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# Fixed point problems for generalized contractions with applications

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## Abstract

In this paper, we investigate the conditions on the control mappings  $\psi, \varphi : (0, \infty) \rightarrow \mathbb{R}$  that guarantee the existence of the fixed points of the mapping  $T : X \rightarrow P(X)$  satisfying the following inequalities:

$$\psi(H(Tx, Ty)) \leq \varphi(d(x, y)) \quad \forall x, y \in X, \text{ provided that } H(Tx, Ty) > 0,$$

and

$$\psi(H(Tx, Ty)) \leq \varphi(A(x, y)) \quad \forall x, y \in X, \text{ provided that } H(Tx, Ty) > 0,$$

where  $A(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty), (d(x, Ty) + d(Tx, y))/2\}$ , and  $(X, d)$  is a metric space. The obtained fixed point results improve many earlier results on the set-valued contractions. As an application, we consider the existence of the solutions of an FDE.

**MSC:** 47H10; 26E05; 26E25

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## 1 Introduction and preliminaries

The metric fixed point theory was initiated by Banach (1922) [15]. This theory has been enriched with well-known structures and metric generalizations. Recently, Chifu [20] established common fixed point theorems endowed with directed graphs in extended b-metric spaces. Ozturk [31] proved a fixed point theorem involving a simulation function and F-contraction. Ozyurt [33] presented fixed point theorems covering a comparison function and large contractions. In [32] the author proved some results on  $\alpha - \varphi$  contractions in Branciari b-metric spaces. The study of F-metric spaces attracted attention of many researchers, and in this direction, several papers were published (see [11, 12, 16]). The existence of solutions of FDEs, IEs, ODEs, and PDEs was investigated by applying various known fixed point results; see [4, 6, 9, 13, 17, 30, 38, 39] for details. A useful generalization of the Banach contraction principle is an F-contraction presented by Wordowski [40]; a survey on this contraction is given in [25]. The notion of F-contraction was generalized using various structures; see [1, 25, 30] for details. Boyd and Wong [18] introduced

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mapping  $\psi : [0, \infty) \rightarrow [0, \infty)$  that satisfy the following conditions to generalize the Banach contraction principle:

- (1)  $\psi(y) < y$  for all  $y > 0$ ,
- (2)  $\lim_{x \rightarrow y^+} \psi(x) < y$  for all  $y > 0$ .

Boyd and Wong [18] used such mapping to present the following result.

**Theorem 1.1** *Let  $(X, d)$  be a complete metric space, and let  $T : X \rightarrow X$  be a mapping satisfying the following contractive condition:*

$$d(Tx, Ty) \leq \psi(d(x, y)) \quad \text{for all } x, y \in X,$$

where  $\psi : [0, \infty) \rightarrow [0, \infty)$  satisfies (1)–(2). Then  $T$  admits a unique fixed point  $u$  in  $X$ , and  $(T^n x) \rightarrow u$  for all  $x \in X$ .

Note that Theorem 1.1 improves the fixed point theorems given by Rakotch [35] and Browder [19]. Recently, Proinov [34] presented a generalization of F-contraction, JS-contraction [24], and many recent results by introducing  $(\phi, \psi)$ -generalized contractions. Using the mappings  $\psi, \phi : (0, \infty) \rightarrow (-\infty, \infty)$ , he introduced the following contractive-type conditions:

$$\begin{aligned} \psi(d(Tx, Ty)) &\leq \phi(d(x, y)) \\ \forall x, y \in X, \text{ provided that } \min\{d(x, y), d(Tx, Ty)\} &> 0, \end{aligned} \tag{1.1}$$

and

$$\begin{aligned} \psi(d(Tx, Ty)) &\leq \phi(A(x, y)) \\ \forall x, y \in X, \text{ provided that } \min\{A(x, y), d(Tx, Ty)\} &> 0, \end{aligned} \tag{1.2}$$

where  $A(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty), (d(x, Ty) + d(Tx, y))/2\}$  and  $T : X \rightarrow X$ . In this paper, we call them  $(\psi, \phi)$ -contractions.

