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# Oscillation criteria of certain fractional partial differential equations

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## Abstract

In this article, we regard the generalized Riccati transformation and Riemann–Liouville fractional derivatives as the principal instrument. In the proof, we take advantage of the fractional derivatives technique with the addition of interval segmentation techniques, which enlarge the manners to demonstrate the sufficient conditions for oscillation criteria of certain fractional partial differential equations.

**Keywords:** Fractional partial differential equation; Oscillation; Riccati transformation

## 1 Introduction

The fractional calculus could be regarded as an age old but interesting theme. The appearance of the fractional differential equations is becoming more and more frequent. Kumar et al. [1, 2] studied the fractional diabetes model as well as the Ambartsumian equation by applying the homotopy analysis transform method (HATM). In 2019, the authors of [3] presented a hybrid numerical scheme based on the HATM in order to detect the fractional model of nonlinear wave-like equations. In [4], the authors dealt with a fractional extension of the Biswas–Milovic (BM) model by using the fractional homotopy analysis transform method (FHATM). In 2019, Singh et al. [5] developed nondifferentiable solutions of extended wave equations. The author of [6] illustrated the rumor spreading dynamical model involving the Atangana–Baleanu derivative of non-integer order. In addition, fractional differential equations play an important role in modeling mechanics, electrical properties of real materials, rheological theory, aerodynamics, finance, bioengineering and so on. Currently, the fractional calculus and the theory of fractional differential equations have become a popular gambit. Kumar et al. [7] analyzed the exothermic reactions model by using fractional energy balance equation (FEBE). Making use of the Caputo–Fabrizio fractional operator and the fixed point theorem, the authors [8] reported a fractional SIRS-SI model. See Refs. [9–12].

The research of the oscillation of the fractional differential equations has been done more and more extensively. Zhou et al. [13, 14] suggested the sufficient conditions for the existence of nonoscillatory solutions for fractional neutral differential equations. In 2019, the authors [15] utilized the sufficient criteria for the oscillation of all solutions to the fractional partial differential equation. However, to the best of the author’s knowledge very little is known about the oscillation criteria of the fractional partial differential equations involved with the Riemann–Liouville fractional partial differential up to now [16–23].

A lot of work of the fractional differential equations which raise more and more attention has been published lately [24]. At the same time, several novel methods have been established to verify the sufficient condition of the oscillation properties of the fractional partial differential equations, such as [25–33]. We study the sufficient condition for oscillation of the solutions by using the generalized Riccati substitution, fractional integral as well as the properties of the Riemann–Liouville fractional derivative. In order to illustrate the main results, we give several examples at the end of the paper.

The Riemann–Liouville fractional derivative may always be used to solve the oscillation of fractional partial differential equations. Li [34] investigated the forced oscillation of fractional partial differential equations of the form,

$$\begin{aligned}
 D_{+,t}^\alpha u(x, t) &= a(t)\Delta u(x, t) - m(x, t, u(x, t)) + f(x, t), \\
 (x, t) &\in \Omega \times R_+ \equiv G.
 \end{aligned}
 \tag{1}$$

Prakash et al. [35] investigated the oscillation of certain nonlinear fractional partial differential equation with damping term,

$$\begin{aligned}
 D_{+,t}^\alpha (r(t)D_{+,t}^\alpha u(x, t)) + p(t)D_{+,t}^\alpha u(x, t) + q(x, t)f(u(x, t)) \\
 = a(t)\Delta u(x, t) + g(x, t), \quad (x, t) \in G.
 \end{aligned}
 \tag{2}$$

Harikrishnan et al. [36] established the oscillation of the fractional differential equation of the form,

$$\begin{aligned}
 D_{+,t}^\alpha (r(t)D_{+,t}^\alpha u(x, t)) + q(x, t)f(u(x, t)) \\
 = a(t)\Delta u(x, t) + g(x, t), \quad (x, t) \in G.
 \end{aligned}
 \tag{3}$$

In [37], Wang and Meng studied the oscillatory behavior of a fractional partial differential equation of this form,

$$\begin{aligned}
 D_{+,t}^\alpha (r(t)D_{+,t}^\alpha u(x, t)) + p(t)D_{+,t}^\alpha u(x, t) \\
 + q(x, t)f\left(\int_0^t (t - \nu)^{-\alpha} u(x, \nu) d\nu\right) \\
 = a(t)\Delta u(x, t), \quad (x, t) \in \Omega \times R_+ \equiv G.
 \end{aligned}
 \tag{4}$$

