

RESEARCH

Open Access



Iterative positive solutions to a coupled fractional differential system with the multistrip and multipoint mixed boundary conditions

Xiaodi Zhao¹, Yuehan Liu¹ and Huihui Pang^{1*}

*Correspondence:

pqh2000@163.com

¹College of Science, China Agricultural University, Beijing, P.R. China

Abstract

Using the monotone iterative technique, we investigate the existence of iterative positive solutions to a coupled system of fractional differential equations supplemented with multistrip and multipoint mixed boundary conditions. It is worth mentioning that the nonlinear terms of the system depend on the lower fractional-order derivatives of the unknown functions and the boundary conditions involve the combination of the multistrip fractional integral and the multipoint value of the unknown functions in $[0, 1]$.

MSC: 26A33; 34B15; 34B18

Keywords: Fractional differential system; Multistrip and multipoint mixed boundary conditions; Green's function; Monotone iterative technique

1 Introduction

Fractional differential equations have attracted more and more scholars' attention since they are more widely used and realistic than integer-order differential equations. In the past few years the fractional boundary value problems are found to be popular in the research community because of their numerous applications in many disciplinary areas, such as optics, thermal, mechanics, control theory, nuclear physics, economics, signal and image processing, medicine, and so on [1–4]. To meet the practical application needs, many different theoretical approaches have been taken to study the existence, uniqueness, and multiplicity of solutions to fractional-order boundary value problems, for instance, the method of upper and lower solutions [5–9], the fixed point theory [10–13], the monotone iterative technique [14–19], the coincidence degree theory [20–22], etc. In comparison, the monotone iterative technique has more advantages, such as it not only proves the existence of positive solutions but also can obtain approximate solutions that can meet different accuracy requirements.

Meanwhile, recently, coupled fractional differential systems have also aroused great interest and developed rapidly. Many researchers established the existence of solutions by the class methods [22–25]. However, to the best of our knowledge, only few papers applied the monotone iterative technique to discuss the boundary value problem of coupled

fractional differential systems [26–28]. To get more extensive results, different from the existing literature, we consider a generalized model that includes the nonlinear terms of the system depending on the lower fractional-order derivatives of the unknown functions and the boundary conditions involving a combination of the multistrip fractional integral and linear multipoint values of the unknown functions in $[0, 1]$.

Based on these considerations, we investigate the existence of iterative positive solutions to the following fractional differential systems:

$$\begin{cases} D_t^{\alpha_1} u(t) + f_1(t, u(t), v(t), D_t^{\gamma_1} u(t), D_t^{\gamma_2} v(t)) = 0, & t \in (0, 1), \\ D_t^{\alpha_2} v(t) + f_2(t, u(t), v(t), D_t^{\gamma_1} u(t), D_t^{\gamma_2} v(t)) = 0, & t \in (0, 1), \end{cases} \tag{1.1}$$

with the coupled fractional-order integral and discrete mixed boundary conditions

$$\begin{cases} u(0) = u'(0) = 0, & u(1) = \sum_{i=1}^m \lambda_{1i} I_t^{\beta_1} v(\xi_i) + \sum_{j=1}^n b_j v(\eta_j), \\ v(0) = v'(0) = 0, & v(1) = \sum_{i=1}^m \lambda_{2i} I_t^{\beta_2} u(\xi_i) + \sum_{j=1}^n b_j u(\eta_j), \end{cases} \tag{1.2}$$

where $2 < \alpha_k \leq 3, 0 < \gamma_k < \alpha_k - 2, 1 < \beta_k \leq 2$ for $k = 1, 2; \lambda_{1i} > 0, \lambda_{2i} > 0, 0 < \xi_i < 1$ for $i = 1, 2, \dots, m, b_j \geq 0, 0 < \eta_j < 1$ for $j = 1, 2, \dots, n$, and $D_t^{\alpha_k}$ and $D_t^{\gamma_k}$ are the standard Riemann–Liouville fractional derivatives of orders α_k and γ_k for $k = 1, 2$.

The coupled multistrip and multipoint mixed boundary conditions in (1.2) represent the value of unknown function $u(t)$ at the right end point $t = 1$, which is equal to the sum of the values of the Riemann–Liouville fractional integral of the unknown function $v(t)$ on the subinterval $[0, \xi_i]$ ($i = 1, 2, \dots, m$) and the linear combination of discrete values of the unknown function $v(t)$ at η_j ($j = 1, 2, \dots, n$).

To apply the monotone iterative technique, we construct a concrete form of initial iterative function vector, which is a fractional power function vector satisfying the multiconstraints from the cone, the monotonicity of the complete continuous operator T , and the monotonicity of the lower fractional-order derivatives of T . The initial function vector of concise form could make the iteration process concise and effective.

2 Preliminaries

In this section, we present here the definitions, some lemmas from the theory of fractional calculus, and some auxiliary results for the proof of our main results.

Definition 2.1 ([1]) The Riemann–Liouville fractional integral of order $\alpha > 0$ of a function $y : (0, \infty) \rightarrow \mathbb{R}$ is given by

$$(I_t^\alpha y)(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} y(s) ds, \quad t > 0,$$

provided that the right-hand side is pointwise defined on $[0, \infty)$, where Γ is the Euler gamma function defined as $\Gamma(\alpha) = \int_0^\infty t^{\alpha-1} e^{-t} dt$ for $\alpha > 0$.

Definition 2.2 ([1]) The Riemann–Liouville fractional derivative of order $\alpha \geq 0$ for a function $y : (0, \infty) \rightarrow \mathbb{R}$ is given by

$$(D_t^\alpha y)(t) = \frac{1}{\Gamma(n - \alpha)} \left(\frac{d}{dt} \right)^n \int_0^t y(s) (t - s)^{n-\alpha-1} ds, \quad t > 0,$$

where $n = [\alpha] + 1$, provided that the right-hand side is pointwise defined on $[0, \infty)$. The notation $[\alpha]$ stands for the largest integer not greater than α . We also denote the Riemann–Liouville fractional derivative of y by $D_t^\alpha y(t)$. If $\alpha = m \in \mathbb{N}$, then $D_t^m y(t) = y^{(m)}(t)$ for $t > 0$, and if $\alpha = 0$, then $D_t^0 y(t) = y(t)$ for $t > 0$.

Lemma 2.1 *Let $\alpha > 0$ and $n = [\alpha] + 1$ for $\alpha \notin \mathbb{N}$, that is, n is the smallest integer greater than or equal to α . Then the solutions of the fractional differential equation $D_t^\alpha u(t) = 0$, $0 < t < 1$, are*

$$u(t) = c_1 t^{\alpha-1} + c_2 t^{\alpha-2} + \dots + c_n t^{\alpha-n}, \quad 0 < t < 1,$$

where c_1, c_2, \dots, c_n are arbitrary real constants.

Lemma 2.2 *Let $\alpha > 0$, let n be the smallest integer greater than or equal to α ($n - 1 < \alpha \leq n$), and let $y \in L^1(0, 1)$. The solutions of the fractional equation $D_t^\alpha u(t) + y(t) = 0$, $0 < t < 1$, are*

$$u(t) = -\frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} y(s) ds + c_1 t^{\alpha-1} + \dots + c_n t^{\alpha-n}, \quad 0 < t < 1,$$

where c_1, c_2, \dots, c_n are arbitrary real constants.

Remark 2.1 The following properties are useful for our discussion:

- (i) As a basic example, we quote for $\alpha > -1$,

$$D_t^\gamma t^\alpha = \frac{\Gamma(\alpha + 1)}{\Gamma(\alpha - \gamma + 1)} t^{\alpha-\gamma};$$

- (ii) $D_t^\gamma I_t^\gamma u(t) = u(t)$ for $u \in L^1(0, 1)$, $\gamma > 0$;
- (iii) Assume that $u \in L^1(0, 1)$ with $\gamma > 0$, then

$$I_t^\gamma (D_t^\gamma u(t)) = u(t) + m_1 t^{\gamma-1} + m_2 t^{\gamma-2} + \dots + m_n t^{\gamma-n}$$

for some $m_i \in \mathbb{R}$, $i = 1, 2, \dots, n$, where n is the smallest integer greater than or equal to γ .

For convenience, we denote

$$\begin{cases} l_1 = \sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - s)^{\beta_2-1} s^{\alpha_1-1} ds + \sum_{j=1}^n b_j \eta_j^{\alpha_1-1}, \\ l_2 = \sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1-1} s^{\alpha_2-1} ds + \sum_{j=1}^n b_j \eta_j^{\alpha_2-1}. \end{cases} \tag{2.1}$$

In the forthcoming analysis, we always need the following assumptions:

- (F₁) $2 < \alpha_k < 3$, $1 < \beta_k \leq 2$, and $0 < \gamma_k < \alpha_k - 2$ for $k = 1, 2$;
- (F₂) $0 < \eta_j$, $\xi_i < 1$, $b_j \geq 0$, and $\lambda_{1i}, \lambda_{2i} > 0$ for $i = 1, 2, \dots, m$, $j = 1, 2, \dots, n$;
- (F₃) $1 - l_1 l_2 > 0$, where l_1, l_2 are defined by (2.1);
- (F₄) $f_i : [0, 1] \times [0, +\infty)^4 \rightarrow [0, +\infty)$, $i = 1, 2$, are continuous functions.

Subject to BVP (1.1) and (1.2), we consider the corresponding linear boundary value problem as follows and establish expressions of the corresponding Green’s functions.

Lemma 2.3 Assume that (F₁)–(F₃) hold. For $h_1, h_2 \in L^1(0, 1)$, the fractional differential system

$$\begin{cases} D_t^{\alpha_1} u(t) + h_1(t) = 0, & t \in (0, 1), \\ D_t^{\alpha_2} v(t) + h_2(t) = 0, & t \in (0, 1), \end{cases} \tag{2.2}$$

with boundary conditions (1.2) has the integral representation

$$\begin{cases} u(t) = \int_0^1 K_1(t, s)h_1(s) ds + \int_0^1 H_1(t, s)h_2(s) ds, \\ v(t) = \int_0^1 K_2(t, s)h_2(s) ds + \int_0^1 H_2(t, s)h_1(s) ds, \end{cases} \tag{2.3}$$

where

$$K_1(t, s) = g_1(t, s) + \frac{l_2 t^{\alpha_1 - 1}}{1 - l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau + \sum_{j=1}^n b_j g_1(\eta_j, s) \right], \tag{2.4}$$

$$H_1(t, s) = \frac{t^{\alpha_1 - 1}}{1 - l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} g_2(\tau, s) d\tau + \sum_{j=1}^n b_j g_2(\eta_j, s) \right],$$

$$K_2(t, s) = g_2(t, s) + \frac{l_1 t^{\alpha_2 - 1}}{1 - l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} g_2(\tau, s) d\tau + \sum_{j=1}^n b_j g_2(\eta_j, s) \right], \tag{2.5}$$

$$H_2(t, s) = \frac{t^{\alpha_2 - 1}}{1 - l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau + \sum_{j=1}^n b_j g_1(\eta_j, s) \right],$$

and for $k = 1, 2$,

$$g_k(t, s) = \frac{1}{\Gamma(\alpha_k)} \begin{cases} t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1} - (t - s)^{\alpha_k - 1}, & 0 \leq s \leq t \leq 1, \\ t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1}, & 0 \leq t \leq s \leq 1. \end{cases} \tag{2.6}$$

Proof From Lemma 2.2 we can reduce (2.2) and (1.2) to the following equivalent integral equations:

$$\begin{cases} u(t) = - \int_0^t \frac{(t-s)^{\alpha_1 - 1}}{\Gamma(\alpha_1)} h_1(s) ds + c_{11} t^{\alpha_1 - 1} + c_{12} t^{\alpha_1 - 2} + c_{13} t^{\alpha_1 - 3}, \\ v(t) = - \int_0^t \frac{(t-s)^{\alpha_2 - 1}}{\Gamma(\alpha_2)} h_2(s) ds + c_{21} t^{\alpha_2 - 1} + c_{22} t^{\alpha_2 - 2} + c_{23} t^{\alpha_2 - 3}, \end{cases} \tag{2.7}$$

where $c_{12}, c_{13}, c_{22}, c_{23}$ are constants.

