3} > \frac{1}{\lambda_1},$$

which is a contradiction with $r(L) = \lambda_1^{-1}$. So (4.15) holds.

It follows from (4.13) that there exist ε_4 ($0 < \varepsilon_4 < \tilde{\lambda}_1$) and $R_0 > 1$ such that

$$f(t, y) \geq (\tilde{\lambda}_1 + \varepsilon_4)y, \quad y \geq R_0, t \in [0, 1]. \tag{4.18}$$

From the proof of Lemma 4.5, there exists $\tau \in (0, \frac{1}{2})$ such that $\tilde{\lambda}_1 \leq \lambda_\tau = (r(L_\tau))^{-1} < \tilde{\lambda}_1 + \varepsilon_4$. Take $\bar{R} = \max\{R_0, \frac{R_0 H(1)}{\lambda \tau^2}\}$. We shall check that

$$Tx \not\leq x, \quad x \in \partial Q_{\bar{R}}. \tag{4.19}$$

If it is not true, there exists $\phi \in \partial Q_{\bar{R}}$ such that $T\phi \leq \phi$. Then it follows from the construction of Q that

$$\phi(t) \geq \frac{\Lambda t(1-t)}{H(1)} \|\phi\| \geq \frac{\Lambda \tau(1-\tau)}{H(1)} \bar{R} \geq \frac{\Lambda \tau^2}{H(1)} \bar{R} \geq R_0, \quad t \in [\tau, 1-\tau].$$

Thus, by (4.18) we have

$$\begin{aligned} \phi(t) &\geq (T\phi)(t) = \int_0^1 K(t,s)a(s)f(s,s^{\alpha-2}\phi(s)) \, ds \\ &\geq \int_{\tau}^{1-\tau} K(t,s)a(s)f(s,s^{\alpha-2}\phi(s)) \, ds \\ &\geq (\tilde{\lambda}_1 + \varepsilon_4) \int_{\tau}^{1-\tau} K(t,s)a(s)s^{\alpha-2}\phi(s) \, ds \\ &= (\tilde{\lambda}_1 + \varepsilon_4)(L_{\tau}\phi)(t). \end{aligned} \tag{4.20}$$

Notice that $\phi \geq \theta$, by Lemma 2.10, there exists $\mu \geq 0$ such that $\phi = \mu x_{\tau}$, x_{τ} is the positive eigenfunction corresponding to the first eigenvalue λ_{τ} of the operator L_{τ} . If $\mu = 0$, then $\phi(t) \equiv 0$, $t \in [0, 1]$. If $\mu > 0$, by (4.20), we know that $\mu x_{\tau}(t) \geq (\tilde{\lambda}_1 + \varepsilon_4)(L_{\tau}\phi)(t) = \mu(\tilde{\lambda}_1 + \varepsilon_4)(L_{\tau}x_{\tau})(t)$, i.e. $x_{\tau} \geq (\tilde{\lambda}_1 + \varepsilon_4)L_{\tau}x_{\tau}$. Considering $\lambda_{\tau} < \tilde{\lambda}_1 + \varepsilon_4$, we have $x_{\tau} = \lambda_{\tau}L_{\tau}x_{\tau} < (\tilde{\lambda}_1 + \varepsilon_4)L_{\tau}x_{\tau}$, a contradiction. Thus, (4.19) is true. By (4.15), (4.19) and Lemma 4.2, we know that T has a positive fixed point in $Q_{\bar{R}} \setminus \bar{Q}_{\bar{r}}$, which implies that BVP (1.2) has at least one positive solution. The proof is completed. \square

Example 4.7 Consider the following problem:

$$\begin{cases} -D_{0+}^{\frac{3}{2}}x(t) + \frac{1}{5}x(t) = a(t)f(t, x(t)), & 0 < t < 1, \\ x(0) = 0, \quad x(1) = 0. \end{cases} \tag{4.21}$$

Here

$$a(t) = \frac{1}{\sqrt[4]{t} \sqrt[8]{(1-t)^3}}, \quad t \in (0, 1), \quad f(t, y) = \sqrt{y} + \ln(1+y), \quad (t, y) \in [0, 1] \times [0, \infty).$$