In this paper, we shall investigate the oscillation criteria for the fractional partial differential equation

$$\begin{aligned}
 D_{+,t}^\alpha (r(t)D_{+,t}^\alpha u(x, t)) + p(t)D_{+,t}^\alpha u(x, t) + q(x, t)f(u(x, t)) \\
 = a(t)\Delta u(x, t) + \sum_{i=1}^m b_i(t)\Delta u(x, t - \tau_i), \quad (x, t) \in \Omega \times R_+ \equiv G,
 \end{aligned}
 \tag{5}$$

with the Robin boundary condition

$$\frac{\partial u(x, t)}{\partial N} + g(x, t)u(x, t) = 0, \quad (x, t) \in \partial\Omega \times R_+,
 \tag{6}$$

where  $\alpha \in (0, 1)$  is a constant,  $D_{+,t}^\alpha$  is the Riemann–Liouville fractional derivative of order  $\alpha$  of  $u$  with respect  $t$ ,  $\Omega$  is a bounded domain in  $R^n$  with piecewise smooth boundary  $\partial\Omega$ ,  $\Delta$  is the Laplacian operator and  $N$  is the unit exterior normal vector to  $\partial\Omega$ , and  $g(x, t)$  is a nonnegative continuous function on  $\partial\Omega \times R_+$ .

Throughout, we assume that:

- (A<sub>1</sub>)  $r(t) \in C^\alpha(R_+, R_+), p(t) \in C(R_+, R), a(t) \in C(R_+, R_+), b_i(t) \in C(R_+, R_+), \tau_i \geq 0$  is a constant,  $i = 1, 2, \dots, m$ ;
- (A<sub>2</sub>)  $q(x, t) \in C(\bar{G}, R_+), \min_{x \in \Omega} q(x, t) = Q(t)$ ;
- (A<sub>3</sub>)  $f : R \rightarrow R$  is a continuous function such that  $\frac{f(x)}{x} \geq m$  for certain constant  $m > 0$  and for all  $x \neq 0$ .

A solution  $u(x, t)$  of (5) is called oscillatory in  $G$  if it is neither eventually positive nor eventually negative. Otherwise, it is called nonoscillatory.

### 2 Preliminaries and basic lemmas

In this section, we list several symbols and lemmas which are useful through this paper.

**Definition 2.1** ([25]) The Riemann–Liouville fractional integral  $I_+^\alpha y$  of order  $\alpha \in R_+$  is defined by

$$(I_+^\alpha y)(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t - v)^{\alpha-1} y(v) dv, \quad t > 0, \tag{7}$$

where  $\Gamma(\alpha)$  is the gamma function defined by  $\Gamma(\alpha) = \int_0^{+\infty} s^{\alpha-1} e^{-s} ds$  for  $\alpha > 0$ . This integral is called left-sided fractional integral.

**Definition 2.2** ([25]) The Riemann–Liouville fractional partial derivative of order  $0 < \alpha < 1$  of a function  $u(x, t)$  is defined by

$$(D_{+,t}^\alpha u)(x, t) = \frac{\partial}{\partial t} \frac{1}{\Gamma(1 - \alpha)} \int_0^t (t - v)^{-\alpha} u(x, v) dv, \quad t > 0, \tag{8}$$

provided the right hand side is pointwise defined on  $R_+$ , where  $\Gamma$  is the gamma function.

**Definition 2.3** ([25]) The Riemann–Liouville fractional derivative of order  $\alpha > 0$  of a function  $y : R_+ \rightarrow R$  on the half-axis  $R_+$  is given by

$$\begin{aligned} (D_{+,t}^\alpha y)(t) &= \frac{d^{[\alpha]}}{dt^{[\alpha]}} (I_+^{[\alpha]-\alpha} y)(t) \\ &= \frac{1}{\Gamma([\alpha] - \alpha)} \frac{d^{[\alpha]}}{dt^{[\alpha]}} \int_0^t (t - v)^{[\alpha]-\alpha-1} y(v) dv, \quad t > 0, \end{aligned} \tag{9}$$

provided the right hand side is pointwise defined on  $R_+$ , where  $[\alpha]$  is the ceiling function of  $\alpha$ .