From $u(0) = u'(0) = v(0) = v'(0) = 0$ we have $c_{12} = c_{13} = c_{22} = c_{23} = 0$. Further, we use the right-hand side boundary conditions of (1.2) to reduce (2.7) to

$$\begin{cases} u(t) = t^{\alpha_1 - 1} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1 - 1} v(s) ds + \sum_{j=1}^n b_j v(\eta_j) \right] + \int_0^1 g_1(t, s) h_1(s) ds, \\ v(t) = t^{\alpha_2 - 1} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - s)^{\beta_2 - 1} u(s) ds + \sum_{j=1}^n b_j u(\eta_j) \right] + \int_0^1 g_2(t, s) h_2(s) ds. \end{cases} \tag{2.8}$$

Then we can get

$$\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1 - 1} v(s) ds + \sum_{j=1}^n b_j v(\eta_j)$$

$$\begin{aligned}
 &= \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - s)^{\beta_2-1} u(s) ds + \sum_{j=1}^n b_j u(\eta_j) \right] \\
 &\quad \times \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1-1} s^{\alpha_2-1} ds + \sum_{j=1}^n b_j \eta_j^{\alpha_2-1} \right] \\
 &\quad + \sum_{j=1}^n b_j \int_0^1 g_2(\eta_j, s) h_2(s) ds \\
 &\quad + \sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \int_0^1 g_2(\tau, s) h_2(s) ds d\tau; \tag{2.9}
 \end{aligned}$$

$$\begin{aligned}
 &\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - s)^{\beta_2-1} u(s) ds + \sum_{j=1}^n b_j u(\eta_j) \\
 &= \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1-1} v(s) ds + \sum_{j=1}^n b_j v(\eta_j) \right] \\
 &\quad \times \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - s)^{\beta_2-1} s^{\alpha_1-1} ds + \sum_{j=1}^n b_j \eta_j^{\alpha_1-1} \right] \\
 &\quad + \sum_{j=1}^n b_j \int_0^1 g_1(\eta_j, s) h_1(s) ds \\
 &\quad + \sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} \int_0^1 g_1(\tau, s) h_1(s) ds d\tau. \tag{2.10}
 \end{aligned}$$

Combining (2.1), (2.9), and (2.10), we can see that

$$\begin{aligned}
 &\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - s)^{\beta_1-1} v(s) ds + \sum_{j=1}^n b_j v(\eta_j) \\
 &= \frac{1}{1 - l_1 l_2} \left[\left(\sum_{j=1}^n b_j \int_0^1 g_2(\eta_j, s) h_2(s) ds \right. \right. \\
 &\quad + \sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \int_0^1 g_2(\tau, s) h_2(s) ds d\tau \Big) \\
 &\quad + l_2 \left(\sum_{j=1}^n b_j \int_0^1 g_1(\eta_j, s) h_1(s) ds \right. \\
 &\quad \left. \left. + \sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} \int_0^1 g_1(\tau, s) h_1(s) ds d\tau \right) \right], \tag{2.11}
 \end{aligned}$$

where l_k ($k = 1, 2$) are defined by (2.1). From (2.9) and (2.11) we have

$$\begin{aligned}
 u(t) &= \frac{t^{\alpha_1-1}}{1 - l_1 l_2} \left(\sum_{j=1}^n b_j \int_0^1 g_2(\eta_j, s) h_2(s) ds \right. \\
 &\quad \left. + \sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \int_0^1 g_2(\tau, s) h_2(s) ds d\tau \right)
 \end{aligned}$$

$$\begin{aligned}
 & + \frac{l_2 t^{\alpha_1 - 1}}{1 - l_1 l_2} \left(\sum_{j=1}^n b_j \int_0^1 g_1(\eta_j, s) h_1(s) ds \right. \\
 & + \left. \sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} \int_0^1 g_1(\tau, s) h_1(s) ds d\tau \right) \\
 & + \int_0^1 g_1(t, s) h_1(s) ds \\
 & = \int_0^1 \left[g_1(t, s) + \frac{l_2 t^{\alpha_1 - 1}}{1 - l_1 l_2} \left(\sum_{j=1}^n b_j g_1(\eta_j, s) + \sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau \right) \right] \\
 & \quad \times h_1(s) ds \\
 & + \int_0^1 \frac{t^{\alpha_1 - 1}}{1 - l_1 l_2} \left(\sum_{j=1}^n b_j g_2(\eta_j, s) + \sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} g_2(\tau, s) d\tau \right) h_2(s) ds \\
 & = \int_0^1 K_1(t, s) h_1(s) ds + \int_0^1 H_1(t, s) h_2(s) ds.
 \end{aligned}$$

Similarly, we obtain

$$v(t) = \int_0^1 K_2(t, s) h_2(s) ds + \int_0^1 H_2(t, s) h_1(s) ds,$$

where $K_2(t, s)$ and $H_2(t, s)$ are given by (2.5).

This completes the proof of the lemma. □

Moreover, according to (2.3) and Remark 2.1, the fractional-order derivative of the solution (2.3) can be expressed as

$$\begin{cases} D_t^{\gamma_1} u(t) = \int_0^1 K_3(t, s) h_1(s) ds + \int_0^1 H_3(t, s) h_2(s) ds, \\ D_t^{\gamma_2} v(t) = \int_0^1 K_4(t, s) h_2(s) ds + \int_0^1 H_4(t, s) h_1(s) ds, \end{cases} \tag{2.12}$$

where

$$\begin{aligned}
 K_3(t, s) & = D_t^{\gamma_1} g_1(t, s) + \frac{l_2 t^{\alpha_1 - \gamma_1 - 1} \Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau \right. \\
 & \quad \left. + \sum_{j=1}^n b_j g_1(\eta_j, s) \right], \\
 H_3(t, s) & = \frac{\Gamma(\alpha_1) t^{\alpha_1 - \gamma_1 - 1}}{\Gamma(\alpha_1 - \gamma_1)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} g_2(\tau, s) d\tau \right. \\
 & \quad \left. + \sum_{j=1}^n b_j g_2(\eta_j, s) \right], \tag{2.13}
 \end{aligned}$$

$$K_4(t, s) = D_t^{\gamma_2} g_2(t, s) + \frac{l_1 t^{\alpha_2 - \gamma_2 - 1} \Gamma(\alpha_2)}{\Gamma(\alpha_2 - \gamma_2)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} g_2(\tau, s) d\tau \right.$$

$$\begin{aligned}
 & + \sum_{j=1}^n b_j g_2(\eta_j, s) \Big], \\
 H_4(t, s) &= \frac{\Gamma(\alpha_2) t^{\alpha_2 - \gamma_2 - 1}}{\Gamma(\alpha_2 - \gamma_2)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau + \sum_{j=1}^n b_j g_1(\eta_j, s) \right],
 \end{aligned}$$

and for $k, j = 1, 2$,

$$D_t^{\gamma_j} g_k(t, s) = \frac{1}{\Gamma(\alpha_k - \gamma_j)} \begin{cases} t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1} - (t - s)^{\alpha_k - \gamma_j - 1}, & 0 \leq s \leq t \leq 1, \\ t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1}, & 0 \leq t \leq s \leq 1. \end{cases} \tag{2.14}$$

Lemma 2.4 Assume that (E_1) holds. Then the functions $g_k(t, s)$ and $D_t^{\gamma_j} g_k(t, s)$, $k, j = 1, 2$, defined by (2.6) and (2.14) have the following properties:

- (1) $0 \leq g_k(t, s) \leq \frac{1}{\Gamma(\alpha_k)} t^{\alpha_k - 1} [(1 - s)^{\alpha_k - 1} + 1]$ for $t, s \in [0, 1]$;
- (2) $|D_t^{\gamma_j} g_k(t, s)| \leq \frac{1}{\Gamma(\alpha_k - \gamma_j)} t^{\alpha_k - \gamma_j - 1} [(1 - s)^{\alpha_k - 1} + 1]$ for $t, s \in [0, 1]$.

