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Stability of delayed HIV dynamics models with two latent reservoirs and immune impairment

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Abstract

The purpose of this paper is to investigate the qualitative behavior of HIV dynamics models with immune impairment. The HIV particles infect both CD4⁺ T cells and macrophages. Both latently and actively infected cells are incorporated into the models. The models consider multiple discrete or distributed delays to characterize the time between an HIV contact of an uninfected target cell and the creation of mature HIV. The existence and global stability of the steady states are determined by the basic reproduction number. The global stability analysis of the steady states is performed using Lyapunov method. We solve the system of delay differential equations numerically to support the theoretical results.

Keywords: HIV infection; Immune impairment; Global stability; Time delay

1 Introduction

In order to understand the Human Immunodeficiency Virus (HIV) dynamics within-host and the drug therapy strategies, many mathematical models have been constructed and developed (see [1–40]). Some of these models assume that HIV infects one category of target cells, that is, CD4⁺ T cells [1, 29, 40]. Among these models, the basic model which has been developed by Nowak and Bangham [1] is considered the most popular. The model is a three-dimensional system of ODEs which characterize the interaction between HIV (v), uninfected CD4⁺ T cells (x), and infected CD4⁺ T cells (u). Other HIV dynamics models assume that HIV has categories of target cells, CD4⁺ T cells and macrophages [30–40]. The basic model describing the HIV interaction with two categories of target cells is presented in [30] and [32] as:

$$\dot{x}_1(t) = \lambda_1 - d_1x_1(t) - \beta_1x_1(t)v(t), \quad (1)$$

$$\dot{u}_1(t) = \beta_1x_1(t)v(t) - \mu_1u_1(t), \quad (2)$$

$$\dot{x}_2(t) = \lambda_2 - d_2x_2(t) - \beta_2x_2(t)v(t), \quad (3)$$

$$\dot{u}_2(t) = \beta_2x_2(t)v(t) - \mu_2u_2(t), \quad (4)$$

$$\dot{v}(t) = k_1u_1(t) + k_2u_2(t) - rv(t). \quad (5)$$

The variables describe the concentrations of x_i , the uninfected and infected cells and free HIV, respectively; $i = 1$ and $i = 2$ represent the $CD4^+$ T cells and macrophages, respectively; λ_i represents the generation rate of the uninfected cells; d_i are the death rate constants; and β_i are the infection rate constants. Equations (2) and (4) represent the population dynamics of the activated infected cells and show that they die with the same constant rate μ_i . The HIV particles are generated from infected $CD4^+$ T cells and infected macrophages at rates $k_1 u_1$ and $k_2 u_2$, respectively. The HIV particles are cleared at rate ν .

A lot of considerations have been added that aim to get the best representation of the HIV infection. Most notable are latent HIV reservoirs which serve as a major barrier in curing HIV infection. Despite the fact that the antiretroviral therapy significantly limits the level of HIV in the blood, there is still a low viral load due to ongoing reactivation of latent infected cells reservoirs. Variant models have been developed to study the dynamics of HIV in the presence of latent reservoirs (see, e.g., [23–34]).

Cytotoxic T Lymphocyte (CTL) cells play a prominent role in achieving the best representation of the HIV dynamics. CTL cells attack the HIV infected cells and hence try to eliminate or control the infection. The first mathematical model describing the interaction between CTL immune response and viral infection had been presented by Nowak and Bangham [1], since then many mathematical models have been presented to study the effect of CTL immune response on virus dynamics (see, e.g., [41–44]). However, it has been reported in [45] that during the infection, HIV causes an impairment in the CTL job. Virus dynamics models with CTL immune impairment have been studied in many papers (see, e.g., [45–52]). All the HIV dynamics models with CTL immune impairment presented in the literature consider one category of target cells, $CD4^+$ T cells.

In the present paper we investigate the global stability of an HIV dynamics model with CTL immune impairment and two categories of target cells, $CD4^+$ T cells and macrophages. The importance of considering such a model is due to the observation of Perleson et al. that after the rapid first phase of decay during the initial 1–2 weeks of an antiretroviral treatment, plasma virus levels declined at a considerably slower rate [31]. This second phase of viral decay was attributed to the turnover of a longer-lived virus reservoir of infected cell population. Therefore, the two target cells model is more accurate than the one target cell model, and then more accurate drug efficacy is determined when using the model with two classes of target cells. Moreover, a better understanding of the mechanisms behind this immune impairment in HIV infection may help to devise better therapeutic regimens and to identify patients more responsive to certain drugs [53]. We consider both latently and actively infected cells. We incorporate multiple discrete or distributed time delays to describe the time between the HIV contacts of target cells and the emission of new mature HIV particles. We study global stability of the two steady states of the model using Lyapunov method. The theoretical results are supported by numerical simulations.

2 HIV model with discrete delays

We study the following HIV model:

$$\dot{x}_1(t) = \lambda_1 - d_1 x_1(t) - \beta_1 x_1(t)v(t), \quad (6)$$

$$\dot{y}_1(t) = \rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1(t - \tau_1)v(t - \tau_1) - a y_1(t) - \delta y_1(t), \quad (7)$$

$$\dot{u}_1(t) = (1 - \rho_1)\beta_1 e^{-\alpha_2 \tau_2} x_1(t - \tau_2)v(t - \tau_2) + \delta y_1(t) - pu_1(t)z(t) - \mu u_1(t), \tag{8}$$

$$\dot{x}_2(t) = \lambda_2 - d_2 x_2(t) - \beta_2 x_2(t)v(t), \tag{9}$$

$$\dot{y}_2(t) = \rho_2 \beta_2 e^{-\alpha_3 \tau_3} x_2(t - \tau_3)v(t - \tau_3) - ay_2(t) - \delta y_2(t), \tag{10}$$

$$\dot{u}_2(t) = (1 - \rho_2)\beta_2 e^{-\alpha_4 \tau_4} x_2(t - \tau_4)v(t - \tau_4) + \delta y_2(t) - pu_2(t)z(t) - \mu u_2(t), \tag{11}$$

$$\dot{v}(t) = ke^{-\alpha_5 \tau_5} (u_1(t - \tau_5) + u_2(t - \tau_5)) - rv(t), \tag{12}$$

$$\dot{z}(t) = c(u_1(t) + u_2(t)) - m(u_1(t) + u_2(t))z(t) - bz(t). \tag{13}$$

Here u_i , y_i and z are the concentrations of the latent infected, actively infected and CTL cells, respectively. The fractions ρ_i and $1 - \rho_i$ with $0 < \rho_i < 1$ where $i = 1, 2$ are the probabilities that upon infection, uninfected cell will become either latently or actively infected. Equations (7) and (10) describe the population dynamics of the latent infected CD4⁺ T and macrophages cells and shows that they die with the same constant rate a and become active with constant rate δy_i . The actively infected cells are removed by the CTL at rate $pu_i z$. The CTLs are proliferated at the rate of $c(u_1 + u_2)$ and decay at rate of bz . The term $m(u_1 + u_2)z$ represents the immune impairment rate. Here τ_1 and τ_3 are the times between HIV entry of CD4⁺ T cells and macrophages, respectively, to become latent infected; τ_2 and τ_4 are the times between HIV entry of CD4⁺ T cells and macrophages, respectively, to produce immature HIV. The immature HIVs need time τ_5 to become mature. The factors $e^{-\alpha_j \tau_j}$, $j = 1, \dots, 5$, represent the probability of surviving to the age of τ_i , where α_j are positive constants.

To ensure the uniqueness of the solution of system (6)–(13), we take the following initial conditions [54]:

$$\begin{aligned} x_1(\eta) &= \omega_1(\eta), & y_1(\eta) &= \omega_2(\eta), & u_1(\eta) &= \omega_3(\eta), \\ x_2(\eta) &= \omega_4(\eta), & y_2(\eta) &= \omega_5(\eta), & u_2(\eta) &= \omega_6(\eta), \\ v(\eta) &= \omega_7(\eta), & z(\eta) &= \omega_8(\eta), & \omega_i(\eta) &\geq 0, \quad \eta \in [-\kappa, 0], i = 1, \dots, 8, \end{aligned} \tag{14}$$

where $\kappa = \max\{\tau_1, \tau_2, \tau_3, \tau_4, \tau_5\}$, $(\omega_1(\eta), \dots, \omega_8(\eta)) \in C([-\kappa, 0], \mathbb{R}_{\geq 0}^8)$, C is the Banach space of continuous functions mapping the interval $[-\kappa, 0]$ into $\mathbb{R}_{\geq 0}$.

2.1 Nonnegativity and boundedness

Proposition 1 *The solutions of system (6)–(13) are nonnegative and ultimately bounded.*

Proof From Eqs. (6)–(13) of the system, we have

$$\begin{aligned} x_i(t) &\geq \omega_{3i-2}(0)e^{-\int_0^t (d_i + \beta_i v(s)) ds}, \quad i = 1, 2, \\ y_i(t) &\geq \omega_{3i-1}(0)e^{-(a+\delta)t}, \quad i = 1, 2, \\ u_i(t) &\geq \omega_{3i}(0)e^{-\int_0^t (\mu + pz(s)) ds}, \quad i = 1, 2, \\ v(t) &\geq \omega_7(0)e^{-rt}, \\ z(t) &\geq \omega_8(0)e^{-\int_0^t (m(u_1(s) + u_2(s)) + b) ds}, \end{aligned}$$

therefore $x_i(t), y_i(t), u_i(t), v(t), z(t) \geq 0$ for all $t \geq 0$ and $i = 1, 2$.

From Eqs. (6) and (9), we have $\sup_{t \rightarrow \infty} x_i(t) \leq \frac{\lambda_i}{d_i}$. Let us define

$$L_1(t) = \rho_1 e^{-\alpha_1 \tau_1} x_1(t - \tau_1) + (1 - \rho_1) e^{-\alpha_2 \tau_2} x_1(t - \tau_2) + \rho_2 e^{-\alpha_3 \tau_3} x_2(t - \tau_3) + (1 - \rho_2) e^{-\alpha_4 \tau_4} x_2(t - \tau_4) + y_1(t) + u_1(t) + y_2(t) + u_2(t) + \frac{\mu}{2c} z(t).$$