**Lemma 2.1** (Lemma 2.4, [30]) *Let*

$$F(t) = \int_0^t (t - v)^{-\alpha} y(v) dv, \quad \alpha \in (0, 1), t > 0. \tag{10}$$

Then

$$F'(t) = \Gamma(1 - \alpha)(D_+^\alpha y)(t). \tag{11}$$

**Lemma 2.2** ([25]) *Let  $\alpha \geq 0$ ,  $m \in \mathbb{N}$ , and  $D = \frac{d}{dx}$ . If the fractional derivatives  $D_+^\alpha y(t)$  and  $D_+^{\alpha+m} y(t)$  exist, then*

$$D^m(D_+^\alpha y(t)) = D_+^{\alpha+m} y(t). \tag{12}$$

**Lemma 2.3** ([25]) *Let  $\alpha \in (0, 1)$  and  $I_+^{1-\alpha} y(t)$  be the fractional integral (7) of order  $1 - \alpha$ , then*

$$I_+^\alpha(D_+^\alpha y(t)) = y(t) - \frac{I_+^{1-\alpha} y(0)}{\Gamma(\alpha)} t^{\alpha-1}. \tag{13}$$

For convenience, we use the following notations in this paper:

$$\begin{aligned} v(t) &= \int_\Omega u(x, t) dx, & \xi &= \frac{t^\alpha}{\Gamma(1 + \alpha)}, & \tilde{c}(\xi) &= c(t), & \tilde{r}(\xi) &= r(t), \\ \tilde{\sigma}(\xi) &= \sigma(t), & \xi_0 &= \frac{t_0^\alpha}{\Gamma(1 + \alpha)}, & \xi_1 &= \frac{t_1^\alpha}{\Gamma(1 + \alpha)}, & \tilde{Q}(\xi) &= Q(t), \\ R(t) &= I_+^\alpha \left( \frac{p(t)}{r(t)} \right). \end{aligned}$$

### 3 Main results

**Theorem 3.1** *Let condition (A<sub>1</sub>)–(A<sub>3</sub>) hold, suppose that there exists a function  $\varphi \in C^1[[t_0, \infty), (0, \infty)]$ , such that*

$$\int_{t_0}^\infty \frac{1}{r(s)e^{R(s)}} ds = \infty, \tag{14}$$

$$\limsup_{t \rightarrow \infty} A(t) > 0, \quad \liminf_{t \rightarrow \infty} A(t) < 0, \tag{15}$$

where

$$A(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t - \xi)^{\alpha-1} \left( -me^{R(\xi)} \varphi(\xi) Q(\xi) + \frac{(D_+^\alpha \varphi(\xi))^2 e^{R(\xi)} r(\xi)}{4\varphi(\xi)} \right) d\xi. \tag{16}$$

Then every solution of (5) is oscillatory.

*Proof* Suppose to the contrary that  $u$  is a nonoscillatory solution of (5). Without loss of generality, we can assume that there exists  $u(x, t) > 0$  and  $u(x, t - \tau_i) > 0$  in  $G \times [t_0, \infty)$  for some  $t_0 > 0$ ,  $i = 1, 2, \dots, m$ . Integrating (5) with respect to  $x$  over the domain  $\Omega$ , we obtain

$$\begin{aligned} & \int_\Omega D_{+,t}^\alpha (r(t) D_{+,t}^\alpha u(x, t)) dx \\ & + p(t) \int_\Omega D_{+,t}^\alpha u(x, t) dx + \int_\Omega q(x, t) f(u(x, t)) dx \\ & = a(t) \int_\Omega \Delta u(x, t) dx + \int_\Omega \sum_{i=1}^m b_i(t) \Delta u(x, t - \tau_i) dx. \end{aligned} \tag{17}$$

Using Green’s formula, it is obvious that

$$\int_{\Omega} \Delta u(x, t) \, dx = \int_{\partial\Omega} \frac{\partial u(x, t)}{\partial N} \, ds = - \int_{\partial\Omega} g(x, t)u(x, t) \, ds \leq 0, \quad t \geq t_1, \tag{18}$$

$$\begin{aligned} \int_{\Omega} \Delta u(x, t - \tau_i) \, dx &= \int_{\partial\Omega} \frac{\partial u(x, t - \tau_i)}{\partial N} \, ds \\ &= - \int_{\partial\Omega} g(x, t - \tau_i)u(x, t - \tau_i) \, ds \\ &\leq 0, \quad t \geq t_1, i = 1, 2, \dots, m, \end{aligned} \tag{19}$$

where  $ds$  is a surface element on  $\partial\Omega$ . By using Jensen’s inequality and  $(A_2)$ , we obtain

$$\int_{\Omega} q(x, t)f(u(x, t)) \, dx \geq Q(t)f\left(\int_{\Omega} u(x, t) \, dx\right) = Q(t)f(v(t)). \tag{20}$$