Proof (1) For $0 \leq s \leq t \leq 1$, we have

$$\begin{aligned}
 g_k(t, s) &= \frac{1}{\Gamma(\alpha_k)} (t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1} - (t - s)^{\alpha_k - 1}) \\
 &= \frac{1}{\Gamma(\alpha_k)} ((t - ts)^{\alpha_k - 1} - (t - s)^{\alpha_k - 1}) \\
 &\geq 0, \\
 g_k(t, s) &= \frac{1}{\Gamma(\alpha_k)} (t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1} - (t - s)^{\alpha_k - 1}) \\
 &\leq \frac{1}{\Gamma(\alpha_k)} t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1} \\
 &\leq \frac{1}{\Gamma(\alpha_k)} t^{\alpha_k - 1} [(1 - s)^{\alpha_k - 1} + 1].
 \end{aligned}$$

For $0 \leq t \leq s \leq 1$, we have

$$0 \leq g_k(t, s) = \frac{1}{\Gamma(\alpha_k)} t^{\alpha_k - 1} (1 - s)^{\alpha_k - 1} \leq \frac{1}{\Gamma(\alpha_k)} t^{\alpha_k - 1} [(1 - s)^{\alpha_k - 1} + 1].$$

(2) For $0 \leq s \leq t \leq 1$, we get

$$\begin{aligned}
 |D_t^{\gamma_j} g_k(t, s)| &= \left| \frac{1}{\Gamma(\alpha_k - \gamma_j)} [t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1} - (t - s)^{\alpha_k - \gamma_j - 1}] \right| \\
 &\leq \frac{1}{\Gamma(\alpha_k - \gamma_j)} [t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1} + (t - s)^{\alpha_k - \gamma_j - 1}] \\
 &\leq \frac{1}{\Gamma(\alpha_k - \gamma_j)} [t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1} + t^{\alpha_k - \gamma_j - 1}] \\
 &= \frac{1}{\Gamma(\alpha_k - \gamma_j)} t^{\alpha_k - \gamma_j - 1} [(1 - s)^{\alpha_k - 1} + 1].
 \end{aligned}$$

For $0 \leq t \leq s \leq 1$, we get

$$\begin{aligned} |D_t^{\gamma_j} g_k(t, s)| &= \frac{1}{\Gamma(\alpha_k - \gamma_j)} t^{\alpha_k - \gamma_j - 1} (1 - s)^{\alpha_k - 1} \\ &\leq \frac{1}{\Gamma(\alpha_k - \gamma_j)} t^{\alpha_k - \gamma_j - 1} [(1 - s)^{\alpha_k - 1} + 1]. \end{aligned}$$

This completes the proof of the lemma. □

For convenience, we denote

$$\varrho_1 = \frac{1}{\Gamma(\alpha_1)} \left[1 + \frac{l_2}{1 - l_1 l_2} \left(\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} \tau^{\alpha_1 - 1} d\tau + \sum_{j=1}^n b_j \eta_j^{\alpha_1 - 1} \right) \right], \tag{2.15}$$

$$\varrho_2 = \frac{1}{\Gamma(\alpha_2)} \left[1 + \frac{l_1}{1 - l_1 l_2} \left(\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} \tau^{\alpha_2 - 1} d\tau + \sum_{j=1}^n b_j \eta_j^{\alpha_2 - 1} \right) \right], \tag{2.16}$$

$$\rho_1 = \frac{1}{\Gamma(\alpha_2)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1 - 1} \tau^{\alpha_2 - 1} d\tau + \sum_{j=1}^n b_j \eta_j^{\alpha_2 - 1} \right], \tag{2.17}$$

$$\rho_2 = \frac{1}{\Gamma(\alpha_1)(1 - l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} \tau^{\alpha_1 - 1} d\tau + \sum_{j=1}^n b_j \eta_j^{\alpha_1 - 1} \right]. \tag{2.18}$$

Lemma 2.5 Assume that (F_1) – (F_3) hold. Then for $(t, s) \in [0, 1] \times [0, 1]$, the functions $K_i(t, s)$ and $H_i(t, s)$, $i = 1, 2, 3, 4$, defined by (2.4), (2.5), and (2.13) satisfy the following inequalities:

- (1) $0 \leq K_1(t, s) \leq t^{\alpha_1 - 1} [(1 - s)^{\alpha_1 - 1} + 1] \varrho_1,$
 $0 \leq K_2(t, s) \leq t^{\alpha_2 - 1} [(1 - s)^{\alpha_2 - 1} + 1] \varrho_2,$
 $|K_3(t, s)| \leq \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} t^{\alpha_1 - \gamma_1 - 1} [(1 - s)^{\alpha_1 - 1} + 1] \varrho_1,$
 $|K_4(t, s)| \leq \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2 - \gamma_2)} t^{\alpha_2 - \gamma_2 - 1} [(1 - s)^{\alpha_2 - 1} + 1] \varrho_2;$
- (2) $0 \leq H_1(t, s) \leq t^{\alpha_1 - 1} [(1 - s)^{\alpha_2 - 1} + 1] \rho_1,$
 $0 \leq H_2(t, s) \leq t^{\alpha_2 - 1} [(1 - s)^{\alpha_1 - 1} + 1] \rho_2,$
 $0 \leq H_3(t, s) \leq \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} t^{\alpha_1 - \gamma_1 - 1} [(1 - s)^{\alpha_2 - 1} + 1] \rho_1,$
 $0 \leq H_4(t, s) \leq \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2 - \gamma_2)} t^{\alpha_2 - \gamma_2 - 1} [(1 - s)^{\alpha_1 - 1} + 1] \rho_2.$

Proof (1) According to (F_3) , Lemma 2.4, and the definition of $K_i(t, s)$, we obtain

$$\begin{aligned} 0 \leq K_1(t, s) &= g_1(t, s) + \frac{l_2 t^{\alpha_1 - 1}}{1 - l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2 - 1} g_1(\tau, s) d\tau + \sum_{j=1}^n b_j g_1(\eta_j, s) \right] \\ &\leq \frac{1}{\Gamma(\alpha_1)} t^{\alpha_1 - 1} [(1 - s)^{\alpha_1 - 1} + 1] \end{aligned}$$

$$\begin{aligned}
 & + \frac{l_2 t^{\alpha_1-1}}{1-l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)\Gamma(\alpha_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} \tau^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] d\tau \right. \\
 & \left. + \frac{1}{\Gamma(\alpha_1)} \sum_{j=1}^n b_j \eta_j^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] \right] \\
 & = t^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] \frac{1}{\Gamma(\alpha_1)} \left[1 + \frac{l_2}{1-l_1 l_2} \left(\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} \tau^{\alpha_1-1} d\tau \right. \right. \\
 & \left. \left. + \sum_{j=1}^n b_j \eta_j^{\alpha_1-1} \right) \right] \\
 & = t^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] \varrho_1
 \end{aligned}$$

and

$$\begin{aligned}
 |K_3(t, s)| & = \left| D_t^{\gamma_1} g_1(t, s) + \frac{l_2 t^{\alpha_1-\gamma_1-1} \Gamma(\alpha_1)}{\Gamma(\alpha_1-\gamma_1)(1-l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} g_1(\tau, s) d\tau \right. \right. \\
 & \left. \left. + \sum_{j=1}^n b_j g_1(\eta_j, s) \right] \right| \\
 & \leq \frac{1}{\Gamma(\alpha_1-\gamma_1)} t^{\alpha_1-\gamma_1-1} [(1-s)^{\alpha_1-1} + 1] \\
 & \quad + \frac{l_2 t^{\alpha_1-\gamma_1-1} \Gamma(\alpha_1)}{\Gamma(\alpha_1-\gamma_1)(1-l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{2i}}{\Gamma(\beta_2)\Gamma(\alpha_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_2-1} \right. \\
 & \quad \left. \times \tau^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] d\tau + \frac{1}{\Gamma(\alpha_1)} \sum_{j=1}^n b_j \eta_j^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] \right] \\
 & \leq \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1-\gamma_1)} t^{\alpha_1-\gamma_1-1} [(1-s)^{\alpha_1-1} + 1] \varrho_1,
 \end{aligned}$$

where ϱ_1 is defined by (2.15).

Similarly, we get

$$\begin{aligned}
 0 \leq K_2(t, s) & \leq t^{\alpha_2-1} [(1-s)^{\alpha_2-1} + 1] \varrho_2, \\
 |K_4(t, s)| & \leq \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2-\gamma_2)} t^{\alpha_2-\gamma_2-1} [(1-s)^{\alpha_2-1} + 1] \varrho_2,
 \end{aligned}$$

where ϱ_2 is defined by (2.16).

(2) According to (F₃), Lemma 2.4, and the definition of $H_k(t, s)$ ($k = 1, 2, 3, 4$), we infer that

$$\begin{aligned}
 0 \leq H_1(t, s) & = \frac{t^{\alpha_1-1}}{1-l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} g_2(\tau, s) d\tau + \sum_{j=1}^n b_j g_2(\eta_j, s) \right] \\
 & \leq \frac{t^{\alpha_1-1}}{1-l_1 l_2} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)\Gamma(\alpha_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \tau^{\alpha_2-1} [(1-s)^{\alpha_2-1} + 1] d\tau \right.
 \end{aligned}$$

$$\begin{aligned}
 & + \frac{1}{\Gamma(\alpha_2)} \sum_{j=1}^n b_j \eta_j^{\alpha_2-1} [(1-s)^{\alpha_2-1} + 1] \Big] \\
 = & t^{\alpha_1-1} [(1-s)^{\alpha_2-1} + 1] \frac{1}{\Gamma(\alpha_2)(1-l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \tau^{\alpha_2-1} d\tau \right. \\
 & \left. + \sum_{j=1}^n b_j \eta_j^{\alpha_2-1} \right] \\
 = & t^{\alpha_1-1} [(1-s)^{\alpha_2-1} + 1] \rho_1
 \end{aligned}$$

and

$$\begin{aligned}
 0 & \leq H_3(t, s) \\
 = & \frac{\Gamma(\alpha_1)t^{\alpha_1-\gamma_1-1}}{\Gamma(\alpha_1-\gamma_1)(1-l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} g_2(\tau, s) d\tau + \sum_{j=1}^n b_j g_2(\eta_j, s) \right] \\
 \leq & \frac{\Gamma(\alpha_1)t^{\alpha_1-\gamma_1-1}}{\Gamma(\alpha_1-\gamma_1)(1-l_1 l_2)} \left[\sum_{i=1}^m \frac{\lambda_{1i}}{\Gamma(\beta_1)\Gamma(\alpha_2)} \int_0^{\xi_i} (\xi_i - \tau)^{\beta_1-1} \tau^{\alpha_2-1} [(1-s)^{\alpha_2-1} + 1] d\tau \right. \\
 & \left. + \frac{1}{\Gamma(\alpha_2)} \sum_{j=1}^n b_j \eta_j^{\alpha_2-1} [(1-s)^{\alpha_2-1} + 1] \right] \\
 = & \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1-\gamma_1)} t^{\alpha_1-\gamma_1-1} [(1-s)^{\alpha_2-1} + 1] \rho_1,
 \end{aligned}$$

where ρ_1 is defined by (2.17). Analogously, we get

$$\begin{aligned}
 0 & \leq H_2(t, s) \leq t^{\alpha_2-1} [(1-s)^{\alpha_1-1} + 1] \rho_2, \\
 0 & \leq H_4(t, s) \leq \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2-\gamma_2)} t^{\alpha_2-\gamma_2-1} [(1-s)^{\alpha_1-1} + 1] \rho_2,
 \end{aligned}$$

where ρ_2 is defined by (2.18).