Then

$$\begin{aligned} \dot{L}_1(t) &= \rho_1 e^{-\alpha_1 \tau_1} [\lambda_1 - d_1 x_1(t - \tau_1) - \beta_1 x_1(t - \tau_1) v(t - \tau_1)] \\ &\quad + (1 - \rho_1) e^{-\alpha_2 \tau_2} [\lambda_1 - d_1 x_1(t - \tau_2) - \beta_1 x_1(t - \tau_2) v(t - \tau_2)] \\ &\quad + \rho_2 e^{-\alpha_3 \tau_3} [\lambda_2 - d_2 x_2(t - \tau_3) - \beta_2 x_2(t - \tau_3) v(t - \tau_3)] \\ &\quad + (1 - \rho_2) e^{-\alpha_4 \tau_4} [\lambda_2 - d_2 x_2(t - \tau_4) - \beta_2 x_2(t - \tau_4) v(t - \tau_4)] \\ &\quad + \rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1(t - \tau_1) v(t - \tau_1) - a y_1(t) - \delta y_1(t) \\ &\quad + (1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2} x_1(t - \tau_2) v(t - \tau_2) + \delta y_1(t) - p u_1(t) z(t) - \mu u_1(t) \\ &\quad + \rho_2 \beta_2 e^{-\alpha_3 \tau_3} x_2(t - \tau_3) v(t - \tau_3) - a y_2(t) - \delta y_2(t) \\ &\quad + (1 - \rho_2) \beta_2 e^{-\alpha_4 \tau_4} x_2(t - \tau_4) v(t - \tau_4) + \delta y_2(t) - p u_2(t) z(t) - \mu u_2(t) \\ &\quad + \frac{\mu}{2} (u_1(t) + u_2(t)) - \frac{\mu m}{2c} (u_1(t) + u_2(t)) z(t) - \frac{\mu b}{2c} z(t) \\ &= \rho_1 e^{-\alpha_1 \tau_1} \lambda_1 + (1 - \rho_1) e^{-\alpha_2 \tau_2} \lambda_1 + \rho_2 e^{-\alpha_3 \tau_3} \lambda_2 + (1 - \rho_2) e^{-\alpha_4 \tau_4} \lambda_2 \\ &\quad - \left(p + \frac{\mu m}{2c} \right) (u_1(t) + u_2(t)) z(t) - \rho_1 e^{-\alpha_1 \tau_1} d_1 x_1(t - \tau_1) \\ &\quad - (1 - \rho_1) e^{-\alpha_2 \tau_2} d_1 x_1(t - \tau_2) \\ &\quad - \rho_2 e^{-\alpha_3 \tau_3} d_2 x_2(t - \tau_3) - (1 - \rho_2) e^{-\alpha_4 \tau_4} d_2 x_2(t - \tau_4) - a y_1(t) - a y_2(t) \\ &\quad - \frac{\mu}{2} u_1(t) - \frac{\mu}{2} u_2(t) - \frac{\mu b}{2c} z(t) \\ &\leq \lambda_1 + \lambda_2 - \delta_1 L_1(t), \end{aligned}$$

$\delta_1 = \min\{d_1, d_2, a, \frac{\mu}{2}, b\}$. Hence $\limsup_{t \rightarrow \infty} L_1(t) \leq M_1$, $\limsup_{t \rightarrow \infty} y_i(t) \leq M_1$, $\limsup_{t \rightarrow \infty} u_i(t) \leq M_1$ and $\limsup_{t \rightarrow \infty} z(t) \leq M_2$, for all $t \geq 0$ where $i = 1, 2$, where, $M_1 = \frac{\lambda_1 + \lambda_2}{\delta_1}$ and $M_2 = \frac{2c}{\mu}$. From Eq. (12) we have

$$\begin{aligned} \dot{v}(t) &= k e^{-\alpha_5 \tau_5} (u_1(t - \tau_5) + u_2(t - \tau_5)) - r v(t) \\ &\leq 2k M_1 - r v(t), \end{aligned}$$

which yields $\limsup_{t \rightarrow \infty} v(t) \leq M_3$ where $M_3 = \frac{2k M_1}{r}$. □

2.2 Steady states

The basic reproduction number of system (6)–(13) is given as:

$$R_0 = \frac{\delta k}{\mu r (a + \delta)} (\gamma_1 \beta_1 x_1^0 + \gamma_2 \beta_2 x_2^0),$$

where

$$\gamma_1 = \rho_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} + \frac{(a + \delta)}{\delta} (1 - \rho_1) e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5},$$

$$\gamma_2 = \rho_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} + \frac{(a + \delta)}{\delta} (1 - \rho_2) e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5},$$

$$x_1^0 = \frac{\lambda_1}{d_1}, \quad x_2^0 = \frac{\lambda_2}{d_2}.$$

Lemma 1 For system (6)–(13) (i) if $R_0 \leq 1$, then there exists an infection-free steady state E_0 , and (ii) if $R_0 > 1$, then there exist two steady states, E_0 and a chronic steady state E^* .

Proof The steady states of model (6)–(13) satisfy

$$\lambda_1 - d_1 x_1 - \beta_1 x_1 v = 0, \tag{15}$$

$$\rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1 v - a y_1 - \delta y_1 = 0, \tag{16}$$

$$(1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2} x_1 v + \delta y_1 - p u_1 z - \mu u_1 = 0, \tag{17}$$

$$\lambda_2 - d_2 x_2 - \beta_2 x_2 v = 0, \tag{18}$$

$$\rho_2 \beta_2 e^{-\alpha_3 \tau_3} x_2 v - a y_2 - \delta y_2 = 0, \tag{19}$$

$$(1 - \rho_2) \beta_2 e^{-\alpha_4 \tau_4} x_2 v + \delta y_2 - p u_2 z - \mu u_2 = 0, \tag{20}$$

$$k e^{-\alpha_5 \tau_5} (u_1 + u_2) - r v = 0, \tag{21}$$

$$c(u_1 + u_2) - m(u_1 + u_2)z - bz = 0. \tag{22}$$

One solution of Eqs. (15)–(22) yields an infection-free steady state $E_0 = (x_1^0, 0, 0, x_2^0, 0, 0, 0, 0)$. Moreover, we have

$$A_1 v^3 + B_1 v^2 + C_1 v + D_1 = 0,$$

where

$$A_1 = \beta_1 \beta_2 (\mu m + pc) r^2,$$

$$B_1 = \beta_1 \beta_2 \mu r b k e^{-\alpha_5 \tau_5} + (\beta_1 d_2 + \beta_2 d_1) (\mu m + pc) r^2 - \frac{\beta_1 \beta_2 m r \delta k}{a + \delta} (\lambda_1 \gamma_1 + \lambda_2 \gamma_2),$$

$$C_1 = \mu r b k e^{-\alpha_5 \tau_5} (\beta_1 d_2 + \beta_2 d_1) + \mu m r^2 d_1 d_2 (1 - R_0) + p c r^2 d_1 d_2 - \frac{\beta_1 \beta_2 b k^2 \delta e^{-\alpha_5 \tau_5}}{a + \delta} (\lambda_1 \gamma_1 + \lambda_2 \gamma_2),$$

$$D_1 = \mu r b k d_1 d_2 e^{-\alpha_5 \tau_5} (1 - R_0).$$

Let

$$\Psi_1(v) = A_1 v^3 + B_1 v^2 + C_1 v + D_1 = 0.$$

If $R_0 > 1$, then $\Psi_1(0) = D_1 < 0$; moreover, $\lim_{v \rightarrow \infty} \Psi_1(v) = \infty$, which implies that there exists $v^* > 0$ such that $\Psi_1(v^*) = 0$. Thus a chronic steady state $E^* = (x_1^*, y_1^*, u_1^*, x_2^*, y_2^*, u_2^*, v^*, z^*)$

exists when $R_0 > 1$, where

$$\begin{aligned} x_i^* &= \frac{\lambda_i}{d_i + \beta_i v^*}, \quad i = 1, 2, \\ y_1^* &= \frac{\rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1^* v^*}{a + \delta}, \quad y_2^* = \frac{\rho_2 \beta_2 e^{-\alpha_3 \tau_3} x_2^* v^*}{a + \delta}, \\ u_i^* &= \frac{\gamma_i \beta_i x_i^* v^* \delta}{e^{-\alpha_5 \tau_5} (\mu + pz^*)(a + \delta)}, \quad \sum_{i=1}^2 u_i^* = \frac{rv^*}{e^{-\alpha_5 \tau_5} k}, \\ z^* &= \frac{crv^*}{bke^{-\alpha_5 \tau_5} + mrv^*}. \end{aligned}$$

□

2.3 Global stability

We use Lyapunov method to investigate the global stability of the steady states. Let $f(\eta) = \eta - 1 - \ln(\eta)$ and $(x_1, y_1, u_1, x_2, y_2, u_2, v, z) = (x_1(t), y_1(t), u_1(t), x_2(t), y_2(t), u_2(t), v(t), z(t))$.

Theorem 1 *If $R_0 \leq 1$, then E_0 for system (6)–(13) is globally asymptotically stable.*

Proof We consider $W_1(x_1, y_1, u_1, x_2, y_2, u_2, v, z)$ as

$$\begin{aligned} W_1 &= \sum_{i=1}^2 \left[\gamma_i x_i^0 f\left(\frac{x_i}{x_i^0}\right) + e^{-\alpha_5 \tau_5} y_i + \frac{a + \delta}{\delta} e^{-\alpha_5 \tau_5} u_i \right] + \frac{\mu(a + \delta)}{\delta k} v + \frac{p(a + \delta)}{2\delta c} e^{-\alpha_5 \tau_5} z^2 \\ &\quad + \rho_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} \int_0^{\tau_1} \beta_1 x_1(t - \vartheta) v(t - \vartheta) d\vartheta \\ &\quad + \frac{(a + \delta)}{\delta} (1 - \rho_1) e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} \int_0^{\tau_2} \beta_1 x_1(t - \vartheta) v(t - \vartheta) d\vartheta \\ &\quad + \rho_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} \int_0^{\tau_3} \beta_2 x_2(t - \vartheta) v(t - \vartheta) d\vartheta \\ &\quad + \frac{(a + \delta)}{\delta} (1 - \rho_2) e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5} \int_0^{\tau_4} \beta_2 x_2(t - \vartheta) v(t - \vartheta) d\vartheta \\ &\quad + \frac{\mu(a + \delta)}{\delta} e^{-\alpha_5 \tau_5} \int_0^{\tau_5} [u_1(t - \vartheta) + u_2(t - \vartheta)] d\vartheta. \end{aligned}$$

It is seen that $W_1 > 0$ for all $x_1, y_1, u_1, x_2, y_2, u_2, v, z > 0$, and $W_1(x_1^0, 0, 0, x_2^0, 0, 0, 0, 0, 0) = 0$. Calculating \dot{W}_1 along system (6)–(13), we obtain

$$\begin{aligned} \dot{W}_1 &= \sum_{i=1}^2 \left[\gamma_i \left(1 - \frac{x_i^0}{x_i}\right) \dot{x}_i + e^{-\alpha_5 \tau_5} \dot{y}_i + \frac{a + \delta}{\delta} e^{-\alpha_5 \tau_5} \dot{u}_i \right] \\ &\quad + \frac{\mu(a + \delta)}{\delta k} \dot{v} + \frac{p(a + \delta)}{\delta c} e^{-\alpha_5 \tau_5} z \dot{z} \\ &\quad + \rho_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} \beta_1 [x_1 v - x_1(t - \tau_1) v(t - \tau_1)] \\ &\quad + \frac{(a + \delta)(1 - \rho_1)}{\delta} e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} \beta_1 [x_1 v - x_1(t - \tau_2) v(t - \tau_2)] \\ &\quad + \rho_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} \beta_2 [x_2 v - x_2(t - \tau_3) v(t - \tau_3)] \\ &\quad + \frac{(a + \delta)(1 - \rho_2)}{\delta} e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5} \beta_2 [x_2 v - x_2(t - \tau_4) v(t - \tau_4)] \end{aligned}$$

$$+ \frac{\mu(a + \delta)}{\delta} e^{-\alpha_5 \tau_5} [u_1 + u_2 - u_1(t - \tau_5) - u_2(t - \tau_5)]. \tag{23}$$

Equation (23) can be simplified as

$$\begin{aligned} \dot{W}_1 = & \sum_{i=1}^2 \left[\gamma_i \left(1 - \frac{x_i^0}{x_i} \right) (\lambda_i - d_i x_i - \beta_i x_i \nu) \right] - \frac{\mu(a + \delta)}{\delta k} r \nu \\ & + \frac{p(a + \delta)}{\delta c} e^{-\alpha_5 \tau_5} z [-m(u_1 + u_2)z - bz] + \gamma_1 \beta_1 x_1 \nu + \gamma_2 \beta_2 x_2 \nu. \end{aligned}$$