Combining (17)–(20), we have

$$D_+^\alpha(r(t)D_+^\alpha v(t)) + p(t)D_+^\alpha v(t) + Q(t)f(v(t)) \leq 0, \tag{21}$$

$$\begin{aligned} D_+^\alpha(e^{R(t)}r(t)D_+^\alpha v(t)) &= e^{R(t)}\frac{p(t)}{r(t)}r(t)D_+^\alpha v(t) + D_+^\alpha(r(t)D_+^\alpha v(t))e^{R(t)} \\ &= e^{R(t)}p(t)D_+^\alpha v(t) + D_+^\alpha(r(t)D_+^\alpha v(t))e^{R(t)} \\ &\leq e^{R(t)}(-Q(t)f(v(t))) \\ &< 0. \end{aligned} \tag{22}$$

Then  $e^{R(t)}r(t)D_+^\alpha v(t)$  is strictly decreasing on  $[t_1, \infty)$ , and thus  $D_+^\alpha v(t)$  is eventually of one sign. We claim  $D_+^\alpha v(t) \geq 0$  on  $[t_2, \infty)$ , where  $t_2 > t_1$  is sufficiently large. Otherwise, assume there exists a sufficiently large  $T > t_2$  such that  $D_+^\alpha v(t) < 0$  on  $[T, \infty)$ . Then, for  $t \in [T, \infty)$ , by Lemma 2.1, we have

$$\frac{F'(t)}{\Gamma(1 - \alpha)} = D_+^\alpha v(t) \leq \frac{r(T)e^{R(T)}(D_+^\alpha v(T))}{r(t)e^{R(t)}}, \tag{23}$$

where

$$F(t) = \int_0^t (t - s)^{-\alpha} v(s) \, ds.$$

Integrating the above inequality from  $T$  to  $t$ , we have

$$F(t) \leq F(T) + \Gamma(1 - \alpha)r(T)e^{R(T)}(D_+^\alpha v(T)) \int_T^t \frac{1}{r(s)e^{R(s)}} \, ds. \tag{24}$$

Letting  $t \rightarrow \infty$ , we get  $\lim_{t \rightarrow \infty} F(t) \leq -\infty$  which is a contradiction. Hence  $D_+^\alpha v(t) \geq 0$  for  $t \geq t_1$  holds. Define the function  $\omega$  by the generalized Riccati substitution

$$\omega(t) = \varphi(t)\frac{e^{R(t)}r(t)D_+^\alpha v(t)}{v(t)}, \quad t \geq t_1, \tag{25}$$

$$\begin{aligned}
 D_+^\alpha \omega(t) &= (D_+^\alpha \varphi(t)) \frac{\omega(t)}{\varphi(t)} + D_+^\alpha \left( \frac{e^{R(t)} r(t) D_+^\alpha v(t)}{v(t)} \right) \varphi(t) \\
 &= (D_+^\alpha \varphi(t)) \frac{\omega(t)}{\varphi(t)} + D_+^\alpha (e^{R(t)} r(t) D_+^\alpha v(t)) \frac{1}{v(t)} \varphi(t) \\
 &\quad + D_+^\alpha \left( \frac{1}{v(t)} \right) e^{R(t)} r(t) D_+^\alpha v(t) \varphi(t) \\
 &\leq (D_+^\alpha \varphi(t)) \frac{\omega(t)}{\varphi(t)} + \frac{\varphi(t) e^{R(t)} (-Q(t) f(v(t)))}{v(t)} \\
 &\quad - \frac{(D_+^\alpha v(t))^2 e^{R(t)} r(t) \varphi(t)}{v^2(t)} \\
 &\leq (D_+^\alpha \varphi(t)) \frac{\omega(t)}{\varphi(t)} + \frac{\varphi(t) e^{R(t)} (-Q(t) m v(t))}{v(t)} - \frac{\omega^2(t)}{\varphi(t) e^{R(t)} r(t)} \\
 &= -m e^{R(t)} \varphi(t) Q(t) - \left( \frac{\omega(t)}{\sqrt{\varphi(t) e^{R(t)} r(t)}} - \frac{D_+^\alpha \varphi(t) \sqrt{e^{R(t)} r(t)}}{2\sqrt{\varphi(t)}} \right)^2 \\
 &\quad + \frac{(D_+^\alpha \varphi(t))^2 e^{R(t)} r(t)}{4\varphi(t)} \\
 &\leq -m e^{R(t)} \varphi(t) Q(t) + \frac{(D_+^\alpha \varphi(t))^2 e^{R(t)} r(t)}{4\varphi(t)}. \tag{26}
 \end{aligned}$$

By Lemma 2.3, we have

$$I_+^\alpha (D_+^\alpha \omega(t)) = \omega(t) - \frac{I_+^{1-\alpha} \omega(0)}{\Gamma(\alpha)} t^{\alpha-1}. \tag{27}$$