This completes the proof of the lemma. □

Let $X = \{u | u \in C[0, 1] \text{ and } D_t^{\gamma_1} u \in C[0, 1]\}$ be endowed with the norm

$$\|u\| = \max\{\|u\|_0, \|D_t^{\gamma_1} u\|_0\},$$

where $\|u\|_0 = \max_{t \in [0,1]} |u(t)|$ and $\|D_t^{\gamma_1} u\|_0 = \max_{t \in [0,1]} |D_t^{\gamma_1} u(t)|$. Also let $Y = \{v | v \in C[0, 1] \text{ and } D_t^{\gamma_2} v \in C[0, 1]\}$ be endowed with the norm

$$\|v\| = \max\{\|v\|_0, \|D_t^{\gamma_2} v\|_0\},$$

where $\|v\|_0 = \max_{t \in [0,1]} |v(t)|$ and $\|D_t^{\gamma_2} v\|_0 = \max_{t \in [0,1]} |D_t^{\gamma_2} v(t)|$. We introduce the product space $(X \times Y, \|(u, v)\|)$ endowed with the norm $\|(u, v)\| = \max\{\|u\|, \|v\|\}$ and define a partial order over the product space:

$$\begin{pmatrix} u_1 \\ v_1 \end{pmatrix} \geq \begin{pmatrix} u_2 \\ v_2 \end{pmatrix}$$

if $u_1(t) \geq u_2(t)$, $v_1(t) \geq v_2(t)$, $D_t^{\gamma_1} u_1(t) \geq D_t^{\gamma_1} u_2(t)$, and $D_t^{\gamma_2} v_1(t) \geq D_t^{\gamma_2} v_2(t)$, $t \in [0, 1]$.

Lemma 2.6 $(X \times Y, \|(u, v)\|)$ is a Banach space.

Proof Let $\{u_n\}_{n=1}^\infty$ be a Cauchy sequence in the space $(X, \|\cdot\|)$. It is obvious that $\{u_n\}_{n=1}^\infty$ and $\{D_t^{\gamma_1} u_n\}_{n=1}^\infty$ are Cauchy sequences in the space $C[0, 1]$. Let us assume that $\{u_n\}_{n=1}^\infty$ and $\{D_t^{\gamma_1} u_n\}_{n=1}^\infty$ uniformly converge on $[0, 1]$ to $u \in C[0, 1]$ and $w \in C[0, 1]$. Now we should prove that $w = D_t^{\gamma_1} u$.

For $t \in [0, 1]$, we have

$$\begin{aligned} |I_t^{\gamma_1} D_t^{\gamma_1} u_n(t) - I_t^{\gamma_1} w(t)| &\leq \frac{1}{\Gamma(\gamma_1)} \int_0^t (t-s)^{\gamma_1-1} |D_t^{\gamma_1} u_n(s) - w(s)| ds \\ &\leq \frac{1}{\Gamma(\gamma_1 + 1)} \max_{s \in [0,1]} |D_t^{\gamma_1} u_n(s) - w(s)|. \end{aligned}$$

In view of the convergence of $\{u_n\}_{n=1}^\infty$, we obtain that $\lim_{n \rightarrow \infty} I_t^{\gamma_1} D_t^{\gamma_1} u_n(t) = I_t^{\gamma_1} w(t)$ uniformly for $t \in [0, 1]$. Otherwise, by Remark 2.1 we have $I_t^{\gamma_1} D_t^{\gamma_1} u_n(t) = u_n(t)$ for $t \in [0, 1]$. These two facts imply that

$$\lim_{n \rightarrow \infty} I_t^{\gamma_1} D_t^{\gamma_1} u_n(t) = \lim_{n \rightarrow \infty} u_n(t) = I_t^{\gamma_1} w(t) \quad \text{for } t \in [0, 1].$$

Combining this with $\lim_{n \rightarrow \infty} u_n(t) = u(t)$ for $t \in [0, 1]$, we have

$$u(t) = I_t^{\gamma_1} w(t) \quad \text{for } t \in [0, 1]. \tag{2.19}$$

Taking the γ_1 -th-order derivatives of both sides of equation (2.19), in consequence, we have

$$D_t^{\gamma_1} I_t^{\gamma_1} w(t) = D_t^{\gamma_1} u(t) \quad \text{for } t \in [0, 1].$$

By Remark 2.1 this leads to

$$w(t) = D_t^{\gamma_1} u(t) \quad \text{for } t \in [0, 1],$$

which proves that $(X, \|\cdot\|)$ is a Banach space.

In the same way, we can prove that $(Y, \|\cdot\|)$ is a Banach space. Moreover, the product space $(X \times Y, \|(u, v)\|)$ is also a Banach space with the norm $\|(u, v)\| = \max\{\|u\|, \|v\|\}$.

The proof of the lemma is completed. □

Further, we define the cone $P \subset X \times Y$ by $P = \{(u, v) \in X \times Y : u(t) \geq 0, v(t) \geq 0, D_t^{\gamma_1} u(t) \geq 0, D_t^{\gamma_2} v(t) \geq 0, t \in [0, 1]\}$. For all $(u, v) \in P$, in view of Lemma 2.3 and (E_4) , let $T: P \rightarrow P$ be the operator defined by

$$T(u, v)(t) = \begin{pmatrix} T_1(u, v)(t) \\ T_2(u, v)(t) \end{pmatrix},$$

where

$$T_1(u, v)(t) = \int_0^1 K_1(t, s) f_{1(u,v)}(s) ds + \int_0^1 H_1(t, s) f_{2(u,v)}(s) ds, \tag{2.20}$$

$$T_2(u, v)(t) = \int_0^1 K_2(t, s)f_{2(u,v)}(s) ds + \int_0^1 H_2(t, s)f_{1(u,v)}(s) ds, \tag{2.21}$$

and for convenience, we set

$$\begin{cases} f_{1(u,v)}(s) \triangleq f_1(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)), \\ f_{2(u,v)}(s) \triangleq f_2(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)). \end{cases}$$

Also, from (2.12) we have

$$D_t^{\gamma_1} T_1(u, v)(t) = \int_0^1 K_3(t, s)f_{1(u,v)}(s) ds + \int_0^1 H_3(t, s)f_{2(u,v)}(s) ds, \tag{2.22}$$

$$D_t^{\gamma_2} T_2(u, v)(t) = \int_0^1 K_4(t, s)f_{2(u,v)}(s) ds + \int_0^1 H_4(t, s)f_{1(u,v)}(s) ds. \tag{2.23}$$

Lemma 2.7 *The operator $T : P \rightarrow P$ is completely continuous.*

Proof By the continuity of the functions $K_1(t, s) - K_4(t, s)$, $H_1(t, s) - H_4(t, s)$, and f_1 and f_2 the operator T is continuous.

Then we show T is uniformly bounded. Let $\Omega \subset P$ be bounded. There exists a positive constant M satisfying the inequality

$$\max\{|f_{1(u,v)}(t)|, |f_{2(u,v)}(t)|\} \leq M, \quad \forall (u, v) \in \Omega. \tag{2.24}$$

For any $(u, v) \in \Omega$, combining Lemma 2.5 with (2.20), (2.22), and (2.24), we get

$$\begin{aligned} |T_1(u, v)(t)| &\leq \left| M \int_0^1 K_1(t, s) ds + M \int_0^1 H_1(t, s) ds \right| \\ &\leq M \int_0^1 \{t^{\alpha_1-1} [(1-s)^{\alpha_1-1} + 1] \varrho_1 + t^{\alpha_1-1} [(1-s)^{\alpha_2-1} + 1] \rho_1\} ds \\ &\leq M \int_0^1 \{[(1-s)^{\alpha_1-1} + 1] \varrho_1 + [(1-s)^{\alpha_2-1} + 1] \rho_1\} ds \end{aligned}$$

and

$$\begin{aligned} |D_t^{\gamma_1} T_1(u, v)(t)| &\leq \left| M \int_0^1 K_3(t, s) ds + M \int_0^1 H_3(t, s) ds \right| \\ &\leq \frac{M\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} \int_0^1 \{t^{\alpha_1-\gamma_1-1} [(1-s)^{\alpha_1-1} + 1] \varrho_1 + t^{\alpha_1-\gamma_1-1} [(1-s)^{\alpha_2-1} + 1] \rho_1\} ds \\ &\leq \frac{M\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} \int_0^1 \{[(1-s)^{\alpha_1-1} + 1] \varrho_1 + [(1-s)^{\alpha_2-1} + 1] \rho_1\} ds, \end{aligned}$$

which implies that $\|T_1(u, v)\|$ is uniformly bounded. Further, we get that $\|T_2(u, v)\|$ is also uniformly bounded. Thus it follows from the above inequalities that the operator T is uniformly bounded.

Next, we show that T is equicontinuous. For any $(u, v) \in \Omega$ and $t_1, t_2 \in [0, 1]$, in view of Lemma 2.5, (2.20), (2.22), and (2.24), we infer that

$$\begin{aligned} &|T_1(u, v)(t_2) - T_1(u, v)(t_1)| \\ &\leq \left| M \int_0^1 (K_1(t_2, s) - K_1(t_1, s)) ds \right| + \left| M \int_0^1 (H_1(t_2, s) - H_1(t_1, s)) ds \right| \\ &\leq M \int_0^1 \{ |(t_2^{\alpha_1-1} - t_1^{\alpha_1-1})[(1-s)^{\alpha_1-1} + 1]| \varrho_1 \\ &\quad + |(t_2^{\alpha_2-1} - t_1^{\alpha_2-1})[(1-s)^{\alpha_2-1} + 1]| \rho_1 \} ds. \end{aligned}$$

Applying the mean value theorem, we have the inequality

$$t_2^{\alpha-1} - t_1^{\alpha-1} \leq (\alpha - 1)|t_2 - t_1|.$$

This implies that

$$\begin{aligned} &|T_1(u, v)(t_2) - T_1(u, v)(t_1)| \\ &\leq M \int_0^1 \{ (\alpha_1 - 1)[(1-s)^{\alpha_1-1} + 1] \varrho_1 + (\alpha_1 - 1)[(1-s)^{\alpha_2-1} + 1] \rho_1 \} ds |t_2 - t_1| \\ &\rightarrow 0 \quad \text{as } t_2 \rightarrow t_1. \end{aligned}$$

Besides, we find

$$\begin{aligned} &|D_t^{\gamma_1} T_1(u, v)(t_2) - D_t^{\gamma_1} T_1(u, v)(t_1)| \\ &\leq \left| M \int_0^1 (K_3(t_2, s) - K_3(t_1, s)) ds \right| + \left| M \int_0^1 (H_3(t_2, s) - H_3(t_1, s)) ds \right| \\ &\leq \frac{M\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} \int_0^1 \{ (\alpha_1 - \gamma_1 - 1)[(1-s)^{\alpha_1-1} + 1] \varrho_1 \\ &\quad + (\alpha_1 - \gamma_1 - 1)[(1-s)^{\alpha_2-1} + 1] \rho_1 \} ds |t_2 - t_1| \\ &\rightarrow 0 \quad \text{as } t_2 \rightarrow t_1. \end{aligned}$$

Therefore T_1 is equicontinuous for all $(u, v) \in \Omega$, and thus T_2 is equicontinuous for all $(u, v) \in \Omega$.

As a consequence, the operator $T(u, v)$ is equicontinuous for all $(u, v) \in \Omega$. By the Arzelà–Ascoli theorem the operator $T(u, v)$ is completely continuous. □

3 Existence of monotone iterative positive solutions

Now, based on Lemmas 2.5–2.7, we will show that there exist positive extremal solutions for BVP (1.1)–(1.2) by the monotone iterative method.