Since $\lambda_i = d_i x_i^0$,

$$\begin{aligned} \dot{W}_1 = & \sum_{i=1}^2 \left[\gamma_i \left(1 - \frac{x_i^0}{x_i} \right) (d_i x_i^0 - d_i x_i) - \gamma_i \beta_i x_i \nu \left(1 - \frac{x_i^0}{x_i} \right) + \gamma_i \beta_i x_i \nu \right] - \frac{\mu(a + \delta)}{\delta k} r \nu \\ & - \frac{pm(a + \delta)}{\delta c} e^{-\alpha_5 \tau_5} (u_1 + u_2) z^2 - \frac{pb(a + \delta)}{\delta c} e^{-\alpha_5 \tau_5} z^2 \\ = & \sum_{i=1}^2 \frac{-d_i \gamma_i (x_i - x_i^0)^2}{x_i} + \frac{\mu r (a + \delta)}{\delta k} (R_0 - 1) \nu \\ & - \frac{pm(a + \delta) e^{-\alpha_5 \tau_5}}{\delta c} \sum_{i=1}^2 u_i z^2 - \frac{pb(a + \delta) e^{-\alpha_5 \tau_5}}{\delta c} z^2. \end{aligned}$$

It follows that $\dot{W}_1 \leq 0$ if $R_0 \leq 1$. Therefore, $\dot{W}_1 = 0$ implies that $x_i = x_i^0, \nu = 0$ and $z = 0$. One can easily show that the largest invariant set $\Omega_0 \subseteq \Omega = \{(x_1, y_1, u_1, x_2, y_2, u_2, \nu, z) | \dot{W}_1 = 0\}$ is the singleton $\{E_0\}$. By LaSalle’s invariance principle, E_0 is globally asymptotically stable. \square

Theorem 2 *If $R_0 > 1$, then E^* for system (6)–(13) is globally asymptotically stable.*

Proof Consider $W_2(x_1, y_1, u_1, x_2, y_2, u_2, \nu, z)$ as

$$\begin{aligned} W_2 = & \sum_{i=1}^2 \left[\gamma_i x_i^* f\left(\frac{x_i}{x_i^*}\right) + e^{-\alpha_5 \tau_5} y_i^* f\left(\frac{y_i}{y_i^*}\right) + \frac{(a + \delta)}{\delta} e^{-\alpha_5 \tau_5} u_i^* f\left(\frac{u_i}{u_i^*}\right) \right] \\ & + \frac{(a + \delta)(\mu + pz^*)}{\delta k} \nu^* f\left(\frac{\nu}{\nu^*}\right) \\ & + \frac{p(a + \delta)}{2\delta(c - mz^*)} e^{-\alpha_5 \tau_5} (z - z^*)^2 + \rho_1 \beta_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} x_1^* \nu^* \int_0^{\tau_1} f\left(\frac{x_1(t - \vartheta)\nu(t - \vartheta)}{x_1^* \nu^*}\right) d\vartheta \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} x_1^* \nu^* \int_0^{\tau_2} f\left(\frac{x_1(t - \vartheta)\nu(t - \vartheta)}{x_1^* \nu^*}\right) d\vartheta \\ & + \rho_2 \beta_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} x_2^* \nu^* \int_0^{\tau_3} f\left(\frac{x_2(t - \vartheta)\nu(t - \vartheta)}{x_2^* \nu^*}\right) d\vartheta \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_2) \beta_2 e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5} x_2^* \nu^* \int_0^{\tau_4} f\left(\frac{x_2(t - \vartheta)\nu(t - \vartheta)}{x_2^* \nu^*}\right) d\vartheta \\ & + \frac{(a + \delta)(\mu + pz^*)}{\delta} e^{-\alpha_5 \tau_5} \int_0^{\tau_5} \left[u_1^* f\left(\frac{u_1(t - \vartheta)}{u_1^*}\right) + u_2^* f\left(\frac{u_2(t - \vartheta)}{u_2^*}\right) \right] d\vartheta. \end{aligned}$$

Calculating \dot{W}_2 along system (6)–(13), we obtain

$$\begin{aligned} \dot{W}_2 = & \sum_{i=1}^2 \left[\gamma_i \left(1 - \frac{x_i^*}{x_i} \right) \dot{x}_i + e^{-\alpha_5 \tau_5} \left(1 - \frac{y_i^*}{y_i} \right) \dot{y}_i + \frac{(a + \delta)}{\delta} e^{-\alpha_5 \tau_5} \left(1 - \frac{u_i^*}{u_i} \right) \dot{u}_i \right] \\ & + \frac{(a + \delta)(\mu + pz^*)}{\delta k} \left(1 - \frac{v^*}{v} \right) \dot{v} \\ & + \frac{p(a + \delta)}{\delta(c - mz^*)} e^{-\alpha_5 \tau_5} (z - z^*) \dot{z} \\ & + \rho_1 \beta_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} x_1^* v^* \left[\frac{x_1 v}{x_1^* v^*} - \frac{x_1(t - \tau_1)v(t - \tau_1)}{x_1^* v^*} + \ln \frac{x_1(t - \tau_1)v(t - \tau_1)}{x_1 v} \right] \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} x_1^* v^* \\ & \times \left[\frac{x_1 v}{x_1^* v^*} - \frac{x_1(t - \tau_2)v(t - \tau_2)}{x_1^* v^*} + \ln \frac{x_1(t - \tau_2)v(t - \tau_2)}{x_1 v} \right] \\ & + \rho_2 \beta_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} x_2^* v^* \left[\frac{x_2 v}{x_2^* v^*} - \frac{x_2(t - \tau_3)v(t - \tau_3)}{x_2^* v^*} + \ln \frac{x_2(t - \tau_3)v(t - \tau_3)}{x_2 v} \right] \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_2) \beta_2 e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5} x_2^* v^* \\ & \times \left[\frac{x_2 v}{x_2^* v^*} - \frac{x_2(t - \tau_4)v(t - \tau_4)}{x_2^* v^*} + \ln \frac{x_2(t - \tau_4)v(t - \tau_4)}{x_2 v} \right] \\ & + \frac{(a + \delta)(\mu + pz^*)}{\delta} e^{-\alpha_5 \tau_5} \left[u_1^* \left(\frac{u_1}{u_1^*} - \frac{u_1(t - \tau_5)}{u_1^*} + \ln \frac{u_1(t - \tau_5)}{u_1} \right) \right. \\ & \left. + u_2^* \left(\frac{u_2}{u_2^*} - \frac{u_2(t - \tau_5)}{u_2^*} + \ln \frac{u_2(t - \tau_5)}{u_2} \right) \right]. \end{aligned}$$

Using the following chronic steady state conditions:

$$\begin{aligned} \lambda_i &= d_i x_i^* + \beta_i x_i^* v^*, & (a + \delta) y_1^* &= \rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1^* v^*, \\ \lambda_i &= d_i x_i^* + \beta_i x_i^* v^*, & (a + \delta) y_1^* &= \rho_1 \beta_1 e^{-\alpha_1 \tau_1} x_1^* v^*, \\ (a + \delta) y_2^* &= \rho_2 \beta_2 e^{-\alpha_3 \tau_3} x_2^* v^*, & (a + \delta)(\mu + pz^*) e^{-\alpha_5 \tau_5} u_i^* &= \delta \gamma_i \beta_i x_i^* v^*, \\ rv^* &= ke^{-\alpha_5 \tau_5} (u_1^* + u_2^*), & c(u_1^* + u_2^*) &= m(u_1^* + u_2^*)z^* + bz^*, \end{aligned}$$

we can simplify:

$$\begin{aligned} & \frac{p}{(c - mz^*)} (z - z^*) \dot{z} \\ &= \frac{p(z - z^*)}{(c - mz^*)} (c(u_1 + u_2) - m(u_1 + u_2)z - bz) \\ &= \frac{p(z - z^*)}{(c - mz^*)} (c(u_1 + u_2) - m(u_1 + u_2)z - bz - c(u_1^* + u_2^*) + m(u_1^* + u_2^*)z^* + bz^*) \\ &= -\frac{pb}{(c - mz^*)} (z - z^*)^2 - \frac{pm(u_1 + u_2)}{(c - mz^*)} (z - z^*)^2 \\ & \quad + p(u_1 - u_1^*)(z - z^*) + p(u_2 - u_2^*)(z - z^*) \end{aligned}$$

$$= p \left[\sum_{i=1}^2 u_i^* z^* - \sum_{i=1}^2 u_i^* z - \sum_{i=1}^2 u_i z^* + \sum_{i=1}^2 u_i z - \frac{[b + m(u_1 + u_2)]}{(c - mz^*)} (z - z^*)^2 \right].$$

Due to steady state conditions, we can rewrite

$$\begin{aligned} \dot{W}_2 = & \sum_{i=1}^2 \frac{-\gamma_i d_i (x_i - x_i^*)^2}{x_i} + \rho_1 \beta_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} x_1^* v^* \left[4 - \frac{x_1^*}{x_1} - \frac{y_1^* x_1 (t - \tau_1) v (t - \tau_1)}{y_1 (t) x_1^* v^*} \right. \\ & \left. - \frac{y_1 u_1^*}{y_1^* u_1} - \frac{u_1 (t - \tau_5) v^*}{u_1^* v} + \ln \frac{x_1 (t - \tau_1) v (t - \tau_1)}{x_1 v} + \ln \frac{u_1 (t - \tau_5)}{u_1} \right] \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} x_1^* v^* \left[3 - \frac{x_1^*}{x_1} - \frac{u_1 (t - \tau_5) v^*}{u_1^* v} \right. \\ & \left. - \frac{u_1^* x_1 (t - \tau_2) v (t - \tau_2)}{u_1 x_1^* v^*} + \ln \frac{x_1 (t - \tau_2) v (t - \tau_2)}{x_1 v} + \ln \frac{u_1 (t - \tau_5)}{u_1} \right] \\ & + \rho_2 \beta_2 e^{-\alpha_3 \tau_3 - \alpha_5 \tau_5} x_2^* v^* \left[4 - \frac{x_2^*}{x_2} - \frac{y_2^* x_2 (t - \tau_3) v (t - \tau_3)}{y_2 x_2^* v^*} - \frac{y_2 u_2^*}{y_2^* u_2} - \frac{u_2 (t - \tau_5) v^*}{u_2^* v} \right. \\ & \left. + \ln \frac{x_2 (t - \tau_3) v (t - \tau_3)}{x_2 v} + \ln \frac{u_2 (t - \tau_5)}{u_2} \right] \\ & + \frac{(a + \delta)}{\delta} (1 - \rho_2) \beta_2 e^{-\alpha_4 \tau_4 - \alpha_5 \tau_5} x_2^* v^* \left[3 - \frac{x_2^*}{x_2} - \frac{u_2 (t - \tau_5) v^*}{u_2^* v} - \frac{u_2^* x_2 (t - \tau_4) v (t - \tau_4)}{u_2 x_2^* v^*} \right. \\ & \left. + \ln \frac{u_2 (t - \tau_5)}{u_2} + \ln \frac{x_2 (t - \tau_4) v (t - \tau_4)}{x_2 v} \right] \\ & - \frac{(a + \delta)}{\delta} e^{-\alpha_5 \tau_5} \frac{p[b + m(u_1 + u_2)]}{(c - mz^*)} (z - z^*)^2. \end{aligned}$$

Consider the following relations:

$$\begin{aligned} & \ln \left(\frac{x_1 (t - \tau_1) v (t - \tau_1)}{x_1 v} \right) + \ln \left(\frac{u_1 (t - \tau_5)}{u_1} \right) \\ & = \ln \left(\frac{x_1^*}{x_1} \right) + \ln \left(\frac{y_1^* x_1 (t - \tau_1) v (t - \tau_1)}{y_1 x_1^* v^*} \right) + \ln \left(\frac{y_1 u_1^*}{y_1^* u_1} \right) + \ln \left(\frac{u_1 (t - \tau_5) v^*}{u_1^* v} \right), \\ & \ln \left(\frac{x_1 (t - \tau_2) v (t - \tau_2)}{x_1 v} \right) + \ln \left(\frac{u_1 (t - \tau_5)}{u_1} \right) \\ & = \ln \left(\frac{x_1^*}{x_1} \right) + \ln \left(\frac{x_1 (t - \tau_2) v (t - \tau_2) u_1^*}{x_1^* v^* u_1} \right) + \ln \left(\frac{u_1 (t - \tau_5) v^*}{u_1^* v} \right). \end{aligned}$$