Obviously, $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$ is continuous, $a : (0, 1) \rightarrow [0, \infty)$ is continuous and $a(t)$ is singular at $t = 0$ and $t = 1$. Moreover,

$$\begin{aligned} 0 &< \int_0^1 s^{\alpha-1}(1-s)^{\alpha-1}a(s) \, ds = \int_0^1 s^{\frac{3}{2}-1}(1-s)^{\frac{3}{2}-1} \frac{1}{\sqrt[4]{s} \sqrt[8]{(1-s)^3}} \, ds \\ &= \int_0^1 s^{\frac{5}{4}-1}(1-s)^{\frac{9}{8}-1} \, ds = B\left(\frac{5}{4}, \frac{9}{8}\right) < +\infty, \\ 0 &< \int_0^1 s^{\alpha-2}(1-s)^{\alpha-2}a(s) \, ds = \int_0^1 s^{\frac{3}{2}-2}(1-s)^{\frac{3}{2}-2} \frac{1}{\sqrt[4]{s} \sqrt[8]{(1-s)^3}} \, ds \\ &= \int_0^1 s^{\frac{1}{4}-1}(1-s)^{\frac{1}{8}-1} \, ds = B\left(\frac{1}{4}, \frac{1}{8}\right) < +\infty, \end{aligned}$$

where $B(\cdot, \cdot)$ denotes a beta function.

Noticing that $\Gamma(\cdot)$ is strictly increasing on $[2, \infty)$, so for any $y \in [0, \infty)$ we have

$$\begin{aligned} h(y) &= \frac{\alpha - 2}{\Gamma(\alpha - 1)} + \sum_{k=1}^{+\infty} \frac{y^k}{\Gamma((k + 1)\alpha - 2)} = -\frac{1}{2\sqrt{\pi}} + \sum_{k=1}^{+\infty} \frac{y^k}{\Gamma(\frac{3}{2}k - \frac{1}{2})} \\ &= -\frac{1}{2\sqrt{\pi}} + y + \sum_{k=2}^{+\infty} \frac{y^k}{\Gamma(\frac{3}{2}k - \frac{1}{2})} \leq -\frac{1}{2\sqrt{\pi}} + y + \sum_{k=2}^{+\infty} \frac{y^k}{\Gamma(k)} \\ &= -\frac{1}{2\sqrt{\pi}} + y \left(1 + \sum_{k=2}^{+\infty} \frac{y^k}{\Gamma(k)} \right) = -\frac{1}{2\sqrt{\pi}} + ye^y. \end{aligned} \tag{4.22}$$

By direct calculation, we have

$$\frac{1}{2\sqrt{\pi}} \approx 0.282095, \quad \frac{1}{5}e^{\frac{1}{5}} \approx 0.244281,$$

(4.22) implies that $h(\frac{1}{5}) < 0$, combining with the monotonicity of $h(y)$, we can obtain $\frac{1}{5} < \tilde{b}$ (\tilde{b} is unique zero point of function h , i.e., $h(\tilde{b}) = 0$).

On the other hand, it is obvious that

$$\begin{aligned} \liminf_{y \rightarrow 0^+} \frac{f(t, y)}{y} &= \liminf_{y \rightarrow 0^+} \frac{\sqrt{y} + \ln(1 + y)}{y} = +\infty, \\ \limsup_{y \rightarrow +\infty} \frac{f(t, y)}{y} &= \limsup_{y \rightarrow +\infty} \frac{\sqrt{y} + \ln(1 + y)}{y} = 0, \end{aligned}$$

uniformly on $t \in [0, 1]$, which implies that

$$\limsup_{y \rightarrow +\infty} \frac{f(t, y)}{y} < \lambda_1 < \liminf_{y \rightarrow 0^+} \frac{f(t, y)}{y}.$$

Therefore, all conditions of Theorem 4.4 are satisfied. Thus Theorem 4.4 ensures that BVP (4.21) has at least one positive solution.

Remark 4.8 In BVP (4.21), note that $a(t)$ is singular at $t = 0$ and $t = 1$, that is to say, the nonlinearity has singularity at $t = 0$ and $t = 1$. This is in essence different from a Dirichlet-type BVP [4, 10, 13].

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Competing interests

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Authors' contributions

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