Theorem 3.1 Assume that (F₁)–(F₄) hold. Let A₁, A₂, and l be three positive constants satisfying

$$l = \max \left\{ A_1 \int_0^1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \rho_1 ds, \right. \\ \left. A_1 \int_0^1 \rho_2 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 \varrho_2 [(1-s)^{\alpha_2-1} + 1] ds \right\}, \tag{3.1}$$

(S1) For $t \in [0, 1]$, $f_j(t, x_1, x_2, x_3, x_4)$ is increasing in $x_i \in [0, l]$ ($i = 1, 2, 3, 4$) for $j = 1, 2$;

(S2) $\max_{0 \leq t \leq 1} f_i(t, l, l, l, l) \leq A_i, f_i(t, 0, 0, 0, 0) \neq 0, 0 \leq t \leq 1$, for $i = 1, 2$.

Then BVP (1.1)–(1.2) has positive solutions (u^*, v^*) and (w^*, z^*) satisfying $0 \leq \|(u^*, v^*)\| \leq l$, and $\lim_{n \rightarrow \infty} (u_n, v_n) = (u^*, v^*)$,

$$(u_n, v_n) = T(u_{n-1}, v_{n-1}) = \begin{pmatrix} T_1(u_{n-1}, v_{n-1}) \\ T_2(u_{n-1}, v_{n-1}) \end{pmatrix}, \quad n = 1, 2, \dots,$$

and

$$\begin{pmatrix} u_0(t) \\ v_0(t) \end{pmatrix} = \begin{pmatrix} t^{\alpha_1-1} \int_0^1 \{A_1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] + A_2 \rho_1 [(1-s)^{\alpha_2-1} + 1]\} ds \\ t^{\alpha_2-1} \int_0^1 \{A_1 \rho_2 [(1-s)^{\alpha_1-1} + 1] + A_2 \varrho_2 [(1-s)^{\alpha_2-1} + 1]\} ds \end{pmatrix}; \tag{3.2}$$

$0 \leq \|(w^*, z^*)\| \leq l$, and $\lim_{n \rightarrow \infty} (w_n, z_n) = (w^*, z^*)$,

$$(w_n, z_n) = T(w_{n-1}, z_{n-1}) = \begin{pmatrix} T_1(w_{n-1}, z_{n-1}) \\ T_2(w_{n-1}, z_{n-1}) \end{pmatrix}, \quad n = 1, 2, \dots,$$

and

$$\begin{pmatrix} w_0(t) \\ z_0(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}. \tag{3.3}$$

Proof Denote $P_l = \{(u, v) \in P \mid \|(u, v)\| \leq l\}$, where l is introduced by (3.1). In the following, we first prove that $T : P_l \rightarrow P_l$. Let $(u, v) \in P_l$. Then for $t \in [0, 1]$, we have

$$0 \leq u(t) \leq \|u\| \leq l, \quad 0 \leq |D_t^{\gamma_1} u(t)| \leq \|u\| \leq l, \\ 0 \leq v(t) \leq \|v\| \leq l, \quad 0 \leq |D_t^{\gamma_2} v(t)| \leq \|v\| \leq l.$$

So, for $0 \leq t \leq 1, i = 1, 2$, by (S1) and (S2) we get

$$0 \leq f_i(t, u(t), v(t), D_t^{\gamma_1} u(t), D_t^{\gamma_2} v(t)) \leq \max_{0 \leq t \leq 1} \{f_i(t, l, l, l, l)\} \leq A_i. \tag{3.4}$$

Consequently, for $t \in [0, 1]$, in view of Lemma 2.5 and (3.4), we have

$$T_1(u, v)(t) = \int_0^1 K_1(t, s) f_1(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \\ + \int_0^1 H_1(t, s) f_2(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds$$

$$\begin{aligned}
 &\leq A_1 \int_0^1 [(1-s)^{\alpha_1-1} + 1] \varrho_1 ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \rho_1 ds \leq l, \\
 |D_t^{\gamma_1} T_1(u, v)(t)| &= \left| \int_0^1 K_3(t, s) f_1(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \right. \\
 &\quad \left. + \int_0^1 H_3(t, s) f_2(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \right| \\
 &\leq A_1 \int_0^1 \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} [(1-s)^{\alpha_1-1} + 1] \varrho_1 ds \\
 &\quad + A_2 \int_0^1 \frac{\Gamma(\alpha_1)}{\Gamma(\alpha_1 - \gamma_1)} [(1-s)^{\alpha_2-1} + 1] \rho_1 ds \\
 &\leq A_1 \int_0^1 [(1-s)^{\alpha_1-1} + 1] \varrho_1 ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \rho_1 ds \leq l,
 \end{aligned}$$

and, further,

$$\begin{aligned}
 T_2(u, v)(t) &= \int_0^1 K_2(t, s) f_2(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \\
 &\quad + \int_0^1 H_2(t, s) f_1(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \\
 &\leq A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \varrho_2 ds + A_1 \int_0^1 [(1-s)^{\alpha_1-1} + 1] \rho_2 ds \leq l, \\
 |D_t^{\gamma_2} T_2(u, v)(t)| &= \left| \int_0^1 K_4(t, s) f_2(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \right. \\
 &\quad \left. + \int_0^1 H_4(t, s) f_1(s, u(s), v(s), D_t^{\gamma_1} u(s), D_t^{\gamma_2} v(s)) ds \right| \\
 &\leq A_2 \int_0^1 \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2 - \gamma_2)} [(1-s)^{\alpha_2-1} + 1] \varrho_2 ds \\
 &\quad + A_1 \int_0^1 \frac{\Gamma(\alpha_2)}{\Gamma(\alpha_2 - \gamma_2)} [(1-s)^{\alpha_1-1} + 1] \rho_2 ds \\
 &\leq A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \varrho_2 ds + A_1 \int_0^1 [(1-s)^{\alpha_1-1} + 1] \rho_2 ds \leq l.
 \end{aligned}$$

As a result, we obtain

$$\|T(u, v)\| = \left\{ \max_{0 \leq t \leq 1} |T_1 u(t)|, \max_{0 \leq t \leq 1} |D_t^{\gamma_1} T_1 u(t)|, \max_{0 \leq t \leq 1} |T_2 v(t)|, \max_{0 \leq t \leq 1} |D_t^{\gamma_2} T_2 v(t)| \right\} \leq l,$$

and thus $T : P_l \rightarrow P_l$.

According to (3.2) and (3.3), it is obvious that $(u_0, v_0), (w_0, z_0) \in P_l$. Using the completely continuous operator T , we define the sequences $\{(u_n, v_n)\}$ and $\{(w_n, z_n)\}$ as $(u_n, v_n) = T(u_{n-1}, v_{n-1}), (w_n, z_n) = T(w_{n-1}, z_{n-1})$ for $n = 1, 2, \dots$. Since $T : P_l \rightarrow P_l$, we get that $(u_n, v_n), (w_n, z_n) \in P_l$ for $n = 1, 2, \dots$.

Hence we prove that there exist (u^*, v^*) and (w^*, z^*) satisfying $\lim_{n \rightarrow \infty} (u_n, v_n) = (u^*, v^*)$ and $\lim_{n \rightarrow \infty} (w_n, z_n) = (w^*, z^*)$, which are monotone positive solutions of problem (1.1)–(1.2).

For $t \in [0, 1]$, by the definition of the iterative scheme we have

$$\begin{aligned}
 T_1(u_0, v_0)(t) &= \int_0^1 K_1(t, s)f_{1(u_0, v_0)}(s) ds + \int_0^1 H_1(t, s)f_{2(u_0, v_0)}(s) ds \\
 &\leq t^{\alpha_1-1} \int_0^1 \{A_1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] + A_2 \rho_1 [(1-s)^{\alpha_2-1} + 1]\} ds \\
 &= u_0(t)
 \end{aligned} \tag{3.5}$$

and

$$\begin{aligned}
 T_2(u_0, v_0)(t) &= \int_0^1 K_2(t, s)f_{2(u_0, v_0)}(s) ds + \int_0^1 H_2(t, s)f_{1(u_0, v_0)}(s) ds \\
 &\leq t^{\alpha_2-1} \int_0^1 \{A_1 \rho_2 [(1-s)^{\alpha_1-1} + 1] + A_2 \varrho_2 [(1-s)^{\alpha_2-1} + 1]\} ds \\
 &= v_0(t).
 \end{aligned} \tag{3.6}$$

From (3.5) and (3.6) we get

$$\begin{pmatrix} u_1(t) \\ v_1(t) \end{pmatrix} = \begin{pmatrix} T_1(u_0, v_0)(t) \\ T_2(u_0, v_0)(t) \end{pmatrix} \leq \begin{pmatrix} u_0(t) \\ v_0(t) \end{pmatrix}. \tag{3.7}$$

Next, we discuss the monotonicity of the fractional derivative of (u, v) . From (3.2) we obtain

$$\begin{aligned}
 D_t^{\gamma_1} u_0(t) &= \int_0^1 \frac{\Gamma(\alpha_1)t^{\alpha_1-\gamma_1-1}}{\Gamma(\alpha_1-\gamma_1)} \{A_1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] + A_2 \rho_1 [(1-s)^{\alpha_2-1} + 1]\} ds \geq 0, \\
 D_t^{\gamma_2} v_0(t) &= \int_0^1 \frac{\Gamma(\alpha_2)t^{\alpha_2-\gamma_2-1}}{\Gamma(\alpha_2-\gamma_2)} \{A_1 \rho_2 [(1-s)^{\alpha_1-1} + 1] + A_2 \varrho_2 [(1-s)^{\alpha_2-1} + 1]\} ds \geq 0.
 \end{aligned}$$

Hence we have

$$\begin{aligned}
 |D_t^{\gamma_1} u_1(t)| &= |D_t^{\gamma_1} T_1(u_0, v_0)(t)| \\
 &= \left| \int_0^1 K_3(t, s)f_{1(u_0, v_0)}(s) ds + \int_0^1 H_3(t, s)f_{2(u_0, v_0)}(s) ds \right| \\
 &\leq A_1 \int_0^1 \frac{\Gamma(\alpha_1)t^{\alpha_1-\gamma_1-1}}{\Gamma(\alpha_1-\gamma_1)} [(1-s)^{\alpha_1-1} + 1] \varrho_1 ds \\
 &\quad + A_2 \int_0^1 \frac{\Gamma(\alpha_1)t^{\alpha_1-\gamma_1-1}}{\Gamma(\alpha_1-\gamma_1)} [(1-s)^{\alpha_2-1} + 1] \rho_1 ds \\
 &= |D_t^{\gamma_1} u_0(t)|
 \end{aligned} \tag{3.8}$$

and

$$|D_t^{\gamma_2} v_1(t)| = |D_t^{\gamma_2} T_2(u_0, v_0)(t)|$$

$$\begin{aligned}
 &= \left| \int_0^1 K_4(t,s)f_{2(u_0,v_0)}(s) ds + \int_0^1 H_4(t,s)f_{1(u_0,v_0)}(s) ds \right| \\
 &\leq A_2 \int_0^1 \frac{\Gamma(\alpha_2)t^{\alpha_2-\gamma_2-1}}{\Gamma(\alpha_2-\gamma_2)} [(1-s)^{\alpha_2-1} + 1] \varrho_2 ds \\
 &\quad + A_1 \int_0^1 \frac{\Gamma(\alpha_2)t^{\alpha_2-\gamma_2-1}}{\Gamma(\alpha_2-\gamma_2)} [(1-s)^{\alpha_1-1} + 1] \rho_2 ds \\
 &= |D_t^{\gamma_2} v_0(t)|. \tag{3.9}
 \end{aligned}$$