Using similar relations for the terms containing τ_3 and τ_4 , we finally obtain

$$\begin{aligned} \dot{W}_2 = & \sum_{i=1}^2 \left[\frac{-\gamma_i d_i (x_i - x_i^*)^2}{x_i} \right. \\ & \left. - \gamma_i \beta_i x_i^* v^* f \left(\frac{x_i^*}{x_i} \right) \right] - \rho_1 \beta_1 e^{-\alpha_1 \tau_1 - \alpha_5 \tau_5} x_1^* v^* \left[f \left(\frac{y_1^* x_1 (t - \tau_1) v (t - \tau_1)}{y_1 x_1^* v^*} \right) + f \left(\frac{y_1 u_1^*}{y_1^* u_1} \right) \right. \\ & \left. + f \left(\frac{u_1 (t - \tau_5) v^*}{u_1^* v} \right) \right] - \frac{(a + \delta)}{\delta} (1 - \rho_1) \beta_1 e^{-\alpha_2 \tau_2 - \alpha_5 \tau_5} x_1^* v^* \\ & \times \left[f \left(\frac{x_1 (t - \tau_2) v (t - \tau_2) u_1^*}{x_1^* v^* u_1} \right) + f \left(\frac{u_1 (t - \tau_5) v^*}{u_1^* v} \right) \right] \end{aligned}$$

$$\begin{aligned}
 & -\rho_2\beta_2e^{-\alpha_3\tau_3-\alpha_5\tau_5}x_2^*v^*\left[f\left(\frac{y_2^*x_2(t-\tau_3)v(t-\tau_3)}{y_2(t)x_2^*v^*}\right)+f\left(\frac{y_2u_2^*}{y_2^*u_2}\right)+f\left(\frac{u_2(t-\tau_5)v^*}{u_2^*v}\right)\right] \\
 & -\frac{(a+\delta)}{\delta}(1-\rho_2)\beta_2e^{-\alpha_4\tau_4-\alpha_5\tau_5}x_2^*v^*\left[f\left(\frac{x_2(t-\tau_4)v(t-\tau_4)u_2^*}{x_2^*v^*u_2}\right)+f\left(\frac{u_2(t-\tau_5)v^*}{u_2^*v}\right)\right] \\
 & -\frac{(a+\delta)}{\delta}\frac{p[b+m(u_1+u_2)]}{(c-mz^*)}e^{-\alpha_5\tau_5}(z-z^*)^2. \tag{24}
 \end{aligned}$$

It follows that $\dot{W}_2 \leq 0$. Now LaSalle’s invariance principle implies that E^* is globally asymptotically stable. \square

3 HIV model with distributed delays

We study the HIV infection model with distributed time delays:

$$\dot{x}_1(t) = \lambda_1 - d_1x_1(t) - \beta_1x_1(t)v(t), \tag{25}$$

$$\dot{y}_1(t) = \rho_1\beta_1\int_0^{s_1} h_1(\tau)e^{-m_1\tau}x_1(t-\tau)v(t-\tau)d\tau - ay_1(t) - \delta y_1(t), \tag{26}$$

$$\begin{aligned}
 \dot{u}_1(t) &= (1-\rho_1)\beta_1\int_0^{s_2} h_2(\tau)e^{-m_2\tau}x_1(t-\tau)v(t-\tau)d\tau \\
 &+ \delta y_1(t) - pu_1(t)z(t) - \mu u_1(t), \tag{27}
 \end{aligned}$$

$$\dot{x}_2(t) = \lambda_2 - d_2x_2(t) - \beta_2x_2(t)v(t), \tag{28}$$

$$\dot{y}_2(t) = \rho_2\beta_2\int_0^{s_3} h_3(\tau)e^{-m_3\tau}x_2(t-\tau)v(t-\tau)d\tau - ay_2(t) - \delta y_2(t), \tag{29}$$

$$\begin{aligned}
 \dot{u}_2(t) &= (1-\rho_2)\beta_2\int_0^{s_4} h_4(\tau)e^{-m_4\tau}x_2(t-\tau)v(t-\tau)d\tau \\
 &+ \delta y_2(t) - pu_2(t)z(t) - \mu u_2(t), \tag{30}
 \end{aligned}$$

$$\dot{v}(t) = k\int_0^{s_5} g(\tau)e^{-n\tau}(u_1(t-\tau) + u_2(t-\tau))d\tau - rv(t), \tag{31}$$

$$\dot{z}(t) = c(u_1(t) + u_2(t)) - m(u_1(t) + u_2(t))z(t) - bz(t). \tag{32}$$

The factors $h_{2i-1}(\tau)e^{-m_{2i-1}\tau}$, $i = 1, 2$ are the probabilities that uninfected cells contacted by HIV at time $t - \tau$ survived τ time units and become latently infected at time t , where $i = 1$ and $i = 2$ represent the CD4⁺ T cells and macrophages, respectively; $h_{2i}(\tau)e^{-m_{2i}\tau}$, $i = 1, 2$ are the probabilities that the uninfected cells contacted by HIV at time $t - \tau$ survived τ time units and become actively infected at time t ; $g(\tau)e^{-n\tau}$ is the probability that an immature pathogen at time $t - \tau$ survived τ time units to become mature at time t . The probability distribution function $h_i(\tau)$, $i = 1, \dots, 4$ and $g(\tau)$ are assumed to satisfy $h_i(\tau) > 0$, $i = 1, \dots, 4$ and $g(\tau) > 0$, as well as

$$\begin{aligned}
 \int_0^{s_j} h_j(\tau)d\tau &= \int_0^{s_5} g(\tau)d\tau = 1, & \int_0^{s_j} h_j(\tau)e^{\varepsilon r}dr < \infty, \\
 \int_0^{s_5} g(\tau)e^{\varepsilon r}dr &< \infty, & i = 1, \dots, 4, \varepsilon > 0.
 \end{aligned}$$

Let

$$H_j = \int_0^{s_j} h_j(\tau)e^{-m_j\tau} d\tau, \quad G = \int_0^{s_5} g(\tau)e^{-n\tau} d\tau = G, \quad j = 1, \dots, 4.$$

Then $0 < H_j \leq 1$ and $0 < G \leq 1, j = 1, \dots, 4$.

The initial conditions for system (25)–(32) are the same as given by (14) where $\kappa = \max\{s_1, s_2, s_3, s_4, s_5\}$.

3.1 Nonnegativity and boundedness

Proposition 2 *The solutions of system (25)–(32) are nonnegative and ultimately bounded.*

Proof The nonnegativity can be shown as in Proposition 1. To show the boundedness, let us define

$$\begin{aligned} U_1(t) &= \rho_1 \int_0^{s_1} h_1(\tau)e^{-m_1\tau} x_1(t - \tau) d\tau + (1 - \rho_1) \int_0^{s_2} h_2(\tau)e^{-m_2\tau} x_1(t - \tau) d\tau \\ &\quad + \rho_2 \int_0^{s_3} h_3(\tau)e^{-m_3\tau} x_2(t - \tau) d\tau + (1 - \rho_2) \int_0^{s_4} h_4(\tau)e^{-m_4\tau} x_2(t - \tau) d\tau \\ &\quad + y_1(t) + u_1(t) + y_2(t) + u_2(t) + \frac{\mu}{2c}z(t). \end{aligned}$$

Then

$$\begin{aligned} \dot{U}_1(t) &= \rho_1 H_1 \lambda_1 + (1 - \rho_1) H_2 \lambda_1 + \rho_2 H_3 \lambda_2 + (1 - \rho_2) H_4 \lambda_2 \\ &\quad - \left(p + \frac{\mu m}{2c} \right) (u_1(t) + u_2(t)) z(t) - \rho_1 e^{-\alpha_1 \tau_1} d_1 x_1(t - \tau_1) \\ &\quad - (1 - \rho_1) e^{-\alpha_2 \tau_2} d_1 x_1(t - \tau_2) \\ &\quad - \rho_2 e^{-\alpha_3 \tau_3} d_2 x_2(t - \tau_3) - (1 - \rho_2) e^{-\alpha_4 \tau_4} d_2 x_2(t - \tau_4) - a y_1(t) - a y_2(t) \\ &\quad - \frac{\mu}{2} u_1(t) - \frac{\mu}{2} u_2(t) - \frac{\mu b}{2c} z(t) \\ &\leq \lambda_1 + \lambda_2 - \delta_1 U_1(t). \end{aligned}$$

Then $\limsup_{t \rightarrow \infty} x_i(t) \leq M_1, \limsup_{t \rightarrow \infty} y_i(t) \leq M_1, \limsup_{t \rightarrow \infty} u_i(t) \leq M_1, \limsup_{t \rightarrow \infty} z(t) \leq M_2$ and $\limsup_{t \rightarrow \infty} v(t) \leq M_3$, where M_1, M_2 and M_3 are defined in the previous section. \square

3.2 Steady states

The basic reproduction number R_0 for system (25)–(32) is as follows:

$$R_0 = \frac{\delta k G}{\mu r(a + \delta)} (\xi_1 \beta_1 x_1^0 + \xi_2 \beta_2 x_2^0),$$

where

$$\xi_1 = \rho_1 H_1 + \frac{(a + \delta)}{\delta} (1 - \rho_1) H_2, \quad \xi_2 = \rho_2 H_3 + \frac{(a + \delta)}{\delta} (1 - \rho_2) H_4.$$

Lemma 2 For system (25)–(32) (i) if $R_0 \leq 1$, then there exists an infection-free steady state E_0 , and (ii) if $R_0 > 1$, then there exist two steady states, E_0 and a chronic steady state E^* .