According to (26), we have

$$I_+^\alpha (D_+^\alpha \omega(t)) \leq I_+^\alpha \left( -m e^{R(t)} \varphi(t) Q(t) + \frac{(D_+^\alpha \varphi(t))^2 e^{R(t)} r(t)}{4\varphi(t)} \right). \tag{28}$$

Then we have

$$\omega(t) - \frac{I_+^{1-\alpha} \omega(0)}{\Gamma(\alpha)} t^{\alpha-1} \leq I_+^\alpha \left( -m e^{R(t)} \varphi(t) Q(t) + \frac{(D_+^\alpha \varphi(t))^2 e^{R(t)} r(t)}{4\varphi(t)} \right). \tag{29}$$

Let  $B = \frac{I_+^{1-\alpha} \omega(0)}{\Gamma(\alpha)}$ , then

$$\begin{aligned}
 \omega(t) &\leq I_+^\alpha \left( -m e^{R(t)} \varphi(t) Q(t) + \frac{(D_+^\alpha \varphi(t))^2 e^{R(t)} r(t)}{4\varphi(t)} \right) + \frac{I_+^{1-\alpha} \omega(0)}{\Gamma(\alpha)} t^{\alpha-1} \\
 &= A(t) + B t^{\alpha-1}. \tag{30}
 \end{aligned}$$

Letting  $t \rightarrow \infty$  in (30), we have

$$\liminf_{t \rightarrow \infty} \omega(t) \leq \liminf_{t \rightarrow \infty} A(t) + \limsup_{t \rightarrow \infty} B t^{\alpha-1} < 0, \tag{31}$$

which contradicts  $\omega(t) \geq 0$ , similarly, if  $u(x, t) < 0$  we can get the contradiction. The proof is complete.  $\square$

For the following theorem, we introduce a class of functions  $R$ . Let

$$D = \{ (t, s) : t \geq s \geq t_0 \}. \tag{32}$$

The function  $H \in C(D, R)$  is said to belong to the class  $R$ , if

- (i)  $H(t, t) = 0$ , for  $t \geq t_0$ ,  $H(t, s) > 0$ , for  $t \neq s$ ;
- (ii)  $H(t, s)$  has partial derivatives on  $D$  such that  $\frac{\partial H}{\partial t}(t, s) = h_1(t, s)\sqrt{H(t, s)}$ ,  $\frac{\partial H}{\partial s}(t, s) = -h_2(t, s)\sqrt{H(t, s)}$ , for some  $h_1, h_2 \in L^1_{loc}(D, R)$ .

**Theorem 3.2** *Suppose conditions  $(A_1)$ – $(A_3)$  hold, and (14)–(15) are also true. If, for any  $T \geq t_0$ , there exists an interval  $(a, b) \in [T, \infty)$ , and there exists a  $c \in (a, b)$ ,  $H \in R$ , such that*

$$\begin{aligned} & \frac{1}{H(c, a)} \left\{ \int_a^c e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(s, a) ds - \int_a^c \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \right. \\ & \quad \times \left. \left( h_1(s, a) + \frac{\tilde{\varphi}'(s) \sqrt{H(s, a)}}{\tilde{\varphi}(s)} \right)^2 ds \right\} + \frac{1}{H(b, c)} \left\{ \int_c^b e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m \right. \\ & \quad \times \left. H(b, s) ds - \int_c^b \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \left( -h_2(b, s) + \frac{\tilde{\varphi}'(s) \sqrt{H(b, s)}}{\tilde{\varphi}(s)} \right)^2 ds \right\} \\ & > 0, \end{aligned} \tag{33}$$

then every solution of (5) is oscillatory.

*Proof* Suppose to the contrary that  $u(x, t)$  is a nonoscillatory solution of (5). Without loss of generality, we can assume that there exists  $u(x, t) > 0$  and  $u(x, t - \tau_i) > 0$  in  $G \times [t_0, \infty)$  for some  $t_0 > 0$ ,  $i = 1, 2, \dots, m$ . Proceeding as in the proof of Theorem 3.1, according to (26), we have

$$D_+^\alpha \omega(t) \leq (D_+^\alpha \varphi(t)) \frac{\omega(t)}{\varphi(t)} - m e^{R(t)} \varphi(t) Q(t) - \frac{\omega^2(t)}{\varphi(t) e^{R(t)} r(t)}. \tag{34}$$