Combining (3.8) and (3.9), we easily to see that

$$\begin{pmatrix} |D_t^{\gamma_1} u_1(t)| \\ |D_t^{\gamma_2} v_1(t)| \end{pmatrix} = \begin{pmatrix} |D_t^{\gamma_1} T_1(u_0, v_0)(t)| \\ |D_t^{\gamma_2} T_2(u_0, v_0)(t)| \end{pmatrix} \leq \begin{pmatrix} |D_t^{\gamma_1} u_0(t)| \\ |D_t^{\gamma_2} v_0(t)| \end{pmatrix}. \tag{3.10}$$

Thus, for $0 \leq t \leq 1$, from (3.7), (3.10), and (S1) we do the second iteration

$$\begin{aligned}
 \begin{pmatrix} u_2(t) \\ v_2(t) \end{pmatrix} &= \begin{pmatrix} T_1(u_1, v_1)(t) \\ T_2(u_1, v_1)(t) \end{pmatrix} \leq \begin{pmatrix} T_1(u_0, v_0)(t) \\ T_2(u_0, v_0)(t) \end{pmatrix} = \begin{pmatrix} u_1(t) \\ v_1(t) \end{pmatrix}, \\
 \begin{pmatrix} |D_t^{\gamma_1} u_2(t)| \\ |D_t^{\gamma_2} v_2(t)| \end{pmatrix} &= \begin{pmatrix} |D_t^{\gamma_1} T_1(u_1, v_1)(t)| \\ |D_t^{\gamma_2} T_2(u_1, v_1)(t)| \end{pmatrix} \leq \begin{pmatrix} |D_t^{\gamma_1} T_1(u_0, v_0)(t)| \\ |D_t^{\gamma_2} T_2(u_0, v_0)(t)| \end{pmatrix} = \begin{pmatrix} |D_t^{\gamma_1} u_1(t)| \\ |D_t^{\gamma_2} v_1(t)| \end{pmatrix}.
 \end{aligned}$$

By induction, for $n = 0, 1, 2, \dots$, we have

$$\begin{pmatrix} u_{n+1}(t) \\ v_{n+1}(t) \end{pmatrix} \leq \begin{pmatrix} u_n(t) \\ v_n(t) \end{pmatrix}, \quad \begin{pmatrix} |D_t^{\gamma_1} u_{n+1}(t)| \\ |D_t^{\gamma_2} v_{n+1}(t)| \end{pmatrix} \leq \begin{pmatrix} |D_t^{\gamma_1} u_n(t)| \\ |D_t^{\gamma_2} v_n(t)| \end{pmatrix} \quad \text{for } 0 \leq t \leq 1.$$

So we assert that $(u_n, v_n) \rightarrow (u^*, v^*)$ and $T(u^*, v^*) = (u^*, v^*)$, since T is completely continuous and $(u_{n+1}, v_{n+1}) = T(u_n, v_n)$.

For the sequence $\{(w_n, z_n)\}_{n=1}^\infty$, we apply a similar argument. For $t \in [0, 1]$, we have

$$\begin{aligned}
 \begin{pmatrix} w_1(t) \\ z_1(t) \end{pmatrix} &= \begin{pmatrix} T_1(w_0, z_0)(t) \\ T_2(w_0, z_0)(t) \end{pmatrix} \\
 &= \begin{pmatrix} \int_0^1 K_1(t,s)f_{1(w_0,z_0)}(s) ds + \int_0^1 H_1(t,s)f_{2(w_0,z_0)}(s) ds \\ \int_0^1 K_2(t,s)f_{2(w_0,z_0)}(s) ds + \int_0^1 H_2(t,s)f_{1(w_0,z_0)}(s) ds \end{pmatrix} \\
 &\geq \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} w_0(t) \\ z_0(t) \end{pmatrix}; \\
 \begin{pmatrix} |D_t^{\gamma_1} w_1(t)| \\ |D_t^{\gamma_2} z_1(t)| \end{pmatrix} &= \begin{pmatrix} |D_t^{\gamma_1} T_1(w_0, z_0)(t)| \\ |D_t^{\gamma_2} T_2(w_0, z_0)(t)| \end{pmatrix} \\
 &= \begin{pmatrix} \int_0^1 K_3(t,s)f_{1(w_0,z_0)}(s) ds + \int_0^1 H_3(t,s)f_{2(w_0,z_0)}(s) ds \\ \int_0^1 K_4(t,s)f_{2(w_0,z_0)}(s) ds + \int_0^1 H_4(t,s)f_{1(w_0,z_0)}(s) ds \end{pmatrix} \\
 &\geq \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} |D_t^{\gamma_1} w_0(t)| \\ |D_t^{\gamma_2} z_0(t)| \end{pmatrix}.
 \end{aligned}$$

To summarize, for $0 \leq t \leq 1$, we have

$$\begin{pmatrix} w_2(t) \\ z_2(t) \end{pmatrix} = \begin{pmatrix} T_1(w_1, z_1)(t) \\ T_2(w_1, z_1)(t) \end{pmatrix} \geq \begin{pmatrix} T_1(w_0, z_0)(t) \\ T_2(w_0, z_0)(t) \end{pmatrix} = \begin{pmatrix} w_1(t) \\ z_1(t) \end{pmatrix},$$

$$\begin{pmatrix} |D_t^{\gamma_1} w_2(t)| \\ |D_t^{\gamma_2} z_2(t)| \end{pmatrix} = \begin{pmatrix} |D_t^{\gamma_1} T_1(w_1, z_1)(t)| \\ |D_t^{\gamma_2} T_2(w_1, z_1)(t)| \end{pmatrix} \geq \begin{pmatrix} |D_t^{\gamma_1} T_1(w_0, z_0)(t)| \\ |D_t^{\gamma_2} T_2(w_0, z_0)(t)| \end{pmatrix} = \begin{pmatrix} |D_t^{\gamma_1} w_1(t)| \\ |D_t^{\gamma_2} z_1(t)| \end{pmatrix}.$$

Analogously, for $n = 1, 2, \dots$, we have

$$\begin{pmatrix} w_{n+1}(t) \\ z_{n+1}(t) \end{pmatrix} \geq \begin{pmatrix} w_n(t) \\ z_n(t) \end{pmatrix}, \quad \begin{pmatrix} |D_t^{\gamma_1} w_{n+1}(t)| \\ |D_t^{\gamma_2} z_{n+1}(t)| \end{pmatrix} \geq \begin{pmatrix} |D_t^{\gamma_1} w_n(t)| \\ |D_t^{\gamma_2} z_n(t)| \end{pmatrix} \quad \text{for } 0 \leq t \leq 1.$$

So we can assert that $(w_n, z_n) \rightarrow (w^*, z^*)$ and $T(w^*, z^*) = (w^*, z^*)$, since T is completely continuous and $(w_{n+1}, z_{n+1}) = T(w_n, z_n)$.

Consequently, there exist (u^*, v^*) and (w^*, z^*) in P_l that are nonnegative extremal solutions of BVP (1.1)–(1.2). From (S2) it is obvious that $(u^*, v^*)(t) > 0$ and $(w^*, z^*)(t) > 0$ for $t \in [0, 1]$, since zero is not a solution of problem (1.1). The proof is completed. \square

Example 3.1 For $t \in [0, 1]$, consider the following fractional differential system:

$$\begin{cases} D_t^{2.5} u(t) + (\frac{1}{2}t^2 + \frac{1}{10}u(t) + \frac{1}{32} \sin(v(t)) + \frac{1}{50}D_t^{0.3}u(t) + \frac{1}{D_t^{0.2}v(t)-\frac{1}{2}} + 2) = 0, \\ D_t^{2.5} v(t) + (\frac{1}{3}t + \frac{1}{4\pi} \sin(2\pi u(t)) + \frac{1}{18}v(t) + \frac{1}{5}(D_t^{0.3}u(t))^2 + D_t^{0.2}v(t) + \frac{10}{11}) = 0, \end{cases} \tag{3.11}$$

with the coupled integral and discrete mixed boundary conditions

$$\begin{cases} u(0) = u'(0) = 0, & u(1) = \sum_{i=1}^2 \lambda_{1i} I_t^{1.5} v(\xi_i) + \sum_{i=1}^2 b_i v(\eta_i), \\ v(0) = v'(0) = 0, & v(1) = \sum_{i=1}^2 \lambda_{2i} I_t^{1.2} u(\xi_i) + \sum_{i=1}^2 b_i u(\eta_i). \end{cases} \tag{3.12}$$

In this model, we set

$$\begin{matrix} \lambda_{11} = \frac{1}{2}, & \lambda_{21} = \frac{2}{7}, & \xi_1 = \frac{1}{4}, & b_1 = \frac{1}{3}, & \eta_1 = \frac{1}{3}, \\ \lambda_{12} = \frac{1}{4}, & \lambda_{22} = \frac{3}{7}, & \xi_2 = \frac{3}{4}, & b_2 = \frac{2}{3}, & \eta_2 = \frac{2}{3}. \end{matrix}$$

It is obvious that (F₁) and (F₂) hold. By calculation we get

$$\begin{matrix} l_1 = 0.4920, & l_2 = 0.4521, \\ \varrho_1 = 0.9675, & \varrho_2 = 0.9675, \\ \rho_1 = 0.4374, & \rho_2 = 0.4760. \end{matrix}$$