Proof The steady states of model (25)–(32) satisfy:

$$\lambda_1 - d_1x_1 - \beta_1x_1v = 0, \tag{33}$$

$$\rho_1\beta_1H_1x_1v - ay_1 - \delta y_1 = 0, \tag{34}$$

$$(1 - \rho_1)\beta_1H_2x_1v + \delta y_1 - pu_1z - \mu u_1 = 0, \tag{35}$$

$$\lambda_2 - d_2x_2 - \beta_2x_2v = 0, \tag{36}$$

$$\rho_2\beta_2H_3x_2v - ay_2 - \delta y_2 = 0, \tag{37}$$

$$(1 - \rho_2)\beta_2H_4x_2v + \delta y_2 - pu_2z - \mu u_2 = 0, \tag{38}$$

$$kG(u_1 + u_2) - rv = 0, \tag{39}$$

$$c(u_1 + u_2) - m(u_1 + u_2)z - bz = 0. \tag{40}$$

We find that system (25)–(32) admits an infection-free steady state $E_0 = (x_1^0, 0, 0, x_2^0, 0, 0, 0, 0)$ where $x_1^0 = \frac{\lambda_1}{d_1}$, $x_2^0 = \frac{\lambda_2}{d_2}$. In addition, from Eqs. (33)–(40) we get

$$A_2v^3 + B_2v^2 + C_2v + D_2 = 0,$$

where

$$A_2 = \beta_1\beta_2(\mu m + pc)r^2,$$

$$B_2 = \beta_1\beta_2\mu rbGk + (\beta_1d_2 + \beta_2d_1)(\mu m + pc)r^2 - \frac{\beta_1\beta_2mr\delta Gk}{a + \delta}(\lambda_1\xi_1 + \lambda_2\xi_2),$$

$$C_2 = \mu rbGk(\beta_1d_2 + \beta_2d_1) + \mu mr^2d_1d_2(1 - R_0) + pc r^2d_1d_2 - \frac{\beta_1\beta_2\delta bG^2k^2}{a + \delta}(\lambda_1\xi_1 + \lambda_2\xi_2),$$

$$D_2 = \mu r b k d_1 d_2 G(1 - R_0).$$

Let

$$\Psi_2(v) = A_2v^3 + B_2v^2 + C_2v + D_2 = 0.$$

If $R_0 > 1$, then $\Psi_2(0) = D_2 < 0$; moreover, $\lim_{v \rightarrow \infty} \Psi_2(v) = \infty$. Then there exists $v^* \in (0, \infty)$ such that $\Psi_2(v^*) = 0$. Therefore, a chronic steady state $E^* = (x_1^*, y_1^*, u_1^*, x_2^*, y_2^*, u_2^*, v^*, z^*)$ exists if $R_0 > 1$, where

$$x_i^* = \frac{\lambda_i}{d_i + \beta_i v^*}, \quad i = 1, 2,$$

$$y_1^* = \frac{\rho_1\beta_1H_1x_1^*v^*}{a + \delta}, \quad y_2^* = \frac{\rho_2\beta_2H_3x_2^*v^*}{a + \delta},$$

$$u_i^* = \frac{\xi_i\beta_ix_i^*v^*\delta}{(\mu + pz^*)(a + \delta)}, \quad \sum_{i=1}^2 u_i^* = \frac{rv^*}{Gk},$$

$$z^* = \frac{crv^*}{bkG + mrv^*}.$$

□

3.3 Global stability

Theorem 3 *If $R_0 \leq 1$, then E_0 for system (25)–(32) is globally asymptotically stable.*

Proof Define

$$\begin{aligned}
 V_1 = & \sum_{i=1}^2 \left[\xi_i x_i^0 f \left(\frac{x_i}{x_i^0} \right) + y_i + \frac{a + \delta}{\delta} u_i \right] + \frac{\mu(a + \delta)}{\delta Gk} v + \frac{p(a + \delta)}{2\delta c} z^2 \\
 & + \rho_1 \beta_1 \int_0^{s_1} h_1(\tau) e^{-m_1 \tau} \int_0^\tau x_1(t - \vartheta) v(t - \vartheta) d\vartheta d\tau \\
 & + \frac{(a + \delta)}{\delta} (1 - \rho_1) \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} \int_0^\tau \beta_1 x_1(t - \vartheta) v(t - \vartheta) d\vartheta d\tau \\
 & + \rho_2 \beta_2 \int_0^{s_3} h_3(\tau) e^{-m_3 \tau} \int_0^\tau x_2(t - \vartheta) v(t - \vartheta) d\vartheta d\tau \\
 & + \frac{(a + \delta)}{\delta} (1 - \rho_2) \beta_2 \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} \int_0^\tau x_2(t - \vartheta) v(t - \vartheta) d\vartheta d\tau \\
 & + \frac{\mu(a + \delta)}{\delta G} \int_0^{s_5} g(\tau) e^{-n\tau} \int_0^\tau [u_1(t - \vartheta) + u_2(t - \vartheta)] d\vartheta d\tau. \tag{41}
 \end{aligned}$$

Calculating \dot{V}_1 along system (25)–(32), we obtain

$$\begin{aligned}
 \dot{V}_1 = & \sum_{i=1}^2 \left[\xi_i \left(1 - \frac{x_i^0}{x_i} \right) \dot{x}_i + \dot{y}_i + \frac{a + \delta}{\delta} \dot{u}_i \right] + \frac{\mu(a + \delta)}{\delta Gk} \dot{v} + \frac{p(a + \delta)}{\delta c} z \dot{z} \\
 & + \rho_1 \beta_1 \int_0^{s_1} h_1(\tau) e^{-m_1 \tau} [x_1(t)v(t) - x_1(t - \tau)v(t - \tau)] d\tau \\
 & + \frac{(a + \delta)(1 - \rho_1)}{\delta} \beta_1 \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} [x_1(t)v(t) - x_1(t - \tau)v(t - \tau)] d\tau \\
 & + \rho_2 \beta_2 \int_0^{s_3} h_3(\tau) e^{-m_3 \tau} [x_2v - x_2(t - \tau)v(t - \tau)] d\tau \\
 & + \frac{(a + \delta)(1 - \rho_2)}{\delta} \beta_2 \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} [x_2v - x_2(t - \tau)v(t - \tau)] d\tau \\
 & + \frac{\mu(a + \delta)}{\delta G} \int_0^{s_5} g(\tau) e^{-n\tau} [u_1 + u_2 - u_1(t - \tau) - u_2(t - \tau)] d\tau.
 \end{aligned}$$

Since $\lambda_i = d_i x_i^0$, we get

$$\begin{aligned}
 \dot{V}_1 = & \sum_{i=1}^2 \left[\xi_i \left(1 - \frac{x_i^0}{x_i} \right) (d_i x_i^0 - d_i x_i) - \xi_i \beta_i x_i v \left(1 - \frac{x_i^0}{x_i} \right) + \xi_i \beta_i x_i v \right] - \frac{\mu(a + \delta)}{\delta Gk} r v \\
 & - \frac{pm(a + \delta)}{\delta c} (u_1 + u_2) z^2 - \frac{pb(a + \delta)}{\delta c} z^2 \\
 = & \sum_{i=1}^2 \frac{-d_i \xi_i (x_i - x_i^0)^2}{x_i} + \frac{\mu r (a + \delta)}{\delta Gk} (R_0 - 1) v - \frac{pm(a + \delta)}{\delta} \sum_{i=1}^2 u_i z^2 - \frac{pb(a + \delta)}{\delta c} z^2.
 \end{aligned}$$

Similar to the proof of Theorem 1, E_0 is globally asymptotically stable if $R_0 \leq 1$. □

Theorem 4 *If $R_0 > 1$, then E^* for system (25)–(32) is globally asymptotically stable.*

Proof Define

$$\begin{aligned}
 V_2 = & \sum_{i=1}^2 \left[\xi_i x_i^* f\left(\frac{x_i}{x_i^*}\right) + y_i^* f\left(\frac{y_i}{y_i^*}\right) + \frac{(a+\delta)}{\delta} u_i^* f\left(\frac{u_i}{u_i^*}\right) \right] + \frac{(a+\delta)(\mu + pz^*)}{\delta Gk} v^* f\left(\frac{v}{v^*}\right) \\
 & + \frac{p(a+\delta)}{2\delta(c - mz^*)} (z - z^*)^2 \\
 & + \rho_1 \beta_1 x_1^* v^* \int_0^{s_1} h_1(\tau) e^{-m_1 \tau} \int_0^\tau f\left(\frac{x_1(t-\vartheta)v(t-\vartheta)}{x_1^* v^*}\right) d\vartheta d\tau \\
 & + \frac{(a+\delta)}{\delta} (1 - \rho_1) \beta_1 x_1^* v^* \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} \int_0^\tau f\left(\frac{x_1(t-\vartheta)v(t-\vartheta)}{x_1^* v^*}\right) d\vartheta d\tau \\
 & + \rho_2 \beta_2 x_2^* v^* \int_0^{s_3} h_3(\tau) e^{-m_3 \tau} \int_0^\tau f\left(\frac{x_2(t-\vartheta)v(t-\vartheta)}{x_2^* v^*}\right) d\vartheta d\tau \\
 & + \frac{(a+\delta)}{\delta} (1 - \rho_2) \beta_2 x_2^* v^* \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} \int_0^\tau f\left(\frac{x_2(t-\vartheta)v(t-\vartheta)}{x_2^* v^*}\right) d\vartheta d\tau \\
 & + \frac{(a+\delta)(\mu + pz^*)}{\delta G} \int_0^{s_5} g(\tau) e^{-n\tau} \int_0^\tau \left[u_1^* f\left(\frac{u_1(t-\vartheta)}{u_1^*}\right) + u_2^* f\left(\frac{u_2(t-\vartheta)}{u_2^*}\right) \right] d\vartheta d\tau.
 \end{aligned}$$

It is seen that function V_2 is positive definite. The time derivative of V_2 is given by the following:

$$\begin{aligned}
 \dot{V}_2 = & \sum_{i=1}^2 \left[\xi_i \left(1 - \frac{x_i^*}{x_i}\right) \dot{x}_i + \left(1 - \frac{y_i^*}{y_i}\right) \dot{y}_i + \frac{(a+\delta)}{\delta} \left(1 - \frac{u_i^*}{u_i}\right) \dot{u}_i \right] \\
 & + \frac{(a+\delta)(\mu + pz^*)}{\delta Gk} \left(1 - \frac{v^*}{v}\right) \dot{v} \\
 & + \frac{p(a+\delta)}{\delta(c - mz^*)} (z - z^*) \dot{z} + \rho_1 \beta_1 x_1^* v^* \int_0^{s_1} h_1(\tau) e^{-m_1 \tau} \left[\frac{x_1 v}{x_1^* v^*} - \frac{x_1(t-\tau)v(t-\tau)}{x_1^* v^*} \right. \\
 & \left. + \ln \frac{x_1(t-\tau)v(t-\tau)}{x_1 v} \right] d\tau \\
 & + \frac{(a+\delta)}{\delta} (1 - \rho_1) \beta_1 x_1^* v^* \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} \left[\frac{x_1 v}{x_1^* v^*} - \frac{x_1(t-\tau)v(t-\tau)}{x_1^* v^*} \right. \\
 & \left. + \ln \frac{x_1(t-\tau)v(t-\tau)}{x_1 v} \right] d\tau \\
 & + \rho_2 \beta_2 x_2^* v^* \int_0^{s_3} h_3(\tau) e^{-m_3 \tau} \left[\frac{x_2 v}{x_2^* v^*} - \frac{x_2(t-\tau)v(t-\tau)}{x_2^* v^*} + \ln \frac{x_2(t-\tau)v(t-\tau)}{x_2 v} \right] d\tau \\
 & + \frac{(a+\delta)}{\delta} (1 - \rho_2) \beta_2 x_2^* v^* \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} \left[\frac{x_2 v}{x_2^* v^*} - \frac{x_2(t-\tau)v(t-\tau)}{x_2^* v^*} \right. \\
 & \left. + \ln \frac{x_2(t-\tau)v(t-\tau)}{x_2 v} \right] d\tau \\
 & + \frac{(a+\delta)(\mu + pz^*)}{\delta G} u_1^* \int_0^{s_5} g(\tau) e^{-n\tau} \left[\frac{u_1}{u_1^*} - \frac{u_1(t-\tau)}{u_1^*} + \ln \frac{u_1(t-\tau)}{u_1} \right] d\tau \\
 & + \frac{(a+\delta)(\mu + pz^*)}{\delta G} u_2^* \int_0^{s_5} g(\tau) e^{-n\tau} \left[\frac{u_2}{u_2^*} - \frac{u_2(t-\tau)}{u_2^*} + \ln \frac{u_2(t-\tau)}{u_2} \right] d\tau.
 \end{aligned}$$