Let  $\omega(t) = \tilde{\omega}(\xi)$ . Then  $D_+^\alpha \omega(t) = \tilde{\omega}'(\xi)$  and  $D_+^\alpha \varphi(t) = \tilde{\varphi}'(\xi)$ . So the above inequality is transformed into

$$\tilde{\omega}'(\xi) \leq \tilde{\varphi}'(\xi) \frac{\tilde{\omega}(\xi)}{\tilde{\varphi}(\xi)} - m e^{\tilde{R}(\xi)} \tilde{\varphi}(\xi) \tilde{Q}(\xi) - \frac{\tilde{\omega}^2(\xi)}{\tilde{\varphi}(\xi) e^{\tilde{R}(\xi)} \tilde{r}(\xi)}. \tag{35}$$

Multiplying both sides of (35) by  $H(s, t)$ , integrating from  $t$  to  $c$  about  $s$ , where  $t \in (a, c]$ ,

$$\begin{aligned} & \int_t^c \tilde{\omega}'(s) H(s, t) ds = \tilde{\omega}(c) H(c, t) - \int_t^c h_1(s, t) \sqrt{H(s, t)} \tilde{\omega}(s) ds, \\ & \int_t^c e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(s, t) ds \\ & \leq -\tilde{\omega}(c) H(c, t) + \int_t^c h_1(s, t) \sqrt{H(s, t)} \tilde{\omega}(s) ds + \int_t^c H(s, t) \tilde{\varphi}'(s) \frac{\tilde{\omega}(s)}{\tilde{\varphi}(s)} ds \\ & \quad - \int_t^c \frac{\tilde{\omega}^2(s)}{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)} H(s, t) ds \end{aligned} \tag{36}$$

$$\begin{aligned}
 &= -\tilde{\omega}(c)H(c, t) - \int_t^c \left\{ \frac{\tilde{\omega}(s)\sqrt{H(s, t)}}{\sqrt{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}} \right. \\
 &\quad \left. - \frac{\frac{\tilde{\varphi}'(s)H(s, t)\tilde{\omega}(s)}{\tilde{\varphi}(s)} + h_1(s, t)\sqrt{H(s, t)}\tilde{\omega}(s)}{2\tilde{\omega}(s)\sqrt{H(s, t)}} \sqrt{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}} \right\}^2 ds \\
 &\quad + \int_t^c \left( \frac{\frac{\tilde{\varphi}'(s)H(s, t)\tilde{\omega}(s)}{\tilde{\varphi}(s)} + h_1(s, t)\sqrt{H(s, t)}\tilde{\omega}(s)}{2\tilde{\omega}(s)\sqrt{H(s, t)}} \right)^2 \tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s) ds \\
 &\leq -\tilde{\omega}(c)H(c, t) \\
 &\quad + \int_t^c \left( \frac{\frac{\tilde{\varphi}'(s)\sqrt{H(s, t)}}{\tilde{\varphi}(s)} + h_1(s, t)}{2} \right)^2 \tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s) ds. \tag{37}
 \end{aligned}$$

Multiplying both sides of (35) by  $H(t, s)$ , integrating from  $c$  to  $t$  over  $s$ , where  $t \in [c, b)$ ,

$$\begin{aligned}
 &\int_c^t \tilde{\omega}'(s)H(t, s) ds = -\tilde{\omega}(c)H(t, c) + \int_c^t \sqrt{H(t, s)}h_2(t, s)\tilde{\omega}(s) ds, \tag{38} \\
 &\int_c^t e^{\tilde{R}(s)}\tilde{\varphi}(s)\tilde{Q}(s)mH(t, s) ds \\
 &\leq \tilde{\omega}(c)H(t, c) - \int_c^t \sqrt{H(t, s)}h_2(t, s)\tilde{\omega}(s) ds + \int_c^t H(t, s)\tilde{\varphi}'(s)\frac{\tilde{\omega}(s)}{\tilde{\varphi}(s)} ds \\
 &\quad - \int_c^t \frac{\tilde{\omega}^2(s)}{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}H(t, s) ds \\
 &= \tilde{\omega}(c)H(t, c) - \int_c^t \left\{ \frac{\tilde{\omega}(s)\sqrt{H(t, s)}}{\sqrt{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}} \right. \\
 &\quad \left. - \frac{\frac{\tilde{\varphi}'(s)H(t, s)\tilde{\omega}(s)}{\tilde{\varphi}(s)} - h_2(t, s)\sqrt{H(t, s)}\tilde{\omega}(s)}{2\tilde{\omega}(s)\sqrt{H(t, s)}} \sqrt{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}} \right\}^2 ds \\
 &\quad + \int_c^t \left( \frac{\frac{\tilde{\varphi}'(s)H(t, s)\tilde{\omega}(s)}{\tilde{\varphi}(s)} - h_2(t, s)\sqrt{H(t, s)}\tilde{\omega}(s)}{2\tilde{\omega}(s)\sqrt{H(t, s)}} \right)^2 \tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s) ds \\
 &\leq \tilde{\omega}(c)H(t, c) \\
 &\quad + \int_c^t \left( \frac{\frac{\tilde{\varphi}'(s)\sqrt{H(t, s)}}{\tilde{\varphi}(s)} - h_2(t, s)}{2} \right)^2 \tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s) ds. \tag{39}
 \end{aligned}$$