Setting $A_1 = A_2 = 5$, we get $l = \max\{A_1 \int_0^1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \rho_1 ds, A_1 \int_0^1 \rho_2 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 \varrho_2 [(1-s)^{\alpha_2-1} + 1] ds\}$. Then all the hypotheses of Theorem 3.1 are satisfied with $l = 11$. Hence, BVP (3.11)–(3.12) has monotone positive

solutions (u^*, v^*) and (w^*, z^*) , which satisfy, for $t \in [0, 1]$,

$$\begin{aligned} \begin{pmatrix} u_0(t) \\ v_0(t) \end{pmatrix} &= \begin{pmatrix} t^{\alpha_1-1} \{A_1 \int_0^1 \varrho_1 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \rho_1 ds\} \\ t^{\alpha_2-1} \{A_1 \int_0^1 \rho_2 [(1-s)^{\alpha_1-1} + 1] ds + A_2 \int_0^1 [(1-s)^{\alpha_2-1} + 1] \varrho_2 ds\} \end{pmatrix} \\ &= \begin{pmatrix} 9.8343t^{1.5} \\ 10.1045t^{1.5} \end{pmatrix} \end{aligned}$$

and

$$\begin{pmatrix} w_0(t) \\ z_0(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

For $n = 1, 2, \dots$, the two iterative schemes are

$$\begin{aligned} \begin{pmatrix} u_0(t) \\ v_0(t) \end{pmatrix} &= \begin{pmatrix} 9.8343t^{1.5} \\ 10.1045t^{1.5} \end{pmatrix}, \quad \dots, \\ \begin{pmatrix} u_{n+1}(t) \\ v_{n+1}(t) \end{pmatrix} &= \begin{pmatrix} T_1(u_n, v_n)(t) \\ T_2(u_n, v_n)(t) \end{pmatrix} = \begin{pmatrix} \int_0^1 K_1(t, s) f_1(u_n, v_n)(s) ds + \int_0^1 H_1(t, s) f_2(u_n, v_n)(s) ds \\ \int_0^1 K_2(t, s) f_2(u_n, v_n)(s) ds + \int_0^1 H_2(t, s) f_1(u_n, v_n)(s) ds \end{pmatrix}, \end{aligned}$$

where

$$\begin{aligned} &\int_0^1 K_1(t, s) f_1(u_n, v_n)(s) ds + \int_0^1 H_1(t, s) f_2(u_n, v_n)(s) ds \\ &= \frac{1}{\Gamma(2.5)} \int_0^1 \left\{ t^{1.5} (1-s)^{1.5} + \frac{l_2 t^{1.5}}{1-l_1 l_2} \left[\frac{2}{7\Gamma(1.2)} \int_0^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \right. \right. \\ &\quad - \frac{2}{7\Gamma(1.2)} \int_s^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{3}{7\Gamma(1.2)} \int_0^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \\ &\quad \left. \left. - \frac{3}{7\Gamma(1.2)} \int_s^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \right\} \\ &\quad \times \left(\frac{1}{2} s^2 + \frac{1}{10} u_n(s) + \frac{1}{32} \sin(v_n(s)) + \frac{1}{50} D_t^{0.3} u_n(s) + \frac{1}{D_t^{0.2} v_n(s) - \frac{1}{2}} + 2 \right) ds \\ &\quad - \frac{1}{\Gamma(2.5)} \int_0^t \left\{ (t-s)^{1.5} + \frac{l_2 t^{1.5}}{1-l_1 l_2} \left[\frac{1}{3} \left(\frac{1}{3}-s\right)^{1.5} + \frac{2}{3} \left(\frac{2}{3}-s\right)^{1.5} \right] \right\} \left(\frac{1}{2} s^2 + \frac{1}{10} u_n(s) \right. \\ &\quad \left. + \frac{1}{32} \sin(v_n(s)) + \frac{1}{50} D_t^{0.3} u_n(s) + \frac{1}{D_t^{0.2} v_n(s) - \frac{1}{2}} + 2 \right) ds \\ &\quad + \frac{1}{\Gamma(2.5)} \int_0^1 \frac{t^{1.5}}{1-l_1 l_2} \left[\frac{1}{2\Gamma(1.5)} \int_0^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} \tau^{1.5} (1-s)^{1.5} d\tau \right. \\ &\quad - \frac{1}{2\Gamma(1.5)} \int_s^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{4\Gamma(1.5)} \int_0^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} \tau^{1.5} (1-s)^{1.5} d\tau \\ &\quad \left. - \frac{1}{4\Gamma(1.5)} \int_s^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \\ &\quad \times \left(\frac{1}{3} s + \frac{1}{4\pi} \sin(2\pi u_n(s)) + \frac{1}{18} v_n(t) + \frac{1}{5} (D_t^{0.3} u_n(t))^2 + D_t^{0.2} v_n(t) + \frac{10}{11} \right) ds \end{aligned}$$

$$\begin{aligned}
 & - \frac{1}{\Gamma(2.5)} \int_0^t \frac{t^{1.5}}{1-l_1l_2} \left[\frac{1}{3} \left(\frac{1}{3} - s \right)^{1.5} + \frac{2}{3} \left(\frac{2}{3} - s \right)^{1.5} \right] \\
 & \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi u_n(s)) + \frac{1}{18} v_n(t) \right) \\
 & + \frac{1}{5} (D_t^{0.3} u_n(t))^2 + D_t^{0.2} v_n(t) + \frac{10}{11} \Big) ds, \\
 & \int_0^1 K_2(t,s) f_2(u_n, v_n)(s) ds + \int_0^1 H_2(t,s) f_1(u_n, v_n)(s) ds \\
 & = \frac{1}{\Gamma(2.5)} \int_0^1 \left\{ t^{1.5} (1-s)^{1.5} + \frac{l_1 t^{1.5}}{1-l_1l_2} \left[\frac{1}{2\Gamma(1.5)} \int_0^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.5} \tau^{1.5} (1-s)^{1.5} d\tau \right. \right. \\
 & - \frac{1}{2\Gamma(1.5)} \int_s^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{4\Gamma(1.5)} \int_0^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.5} \tau^{1.5} (1-s)^{1.5} d\tau \\
 & \left. \left. - \frac{1}{4\Gamma(1.5)} \int_s^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \right\} \\
 & \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi u_n(s)) + \frac{1}{18} v_n(t) + \frac{1}{5} (D_t^{0.3} u_n(t))^2 + D_t^{0.2} v_n(t) + \frac{10}{11} \Big) ds \\
 & - \frac{1}{\Gamma(2.5)} \int_0^t \left\{ (t-s)^{1.5} + \frac{l_1 t^{1.5}}{1-l_1l_2} \left[\frac{1}{3} \left(\frac{1}{3} - s \right)^{1.5} + \frac{2}{3} \left(\frac{2}{3} - s \right)^{1.5} \right] \right\} \\
 & \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi u_n(s)) \right) \\
 & + \frac{1}{18} v_n(t) + \frac{1}{5} (D_t^{0.3} u_n(t))^2 + D_t^{0.2} v_n(t) + \frac{10}{11} \Big) ds \\
 & + \frac{1}{\Gamma(2.5)} \int_0^1 \frac{t^{1.5}}{1-l_1l_2} \left[\frac{2}{7\Gamma(1.2)} \int_0^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \right. \\
 & - \frac{2}{7\Gamma(1.2)} \int_s^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{3}{7\Gamma(1.2)} \int_0^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \\
 & \left. - \frac{3}{7\Gamma(1.2)} \int_s^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \\
 & \times \left(\frac{1}{2}s^2 + \frac{1}{10} u_n(s) + \frac{1}{32} \sin(v_n(s)) + \frac{1}{50} D_t^{0.3} u_n(s) + \frac{1}{D_t^{0.2} v_n(s) - \frac{1}{2}} + 2 \right) ds \\
 & - \frac{1}{\Gamma(2.5)} \int_0^t \frac{t^{1.5}}{1-l_1l_2} \left[\frac{1}{3} \left(\frac{1}{3} - s \right)^{1.5} + \frac{2}{3} \left(\frac{2}{3} - s \right)^{1.5} \right] \\
 & \times \left(\frac{1}{2}s^2 + \frac{1}{10} u_n(s) + \frac{1}{32} \sin(v_n(s)) \right) \\
 & + \frac{1}{50} D_t^{0.3} u_n(s) + \frac{1}{D_t^{0.2} v_n(s) - \frac{1}{2}} + 2 \Big) ds,
 \end{aligned}$$

and

$$\begin{pmatrix} w_0(t) \\ z_0(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \dots,$$

$$\begin{pmatrix} w_{n+1}(t) \\ z_{n+1}(t) \end{pmatrix} = \begin{pmatrix} \int_0^1 K_1(t,s)f_{1(w_n,z_n)}(s) ds + \int_0^1 H_1(t,s)f_{2(w_n,z_n)}(s) ds \\ \int_0^1 K_2(t,s)f_{2(w_n,z_n)}(s) ds + \int_0^1 H_2(t,s)f_{1(w_n,z_n)}(s) ds \end{pmatrix},$$

where

$$\begin{aligned} & \int_0^1 K_1(t,s)f_{1(w_n,z_n)}(s) ds + \int_0^1 H_1(t,s)f_{2(w_n,z_n)}(s) ds \\ &= \frac{1}{\Gamma(2.5)} \int_0^1 \left\{ t^{1.5}(1-s)^{1.5} + \frac{l_2 t^{1.5}}{1-l_1 l_2} \left[\frac{2}{7\Gamma(1.2)} \int_0^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.2} \tau^{1.5}(1-s)^{1.5} d\tau \right. \right. \\ & \quad - \frac{2}{7\Gamma(1.2)} \int_s^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{3}{7\Gamma(1.2)} \int_0^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.2} \tau^{1.5}(1-s)^{1.5} d\tau \\ & \quad \left. \left. - \frac{3}{7\Gamma(1.2)} \int_s^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \right\} \\ & \quad \times \left(\frac{1}{2}s^2 + \frac{1}{10}w_n(s) + \frac{1}{32} \sin(z_n(s)) + \frac{1}{50} D_t^{0.3} w_n(s) + \frac{1}{D_t^{0.2} z_n(s) - \frac{1}{2}} + 2 \right) ds \\ & \quad - \frac{1}{\Gamma(2.5)} \int_0^t \left\{ (t-s)^{1.5} + \frac{l_2 t^{1.5}}{1-l_1 l_2} \left[\frac{1}{3} \left(\frac{1}{3}-s\right)^{1.5} + \frac{2}{3} \left(\frac{2}{3}-s\right)^{1.5} \right] \right\} \left(\frac{1}{2}s^2 + \frac{1}{10}w_n(s) \right. \\ & \quad \left. + \frac{1}{32} \sin(z_n(s)) + \frac{1}{50} D_t^{0.3} w_n(s) + \frac{1}{D_t^{0.2} z_n(s) - \frac{1}{2}} + 2 \right) ds \\ & \quad + \frac{1}{\Gamma(2.5)} \int_0^1 \frac{t^{1.5}}{1-l_1 l_2} \left[\frac{1}{2\Gamma(1.5)} \int_0^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} \tau^{1.5}(1-s)^{1.5} d\tau \right. \\ & \quad - \frac{1}{2\Gamma(1.5)} \int_s^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{4\Gamma(1.5)} \int_0^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} \tau^{1.5}(1-s)^{1.5} d\tau \\ & \quad \left. - \frac{1}{4\Gamma(1.5)} \int_s^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \\ & \quad \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi w_n(s)) + \frac{1}{18} z_n(t) + \frac{1}{5} (D_t^{0.3} w_n(t))^2 + D_t^{0.2} z_n(t) + \frac{10}{11} \right) ds \\ & \quad - \frac{1}{\Gamma(2.5)} \int_0^t \frac{t^{1.5}}{1-l_1 l_2} \left[\frac{1}{3} \left(\frac{1}{3}-s\right)^{1.5} + \frac{2}{3} \left(\frac{2}{3}-s\right)^{1.5} \right] \\ & \quad \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi w_n(s)) + \frac{1}{18} z_n(t) \right. \\ & \quad \left. + \frac{1}{5} (D_t^{0.3} w_n(t))^2 + D_t^{0.2} z_n(t) + \frac{10}{11} \right) ds, \\ & \int_0^1 K_2(t,s)f_{2(w_n,z_n)}(s) ds + \int_0^1 H_2(t,s)f_{1(w_n,z_n)}(s) ds \\ &= \frac{1}{\Gamma(2.5)} \int_0^1 \left\{ t^{1.5}(1-s)^{1.5} + \frac{l_1 t^{1.5}}{1-l_1 l_2} \left[\frac{1}{2\Gamma(1.5)} \int_0^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} \tau^{1.5}(1-s)^{1.5} d\tau \right. \right. \\ & \quad - \frac{1}{2\Gamma(1.5)} \int_s^{\frac{1}{4}} \left(\frac{1}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{4\Gamma(1.5)} \int_0^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} \tau^{1.5}(1-s)^{1.5} d\tau \\ & \quad \left. \left. - \frac{1}{4\Gamma(1.5)} \int_s^{\frac{3}{4}} \left(\frac{3}{4}-\tau\right)^{0.5} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \right\} \end{aligned}$$