Using chronic steady state conditions

$$\begin{aligned} \lambda_i &= d_i x_i^* + \beta_i x_i^* v^*, & (a + \delta) y_1^* &= \rho_1 \beta_1 H_1 x_1^* v^*, \\ (a + \delta) y_2^* &= \rho_2 \beta_2 H_3 x_2^* v^*, & (a + \delta)(\mu + pz^*) u_i^* &= \xi_i \beta_i \delta x_i^* v^*, \\ rv^* &= kG(u_1^* + u_2^*), & 0 &= c(u_1^* + u_2^*) - m(u_1^* + u_2^*)z^* - bz^*, \end{aligned}$$

we can simplify:

$$\begin{aligned} & \frac{p}{(c - mz^*)} (z - z^*) \dot{z} \\ &= \frac{p(a + \delta)(z - z^*)}{\delta(c - mz^*)} (c(u_1 + u_2) - m(u_1 + u_2)z - bz) \\ &= p \left[\sum_{i=1}^2 u_i^* z^* - \sum_{i=1}^2 u_i^* z - \sum_{i=1}^2 u_i z^* + \sum_{i=1}^2 u_i z - \frac{[b + m \sum_{i=1}^2 u_i]}{(c - mz^*)} (z - z^*)^2 \right]. \end{aligned} \tag{42}$$

The following relations will be used:

$$\begin{aligned} \ln \left(\frac{x_1(t - \tau)v(t - \tau)}{x_1 v} \right) &= \ln \left(\frac{x_1^* v^* y_1}{x_1 v y_1^*} \right) + \ln \left(\frac{y_1^* x_1(t - \tau)v(t - \tau)}{y_1 x_1^* v^*} \right), \\ \ln \left(\frac{x_1(t - \tau)v(t - \tau)}{x_1 v} \right) &= \ln \left(\frac{x_1^* v^* u_1}{x_1 v u_1^*} \right) + \ln \frac{u_1^* x_1(t - \tau)v(t - \tau)}{u_1 x_1^* v^*}, \\ \ln \left(\frac{u_i(t - \tau)}{u_i} \right) &= \ln \left(\frac{v u_i^*}{v^* u_i} \right) + \ln \left(\frac{u_i(t - \tau)v^*}{u_i^* v} \right). \end{aligned}$$

Now using the last relations with steady state conditions and Eq. (42), we can rewrite

$$\begin{aligned} \dot{V}_2(t) &= \sum_{i=1}^2 \left[\frac{-\xi_i d_i (x_i - x_i^*)^2}{x_i} + \xi_i \beta_i x_i^* v^* \left(1 - \frac{x_i^*}{x_i} \right) \right. \\ &\quad - \frac{\xi_i \beta_i x_i^* v^*}{G} \int_0^{s5} g(\tau) e^{-n\tau} f \left(\frac{v^* u_i(t - \tau)}{v u_i^*} \right) d\tau \\ &\quad + \frac{\xi_i \beta_i x_i^* v^*}{G} \int_0^{s5} g(\tau) e^{-n\tau} \ln \frac{v u_i^*}{v^* u_i} d\tau \left. \right] - \rho_1 \beta_1 H_1 x_1^* v^* \left(\frac{y_1 u_1^*}{y_1^* u_1} - 1 \right) \\ &\quad - \rho_2 \beta_2 H_3 x_2^* v^* \left(\frac{y_2 u_2^*}{y_2^* u_2} - 1 \right) \\ &\quad - \rho_1 \beta_1 x_1^* v^* \int_0^{s1} h_1(\tau) e^{-m_1 \tau} f \left(\frac{y_1^* x_1(t - \tau)v(t - \tau)}{y_1 x_1^* v^*} \right) d\tau \\ &\quad + \rho_1 \beta_1 x_1^* v^* \int_0^{s1} h_1(\tau) e^{-m_1 \tau} \ln \frac{y_1 x_1^* v^*}{y_1^* x_1 v} d\tau \\ &\quad - \rho_2 \beta_2 x_2^* v^* \int_0^{s3} h_3(\tau) e^{-m_3 \tau} f \left(\frac{y_2^* x_2(t - \tau)v(t - \tau)}{y_2 x_2^* v^*} \right) d\tau \\ &\quad + \rho_2 \beta_2 x_2^* v^* \int_0^{s3} h_3(\tau) e^{-m_3 \tau} \ln \frac{y_2 x_2^* v^*}{y_2^* x_2 v} d\tau \\ &\quad + \frac{a + \delta}{\delta} (1 - \rho_1) \beta_1 x_1^* v^* \int_0^{s2} h_2(\tau) e^{-m_2 \tau} \ln \frac{u_1 x_1^* v^*}{u_1^* x_1 v} d\tau \end{aligned}$$

$$\begin{aligned}
 & + \frac{a + \delta}{\delta} \rho_2 \beta_2 x_2^* v^* \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} \ln \frac{u_2 x_2^* v^*}{u_2^* x_2 v} d\tau \\
 & - \frac{a + \delta}{\delta} (1 - \rho_1) \beta_1 x_1^* v^* \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} f\left(\frac{u_1^* x_1(t - \tau) v(t - \tau)}{u_1 x_1^* v^*}\right) d\tau \\
 & - \frac{a + \delta}{\delta} (1 - \rho_2) \beta_2 x_2^* v^* \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} f\left(\frac{u_2^* x_2(t - \tau) v(t - \tau)}{u_2 x_2^* v^*}\right) d\tau \\
 & - \frac{p(a + \delta)[b + m(u_1 + u_2)]}{\delta(c - mz^*)} (z - z^*)^2.
 \end{aligned}$$

Finally, we obtain

$$\begin{aligned}
 \dot{V}_2(t) = & - \sum_{i=1}^2 \left[\frac{\xi_i d_i (x_i - x_i^*)^2}{x_i} + \xi_i \beta_i x_i^* v^* f\left(\frac{x_i^*}{x_i}\right) \right. \\
 & \left. + \frac{\xi_i \beta_i x_i^* v^*}{G} \int_0^{s_5} g(\tau) e^{-n\tau} f\left(\frac{v^* u_i(t - \tau)}{v u_i^*}\right) d\tau \right] \\
 & - \rho_1 \beta_1 H_1 x_1^* v^* f\left(\frac{y_1 u_1^*}{y_1^* u_1}\right) - \rho_1 \beta_1 x_1^* v^* \int_0^{s_1} h_1(\tau) e^{-m_1 \tau} f\left(\frac{y_1^* x_1(t - \tau) v(t - \tau)}{y_1 x_1^* v^*}\right) d\tau \\
 & - \rho_2 \beta_2 H_3 x_2^* v^* f\left(\frac{y_2 u_2^*}{y_2^* u_2}\right) - \rho_2 \beta_2 x_2^* v^* \int_0^{s_3} h_3(\tau) e^{-m_3 \tau} f\left(\frac{y_2^* x_2(t - \tau) v(t - \tau)}{y_2 x_2^* v^*}\right) d\tau \\
 & - \frac{a + \delta}{\delta} (1 - \rho_1) \beta_1 x_1^* v^* \int_0^{s_2} h_2(\tau) e^{-m_2 \tau} f\left(\frac{u_1^* x_1(t - \tau) v(t - \tau)}{u_1 x_1^* v^*}\right) d\tau \\
 & - \frac{a + \delta}{\delta} (1 - \rho_2) \beta_2 x_2^* v^* \int_0^{s_4} h_4(\tau) e^{-m_4 \tau} f\left(\frac{u_2^* x_2(t - \tau) v(t - \tau)}{u_2 x_2^* v^*}\right) d\tau \\
 & - \frac{p(a + \delta)[b + m(u_1 + u_2)]}{\delta(c - mz^*)} (z - z^*)^2.
 \end{aligned}$$

Applying LaSalle’s invariance principle to the last equation, we get $\dot{V}_2 \leq 0$, leading to the global asymptotic stability of the chronic steady state E^* . □

4 Numerical simulations

In this section, we perform numerical simulation for model (6)–(13) with values of the parameters given in Table 1. Let us consider for simplicity that $\tau_1 = \tau_2 = \tau_3 = \tau_4 = \tau_5 = \tau_c$, and chose the initial conditions as:

(IC1) $\omega_1(\eta) = 700, \omega_2(\eta) = 20, \omega_3(\eta) = 15, \omega_4(\eta) = 15, \omega_5(\eta) = 0.0005, \omega_6(\eta) = 0.0005, \omega_7(\eta) = 15$ and $\omega_8(\eta) = 1.5$;

(IC2) $\omega_1(\eta) = 500, \omega_2(\eta) = 15, \omega_3(\eta) = 10, \omega_4(\eta) = 10, \omega_5(\eta) = 0.001, \omega_6(\eta) = 0.001, \omega_7(\eta) = 12$ and $\omega_8(\eta) = 1$;

(IC3) $\omega_1(\eta) = 300, \omega_2(\eta) = 5, \omega_3(\eta) = 5, \omega_4(\eta) = 1, \omega_5(\eta) = 0.3, \omega_6(\eta) = 0.3, \omega_7(\eta) = 8$ and $\omega_8(\eta) = 0.5, \eta \in [-\max\{\tau_1, \tau_2, \tau_3, \tau_4, \tau_5\}, 0]$.

Case I. Stability of the steady states

Let $\tau_c = 0.7$ and $\rho_1 = \rho_2 = 0.5$. We have two subcases shown in Fig. 1:

(a) if $\beta_1 = 2.4 \times 10^{-5}$ and $\beta_2 = 2 \times 10^{-5}$, then $R_0 = 0.0264 < 1$. It follows that E_0 is globally asymptotically stable. In this case the concentration of the uninfected cells is increasing and returns to its normal value λ_i/d_i , while the concentrations of infected cells, HIV particles and CTLs are decaying and approach zero.

Table 1 The parameter values of model (6)–(13)

Parameter	Value	Parameter	Value
λ_1	10	λ_2	0.03198
d_1	0.01	d_2	0.01
β_1	varied	β_2	varied
ρ_1	varied	ρ_2	varied
a	0.1	α_1	1
p	0.04	α_2	1
k	6	α_3	1
r	3	α_4	1
c	0.025	α_5	1
b	0.2	δ	0.05
μ	0.3	m	0.005

(b) if $\beta_1 = 0.002$ and $\beta_2 = 0.001$ then $R_0 = 2.1955 > 1$. Therefore, E^* exists and is globally asymptotically stable. In this case the concentration of the uninfected cells is decreasing, while the concentrations of infected cells, HIV particles and CTLs are increasing. In this situation HIV infection will be chronic.