Letting  $t \rightarrow a^+$  in (37) and  $t \rightarrow b^-$  in (39),

$$\begin{aligned}
 &\frac{1}{H(c, a)} \left\{ \int_a^c e^{\tilde{R}(s)}\tilde{\varphi}(s)\tilde{Q}(s)mH(s, a) ds - \int_a^c \frac{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}{4} \right. \\
 &\quad \times \left( h_1(s, a) + \frac{\tilde{\varphi}'(s)\sqrt{H(s, a)}}{\tilde{\varphi}(s)} \right)^2 ds \Big\} + \frac{1}{H(b, c)} \left\{ \int_c^b e^{\tilde{R}(s)}\tilde{\varphi}(s)\tilde{Q}(s)m \right. \\
 &\quad \times H(b, s) ds - \int_c^b \frac{\tilde{\varphi}(s)e^{\tilde{R}(s)}\tilde{r}(s)}{4} \left( -h_2(b, s) + \frac{\tilde{\varphi}'(s)\sqrt{H(b, s)}}{\tilde{\varphi}(s)} \right)^2 ds \Big\} \\
 &\leq 0, \tag{40}
 \end{aligned}$$

which contradicts Eq. (33). The proof is complete.  $\square$



**Theorem 3.3** *Suppose conditions (A<sub>1</sub>)–(A<sub>3</sub>) hold, and (14)–(15) are also true. If, for any  $T \geq t_0$ , there exists an interval  $(a, b) \in [T, \infty)$ , and there exists a  $c \in (a, b)$ ,  $H \in R$ , such that*

$$\limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(s, l) ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \times \left( h_1(s, l) + \frac{\tilde{\varphi}'(s) \sqrt{H(s, l)}}{\tilde{\varphi}(s)} \right)^2 ds \right\} > 0, \tag{41}$$

$$\limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(t, s) ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \times \left( -h_2(t, s) + \frac{\tilde{\varphi}'(s) \sqrt{H(t, s)}}{\tilde{\varphi}(s)} \right)^2 ds \right\} > 0, \tag{42}$$

then, for  $l \in [t_0, \infty)$ ,  $t_1 > t_0$  positive, every solution of (5) is oscillatory.

*Proof* Suppose to the contrary that  $u(x, t)$  is a nonoscillatory solution of (5). Without loss of generality, we can assume that there exists  $u(x, t) > 0$  and  $u(x, t - \tau_i) > 0$  in  $G \times [t_0, \infty)$  for some  $t_2 \geq t_1, i = 1, 2, \dots, m$ .

Letting  $l = a \geq t_2$  in (41), according to (41) we have  $c > a$  such that

$$\int_a^c e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(s, a) ds - \int_a^c \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \times \left( h_1(s, a) + \frac{\tilde{\varphi}'(s) \sqrt{H(s, a)}}{\tilde{\varphi}(s)} \right)^2 ds > 0. \tag{43}$$

Letting  $l = c \geq t_2$  in (42), according to (42) we have  $b > c$  such that

$$\int_c^b e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m H(b, s) ds - \int_c^b \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \times \left( -h_2(b, s) + \frac{\tilde{\varphi}'(s) \sqrt{H(b, s)}}{\tilde{\varphi}(s)} \right)^2 ds > 0. \tag{44}$$

According to (43) and (44) we find that (33) is true. Then every solution of (5) is oscillatory. □

If we let  $H(t, s) = (t - s)^\lambda$ , where  $t \geq s \geq t_0$ , we have the following lemma.

**Lemma 3.1** *Suppose conditions (A<sub>1</sub>)–(A<sub>3</sub>) hold, and (14)–(15) are also true. Then the following inequalities are true:*

$$\limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m (s - l)^\lambda ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \times \left( \lambda (s - l)^{\frac{\lambda-2}{2}} + \frac{\tilde{\varphi}'(s) (s - l)^{\frac{\lambda}{2}}}{\tilde{\varphi}(s)} \right)^2 ds \right\} > 0, \tag{45}$$

$$\limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m (t - s)^\lambda ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4}$$

$$\times \left( -\lambda(t-s)^{\frac{\lambda-2}{2}} + \frac{\tilde{\varphi}'(s)(t-s)^{\frac{\lambda}{2}}}{\tilde{\varphi}(s)} \right)^2 ds \Big\} > 0. \tag{46}$$

Then, for every  $l \geq t_0$ , Eq. (5) is oscillatory.