$$\begin{aligned}
 & \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi w_n(s)) + \frac{1}{18}z_n(t) + \frac{1}{5}(D_t^{0.3} w_n(t))^2 + D_t^{0.2} z_n(t) + \frac{10}{11} \right) ds \\
 & - \frac{1}{\Gamma(2.5)} \int_0^t \left\{ (t-s)^{1.5} + \frac{l_1 t^{1.5}}{1-l_1 l_2} \left[\frac{1}{3} \left(\frac{1}{3} - s \right)^{1.5} + \frac{2}{3} \left(\frac{2}{3} - s \right)^{1.5} \right] \right\} \\
 & \times \left(\frac{1}{3}s + \frac{1}{4\pi} \sin(2\pi w_n(s)) \right. \\
 & \left. + \frac{1}{18}z_n(t) + \frac{1}{5}(D_t^{0.3} w_n(t))^2 + D_t^{0.2} z_n(t) + \frac{10}{11} \right) ds \\
 & + \frac{1}{\Gamma(2.5)} \int_0^1 \frac{t^{1.5}}{1-l_1 l_2} \left[\frac{2}{7\Gamma(1.2)} \int_0^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \right. \\
 & - \frac{2}{7\Gamma(1.2)} \int_s^{\frac{1}{4}} \left(\frac{1}{4} - \tau \right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{3}{7\Gamma(1.2)} \int_0^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.2} \tau^{1.5} (1-s)^{1.5} d\tau \\
 & \left. - \frac{3}{7\Gamma(1.2)} \int_s^{\frac{3}{4}} \left(\frac{3}{4} - \tau \right)^{0.2} (\tau-s)^{1.5} d\tau + \frac{1}{3} \cdot \frac{1^{1.5}}{3} (1-s)^{1.5} + \frac{2}{3} \cdot \frac{2^{1.5}}{3} (1-s)^{1.5} \right] \\
 & \times \left(\frac{1}{2}s^2 + \frac{1}{10}w_n(s) + \frac{1}{32} \sin(z_n(s)) + \frac{1}{50}D_t^{0.3} w_n(s) + \frac{1}{D_t^{0.2} z_n(s) - \frac{1}{2}} + 2 \right) ds \\
 & - \frac{1}{\Gamma(2.5)} \int_0^t \frac{t^{1.5}}{1-l_1 l_2} \left[\frac{1}{3} \left(\frac{1}{3} - s \right)^{1.5} + \frac{2}{3} \left(\frac{2}{3} - s \right)^{1.5} \right] \\
 & \times \left(\frac{1}{2}s^2 + \frac{1}{10}w_n(s) + \frac{1}{32} \sin(z_n(s)) \right. \\
 & \left. + \frac{1}{50}D_t^{0.3} w_n(s) + \frac{1}{D_t^{0.2} z_n(s) - \frac{1}{2}} + 2 \right) ds.
 \end{aligned}$$

Acknowledgements

The authors would like to thank very much the anonymous referees for helpful comments and suggestions, which led to an improvement of presentation and quality of the work.

Funding

The work is supported by National Training Program of Innovation (Project No. 201910019172). The funding body plays an important role in the design of the study and analysis, calculation, and writing the manuscript.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally to the manuscript, read, and approved the final draft.

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Received: 7 April 2019 Accepted: 25 July 2019 Published online: 11 September 2019

References

1. Podlubny, I.: *Fractional Differential Equations*. Mathematics in Science and Engineering. Academic Press, New York (1999)
2. Kilbas, A.A., Srivastava, H.M., Trujillo, J.J.: *Theory and Applications of Fractional Differential Equations*. North-Holland Mathematics Studies. Elsevier, Amsterdam (2006)
3. Liu, Y., Ahmad, B.: A study of impulsive multiterm fractional differential equations with single and multiple base point and applications. *Sci. World J.* **2014**, Article ID 194346 (2014)
4. Hilfer, R.: *Applications of Fractional Calculus in Physics*. World Scientific, Singapore (2000)
5. Zhang, W., Bai, Z., Sun, S.: Extremal solutions for some periodic fractional differential equations. *Adv. Differ. Equ.* **2016**, 179 (2016)
6. Liu, X., Jia, M., Ge, W.: The method of lower and upper solutions for mixed fractional four-point boundary value problem with p -Laplacian operator. *Appl. Math. Lett.* **65**, 56–62 (2017)

7. Yan, F., Zuo, M., Hao, X.: Positive solution for a fractional singular boundary value problem with p -Laplacian operator. *Bound. Value Probl.* **2018**(1), 51 (2018)
8. Xu, M., Han, Z.: Positive solutions for integral boundary value problem of two-term fractional differential equations. *Bound. Value Probl.* **2018**(1), 100 (2018)
9. Jia, M., Liu, X.: Multiplicity of solutions for integral boundary value problems of fractional differential equations with upper and lower solutions. *Appl. Math. Comput.* **232**, 313–323 (2014)
10. Ahmed, H.M., El-Borai, M.M.: Hilfer fractional stochastic integro-differential equations. *Appl. Math. Comput.* **331**, 182–189 (2018)
11. Sheng, K., Zhang, W., Bai, Z.: Positive solutions to fractional boundary-value problems with p -Laplacian on time scales. *Bound. Value Probl.* **2018**(1), 70 (2018)
12. Jiang, J., Liu, W., Wang, H.: Positive solutions to singular Dirichlet-type boundary value problems of nonlinear fractional differential equations. *Adv. Differ. Equ.* **2018**(1), 169 (2018)
13. Ahmad, B., Ntouyas, S.K., Alsaedi, A.: Existence of solutions for fractional differential equations with nonlocal and average type integral boundary conditions. *J. Appl. Math. Comput.* **53**, 129–145 (2017)
14. Bo, S.: Monotone iterative technique and positive solutions to a third-order differential equation with advanced arguments and Stieltjes integral boundary conditions. *Adv. Differ. Equ.* **2018**(1), 218 (2018)
15. Guo, L., Liu, L., Wu, Y.: Uniqueness of iterative positive solutions for the singular fractional differential equations with integral boundary conditions. *Bound. Value Probl.* **2016**, 147 (2016)
16. Wang, G., Pei, K., Agarwal, R.P., Zhang, L., Ahmad, B.: Nonlocal Hadamard fractional boundary value problem with Hadamard integral and discrete boundary conditions on a half-line. *J. Comput. Appl. Math.* **343**, 230–239 (2018)
17. Song, Q., Bai, Z.: Positive solutions of fractional differential equations involving the Riemann–Stieltjes integral boundary condition. *Adv. Differ. Equ.* **2018**(1), 183 (2018)
18. Liu, X., Jia, M.: Solvability and numerical simulations for BVPs of fractional coupled systems involving left and right fractional derivatives. *Appl. Math. Comput.* **353**, 230–242 (2019)
19. Liu, X., Jia, M.: The method of lower and upper solutions for the general boundary value problems of fractional differential equations with p -Laplacian. *Adv. Differ. Equ.* **2018**, 28 (2018)
20. Ali, N., Shah, K., Baleanu, D., Arif, M., Khan, R.A.: Study of a class of arbitrary order differential equations by a coincidence degree method. *Bound. Value Probl.* **2017**(1), 111 (2017)
21. Bai, Z., Zhang, Y.: Solvability of fractional three-point boundary value problems with nonlinear growth. *Appl. Math. Comput.* **218**(5), 1719–1725 (2011)
22. Zhang, Y., Bai, Z., Feng, T.: Existence results for a coupled system of nonlinear fractional three-point boundary value problems at resonance. *Comput. Math. Appl.* **61**(4), 1032–1047 (2018)
23. Alsaedi, A., Ntouyas, S.K., Garout, D., Ahmad, B.: Coupled fractional-order systems with nonlocal coupled integral and discrete boundary conditions. *Bull. Malays. Math. Sci. Soc.* **42**, 241–266 (2017)
24. Dimplekumar, C., Avadhesh, K.: Existence, uniqueness and Ulam's stability of solutions for a coupled system of fractional differential equations with integral boundary conditions. *Mathematics* **6**(6), 96 (2018)
25. Cui, M., Zhu, Y., Pang, H.: Existence and uniqueness results for a coupled fractional order systems with the multi-strip and multi-point mixed boundary conditions. *Adv. Differ. Equ.* **2017**(1), 224 (2017)
26. Yang, W.: Monotone iterative technique for a coupled system of nonlinear Hadamard fractional differential equations. *J. Appl. Math. Comput.* (2018). <https://doi.org/10.1007/s12190-018-1192-x>
27. Wen, R., Zhao, P.: A medium-shifted splitting iteration method for a diagonal-plus-Toeplitz linear system from spatial fractional Schrödinger equations. *Bound. Value Probl.* **2018**(1), 45 (2018)
28. Li, Y., Shah, K., Khan, R.A.: Iterative technique for coupled integral boundary value problem of non-integer order differential equations. *Adv. Differ. Equ.* **2017**(1), 251 (2017)

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)