From the above, one can see that the infection rate parameters β_1 and β_2 have significant effects on stabilizing the infection-free steady state. This is because R_0 can be decreased by decreasing the values of β_1 and β_2 . The values of the parameters β_1 and β_2 can be reduced when an HIV infected patient is treated by reverse transcriptase inhibitor (RTI) drugs which prevent HIV from infecting the uninfected target cells. When incorporating the RTI drugs into the HIV dynamics model, the parameters β_1 and β_2 will be replaced by $(1 - \epsilon)\beta_1$ and $(1 - \epsilon)\beta_2$, respectively, where ϵ is the drug efficacy with $0 \leq \epsilon < 1$. In this case, the basic reproduction number is given by

$$R_0(\epsilon) = \frac{(1 - \epsilon)\delta k}{\mu r(a + \delta)} (\gamma_1 \beta_1 x_1^0 + \gamma_2 \beta_2 x_2^0).$$

Therefore, one can find the minimum drug efficacy ϵ_m , which makes $R_0(\epsilon) \leq 1$ and then stabilizes the system around the infection-free steady state E_0 , as:

$$\epsilon_m = \max \left\{ 1 - \frac{\mu r(a + \delta)}{\delta k(\gamma_1 \beta_1 x_1^0 + \gamma_2 \beta_2 x_2^0)}, 0 \right\}. \tag{43}$$

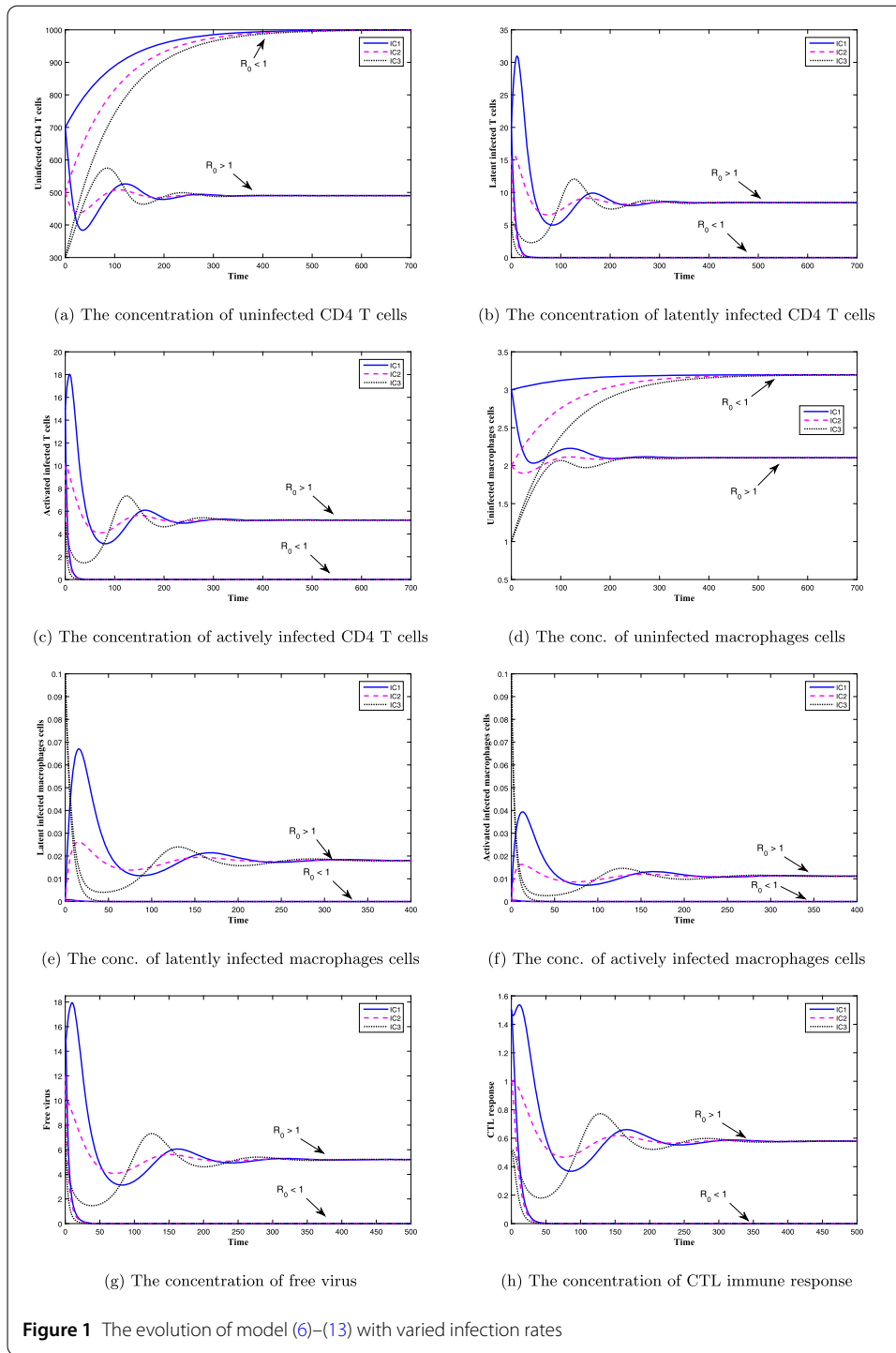
Case II. Effect of the time delay on the HIV dynamics

In this case, we fix the parameters $\beta_1 = 0.002$, $\beta_2 = 0.001$ and $\rho_1 = \rho_2 = 0.5$. We consider initial conditions IC1. Figure 2 shows that the stability of the steady states has been changed by changing the values of the delay parameter τ_c . It can be seen that as τ_c is increased the concentration of the uninfected cells is increased, while the concentrations of infected cells, free HIV particles and CTLs are decreased. From Fig. 2 we can see that, in case of smaller values of τ_c , trajectories of the system will converge to E^* . If the value of τ_c is increased, trajectories will converge to E^* and finally approach E_0 . Using the values of the parameters given in Table 1, we have the following:

- (i) if $0.0 \leq \tau_c < 1.0932$, then E^* exists and is globally asymptotically stable;
- (ii) if $\tau_c \geq 1.0932$, then E_0 is globally asymptotically stable.

This result support the results of Theorems 1 and 2.

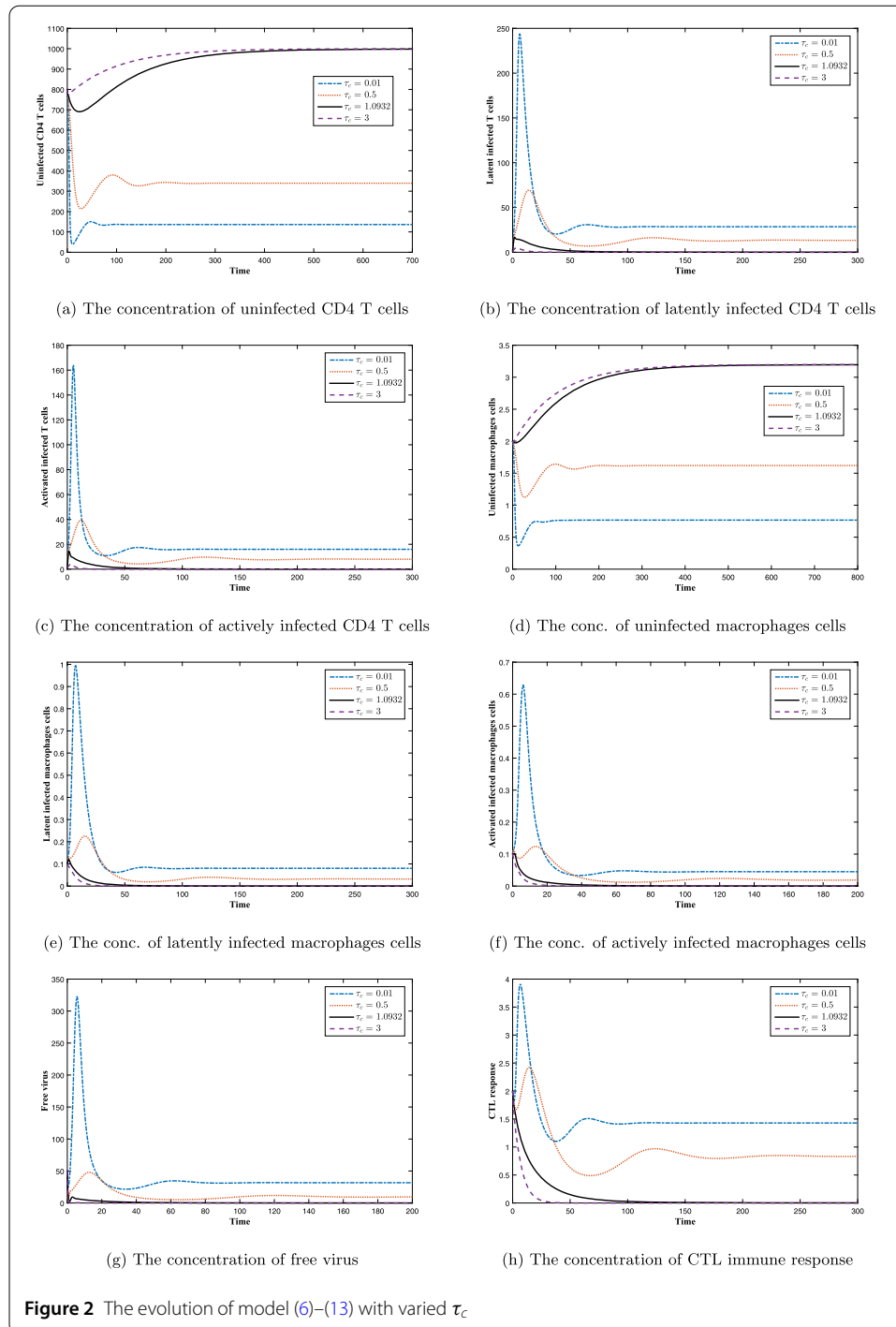
From a biological point of view, the intracellular delay plays a similar role as an antiviral treatment in eliminating the virus. We observe that sufficiently large delay suppresses viral



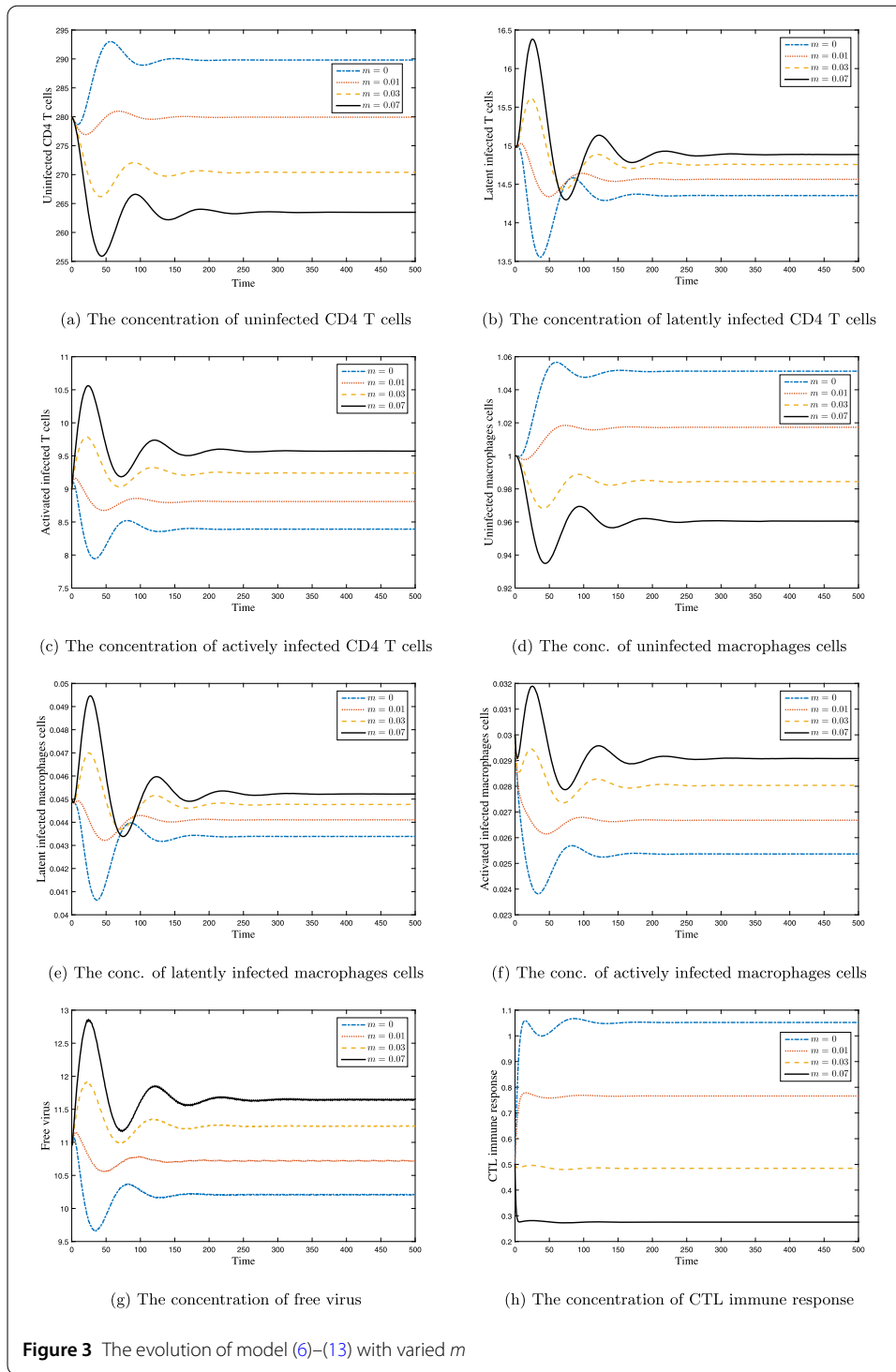
replication and clears the virus from the body. This gives us some suggestions on new drugs to prolong the increase of the intracellular delay period.