In general, considering  $H(t, s) = (K(t) - K(s))^\lambda$ , where  $K(t) = \int_{t_1}^t \frac{1}{r(s)} ds$ , we have the following lemma.

**Lemma 3.2** *Suppose conditions (A<sub>1</sub>)–(A<sub>3</sub>) hold, and (14)–(15) are also true. Then the following inequalities are true:*

$$\begin{aligned} & \limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m(K(s) - K(l))^\lambda ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \right. \\ & \times \left. \left( \frac{\lambda(K(s) - K(l))^{\frac{\lambda-2}{2}}}{r(s)} + \frac{\tilde{\varphi}'(s)(K(s) - K(l))^{\frac{\lambda}{2}}}{\tilde{\varphi}(s)} \right)^2 ds \right\} > 0, \end{aligned} \tag{47}$$

$$\begin{aligned} & \limsup_{t \rightarrow \infty} \left\{ \int_l^t e^{\tilde{R}(s)} \tilde{\varphi}(s) \tilde{Q}(s) m(K(t) - K(s))^\lambda ds - \int_l^t \frac{\tilde{\varphi}(s) e^{\tilde{R}(s)} \tilde{r}(s)}{4} \right. \\ & \times \left. \left( -\frac{\lambda(K(t) - K(s))^{\frac{\lambda-2}{2}}}{r(s)} + \frac{\tilde{\varphi}'(s)(K(t) - K(s))^{\frac{\lambda}{2}}}{\tilde{\varphi}(s)} \right)^2 ds \right\} > 0. \end{aligned} \tag{48}$$

Then, for every  $l \geq t_0$ , Eq. (5) is oscillatory.

### 4 Examples

*Example 4.1* Consider the following fractional partial differential equation:

$$\begin{aligned} & D_{+,t}^\alpha (e^t D_{+,t}^\alpha u(x, t)) + (t-1) D_{+,t}^\alpha u(x, t) + (t^2 + x^2)(u(x, t) + 1) \\ & = t \Delta u(x, t) + 5t \Delta u(x, t-1), \quad (x, t) \in (0, \pi) \times (0, \infty), \end{aligned} \tag{49}$$

with the Robin boundary condition

$$u_x(0, t) = u_x(\pi, t) = 0. \tag{50}$$

Notice  $\alpha \in (0, 1)$ ,  $r(t) = e^t$ ,  $p(t) = t - 1$ ,  $q(x, t) = t^2 + x^2$ ,  $Q(t) = t^2$ ,  $f(x) = x + 1$ ,  $m = 1$ ,  $a(t) = t$ ,  $b_1(t) = 5t$ ,  $\tau_1 = 1$ ,  $\Omega = (0, \pi)$ .

Then (49) is oscillatory by Theorem 3.1.

*Example 4.2* Consider the following fractional partial differential equation:

$$\begin{aligned} & D_{+,t}^{\frac{1}{2}} \left( \frac{1}{t} D_{+,t}^{\frac{1}{2}} u(x, t) \right) + t(t^2 - 1) D_{+,t}^{\frac{1}{2}} u(x, t) + te^x 2u(x, t) \\ & = e^t \Delta u(x, t) + e^t \Delta u(x, t-3), \quad (x, t) \in (0, \pi) \times (0, \infty), \end{aligned} \tag{51}$$

with the Robin boundary condition

$$u_x(0, t) = u_x(\pi, t) = 0. \tag{52}$$

Notice  $\alpha = \frac{1}{2}$ ,  $r(t) = \frac{1}{t}$ ,  $p(t) = t(t^2 - 1)$ ,  $q(x, t) = te^x$ ,  $Q(t) = t$ ,  $f(x) = 2x$ ,  $m = 1$ ,  $a(t) = e^t$ ,  $b_1(t) = e^t$ ,  $\tau_1 = 3$ ,  $\Omega = (0, \pi)$ .

Then (51) is oscillatory by Theorem 3.1.

## 5 Conclusion

In this paper, we illustrate the sufficient conditions for oscillation criteria of certain fractional partial differential equations by using the generalized Riccati transformation and Riemann–Liouville derivative. The proof has become concise with the aid of fractional calculus and fractional derivatives. The results provide some new methods to research the oscillation criteria of fractional partial differential equations.

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### Authors' contributions

The authors state that assignments have been finished, respectively. All authors read and approved the final manuscript.

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