Case III. Effect of latency on the dynamical behavior of the system

In this case, we show the HIV dynamics for different values of ρ_i , the fraction of uninfected cells that become latently infected cells. We take $\beta_1 = 0.002$, $\beta_2 = 0.001$, $\tau_c = 0.8$ and the initial conditions IC1. For simplicity we let $\rho_1 = \rho_2 = \rho_c$. Figure 4 shows the effect



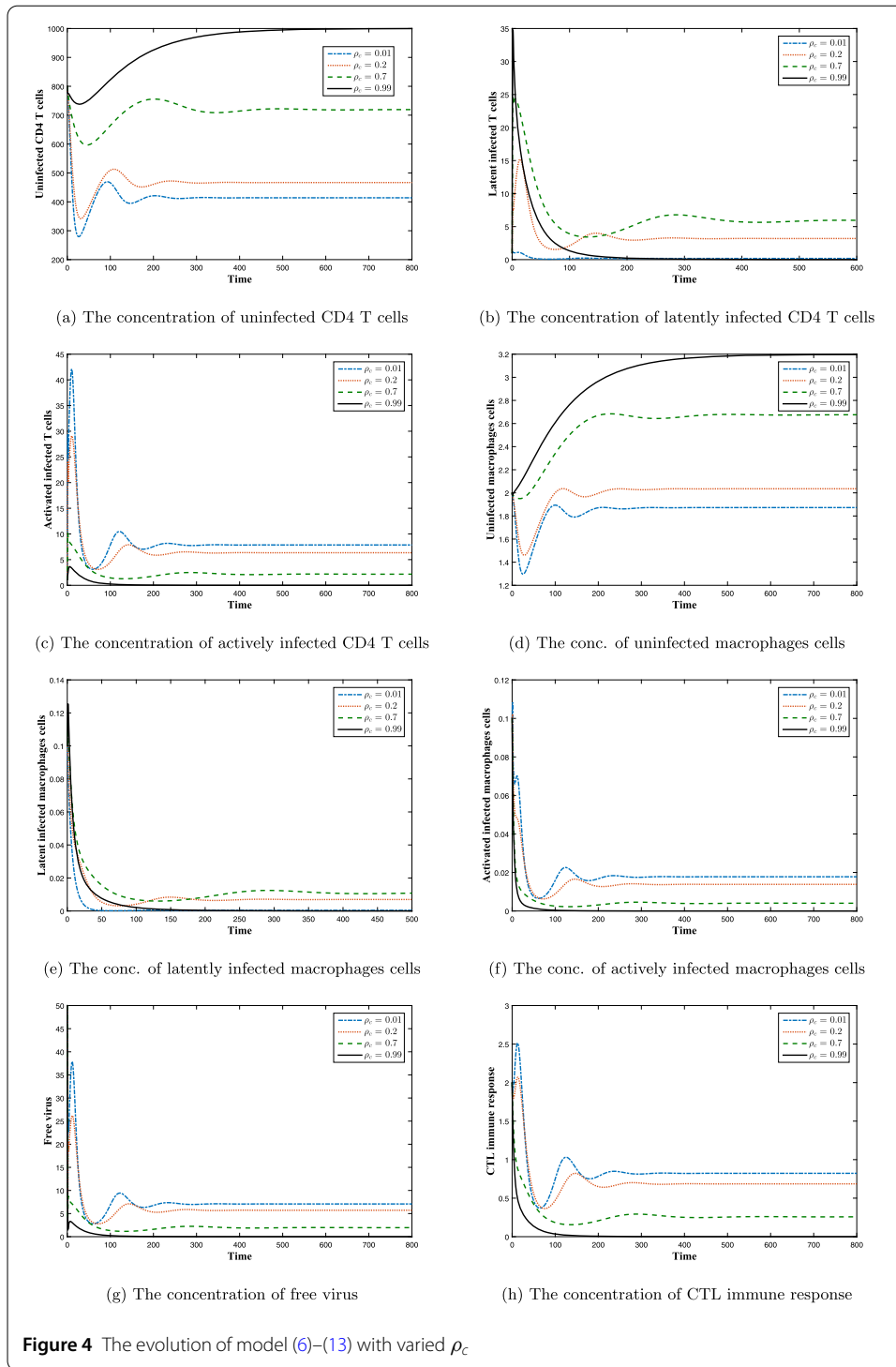
of ρ_c on the the evolution of system states. When ρ_c increases, we observe an increase in the concentration of the latently infected CD4⁺ T cells and macrophages. This means that the reservoirs of these cells are enlarged, which promotes an increase in the amount of virus that escapes treatment [18]. Subsequently, after activation of the latently infected cells, new HIV will be produced and released into the blood stream [55]. From Fig. 4 we can see that, when ρ_c is increased, the concentrations of uninfected cells, actively infected



cells, free HIV particles and CTLs are decreased. Using the values of the parameters given in Table 1 we have the following:

- (i) if $0.0 \leq \rho_c < 0.9437$, then $R_0 > 1$ and E^* exists and is globally asymptotically stable;
- (ii) if $\rho_c \geq 0.9437$, then $R_0 \leq 1$ and E_0 is globally asymptotically stable.

Case IV. Effect of the immune impairment parameter m on the HIV dynamics



In this case, we choose $\beta_1 = 2.4 \times 10^{-3}$, $\beta_2 = 2 \times 10^{-3}$, $\tau_c = 0.5$, $\rho_c = 0.5$ and the initial conditions IC4: $\omega_1(\eta) = 280$, $\omega_2(\eta) = 15$, $\omega_3(\eta) = 9$, $\omega_4(\eta) = 1$, $\omega_5(\eta) = 0.045$, $\omega_6(\eta) = 0.03$, $\omega_7(\eta) = 11$ and $\omega_8(\eta) = 0.5$. Figure 3 shows that, as m is increased, the concentration of CTL cells is decreased and then the concentrations of latently infected cells, actively infected cells and free HIV particles are increased, while the concentration of the unin-

fectected cells is decreased. We note that R_0 does not depend on the parameter m ; therefore, m does not change the stability properties of steady states.

5 Conclusion and discussion

All of the existing mathematical models of HIV infection with CTL immune impairment study the HIV infection and production in one class of target cells, $CD4^+$ T cells. However, it has been reported in several papers that HIV can infect both $CD4^+$ T cells and macrophages. In this paper, we have studied an HIV dynamics model with CTL immune impairment and with two classes of target cells, $CD4^+$ T cells and macrophages. We have considered two types of infected cells, latently infected cells (such cells contain HIV but are not producing it) and actively infected cells (such cells are producing HIV). The model considers multiple discrete or distributed time delays to characterize the time between an HIV contact of an uninfected target cell and the creation of mature HIV particles. We have shown that the solutions of the model are nonnegative and ultimately bounded which ensures the well-posedness of the model. We have derived a biological threshold number R_0 (the basic reproduction number) which fully determines the existence and stability of the two steady states of the model. We have investigated the global stability of the model steady states by using Lyapunov method and LaSalle’s invariance principle. We have proven that (i) if $R_0 \leq 1$, then the infection-free steady state E_0 is globally asymptotically stable and HIV is predicted to be completely cleared from the HIV infected individuals, (ii) if $R_0 > 1$, then the chronic steady state E^* is globally asymptotically stable and a chronic HIV infection is attained. We have conducted numerical simulations and have shown that both the theoretical and numerical results are consistent.

Our analysis extends the results presented in [49], where the global stability was analyzed for a model with one target cell population. When we consider the HIV dynamics with only one class of target cells, $CD4^+$ T cells, then model (6)–(13) under the effect of RTI drug therapy with drug efficacy ϵ leads to the following model:

$$\dot{x}_1(t) = \lambda_1 - d_1x_1(t) - (1 - \epsilon)\beta_1x_1(t)v(t), \tag{44}$$

$$\dot{y}_1(t) = (1 - \epsilon)\rho_1\beta_1e^{-\alpha_1\tau_1}x_1(t - \tau_1)v(t - \tau_1) - ay_1(t) - \delta y_1(t), \tag{45}$$

$$\dot{u}_1(t) = (1 - \epsilon)(1 - \rho_1)\beta_1e^{-\alpha_2\tau_2}x_1(t - \tau_2)v(t - \tau_2) + \delta y_1(t) - pu_1(t)z(t) - \mu u_1(t), \tag{46}$$

$$\dot{v}(t) = ke^{-\alpha_5\tau_5}u_1(t - \tau_5) - rv(t), \tag{47}$$

$$\dot{z}(t) = cu_1(t) - mu_1(t)z(t) - bz(t). \tag{48}$$

The basic reproduction number for system (44)–(48) is given by

$$R_0^C(\epsilon) = \frac{(1 - \epsilon)\delta k \gamma_1 \beta_1 x_1^0}{\mu r(a + \delta)}.$$

The basic reproduction number for system (6)–(13) under the effect of RTI drug therapy can be written as:

$$R_0(\epsilon) = R_0^C(\epsilon) + R_0^M(\epsilon),$$

$$R_0^C(\epsilon) = \frac{(1 - \epsilon)\delta k \gamma_1 \beta_1 x_1^0}{\mu r(a + \delta)},$$

$$R_0^M(\epsilon) = \frac{(1-\epsilon)\delta k \gamma_2 \beta_2 x_2^0}{\mu r(a+\delta)},$$

where $R_0^M(\epsilon)$ is the basic reproduction number of a model that describes the HIV dynamics with only macrophages and neglects the CD4⁺ T cells. For system (44)–(48) one can determine the minimum drug efficacy ϵ_m^C such that $R_0^C(\epsilon_m^C) < 1$, namely

$$\epsilon_m^C = \max \left\{ 1 - \frac{\mu r(a+\delta)}{\delta k \gamma_1 \beta_1 x_1^0}, 0 \right\}. \quad (49)$$

Comparing Eqs. (43) and (49), we get that $\epsilon_m^C \leq \epsilon_m$. Therefore, if we apply drugs with ϵ such that $\epsilon_m^C \leq \epsilon < \epsilon_m$, this guarantees that $R_0^C(\epsilon) \leq 1$, and then E_0 of system (44)–(48) is globally asymptotically stable; however, $R_0(\epsilon) > 1$ and so E_0 of (6)–(13) is unstable. Therefore, more accurate drug efficacy ϵ is determined when using the model with two classes of target cells. This shows the importance of considering the effect of the macrophages in the HIV dynamics.

In the literature, fractional-order differential equations have been applied with the purpose of obtaining a deeper understanding of the complex behavioral patterns of HIV dynamical systems [53, 55–57]. The memory property of the fractional models allows the integration of more information from the past, which translates into more accurate predictions for the model. Clinicians can thus use the information (in terms of behavior predictions) of fractional-order systems to fit patients' data with the most appropriate non-integer-order index [53]. As a future work it is reasonable to use a corresponding fractional modification of our models, as fractional differential equations inherently include memory.

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Authors' contributions

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