Proinov [34] established the following fixed point results.

**Theorem 1.2** *Let  $(X, d)$  be a complete metric space, and let  $T : X \rightarrow X$  be a mapping satisfying (1.1). Suppose the mappings  $\psi, \phi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i)  $\psi$  is nondecreasing;
- (ii)  $\phi(y) < \psi(y)$  for all  $y > 0$ ;
- (iii)  $\limsup_{y \rightarrow r^+} \phi(y) < \psi(r)$  for all  $r > 0$ .

Then  $T$  has a unique fixed point  $p \in X$ , and the iterative sequence  $(T^n x)$  converges to  $p$  for all  $x \in X$ .

**Theorem 1.3** ([34]) *Let  $(X, d)$  be a complete metric space, and let  $T : X \rightarrow X$  be a mapping satisfying (1.1). Suppose the mappings  $\psi, \phi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i)  $\phi(y) < \psi(y)$  for all  $y > 0$ ;
- (ii)  $\inf_{y > \epsilon} \psi(y) > -\infty$  for all  $\epsilon > 0$ ;

(iii) if  $(\psi(y_n))$  and  $(\varphi(y_n))$  are convergent sequences such that

$$\lim_{n \rightarrow \infty} \psi(y_n) = \lim_{n \rightarrow \infty} \varphi(y_n) \text{ and } (\psi(y_n)) \text{ is strictly decreasing, then } \lim_{n \rightarrow \infty} y_n = 0;$$

(iv)  $\limsup_{y \rightarrow \epsilon^+} \varphi(y) < \liminf_{y \rightarrow \epsilon} \psi(y)$  or  $\limsup_{y \rightarrow \epsilon} \varphi(y) < \liminf_{y \rightarrow \epsilon^+} \psi(y)$  for all  $\epsilon > 0$ ;

(v)  $T$  has a closed graph, or  $\limsup_{y \rightarrow 0^+} \varphi(y) < \liminf_{y \rightarrow \epsilon} \psi(y)$  for all  $\epsilon > 0$ .

Then  $T$  has a unique fixed point  $u \in X$ , and the iterative sequence  $(T^n x)$  converges to  $u$  for all  $x \in X$ .

**Remark 1.4** Theorems 1.2 and 1.3 also hold if we replace contractive condition (1.1) with (1.2).

The following lemma is often seen in different papers (see [18, 34]) and provides a method to prove that a sequence to be Cauchy.

**Lemma 1.5** Let  $(X, d)$  be a metric space, and let  $\{q_n\} \subset X$  be a sequence such that  $\lim_{n \rightarrow \infty} d(q_n, q_{n+1}) = 0$ . If the sequence  $\{q_n\}$  is not Cauchy, then there exist two subsequences  $\{q_{n_k}\}$  and  $\{q_{m_k}\}$  and  $\epsilon > 0$  such that

$$\lim_{k \rightarrow \infty} d(q_{n_k+1}, q_{m_k+1}) = \epsilon + \tag{1.3}$$

and

$$\lim_{k \rightarrow \infty} d(q_{n_k}, q_{m_k}) = d(q_{n_k+1}, q_{m_k}) = d(q_{n_k}, q_{m_k+1}) = \epsilon. \tag{1.4}$$

For the control mappings  $\psi, \varphi : (0, \infty) \rightarrow \mathbb{R}$ , the following conditions are needed for the upcoming results:

- (i)  $\inf_{x > \epsilon} \psi(x) > -\infty$  for any  $\epsilon > 0$ .
- (ii)  $\liminf_{x \rightarrow \epsilon^+} \psi(x) > -\infty$  for any  $\epsilon > 0$ .
- (iii)  $\lim_{n \rightarrow \infty} \psi(x_n) = -\infty$  implies  $\lim_{n \rightarrow \infty} x_n = 0$ .
- (iv)  $\lim_{n \rightarrow \infty} \varphi(x_n) = 0$  implies  $\lim_{n \rightarrow \infty} x_n = 0$ , where  $\{x_n\}$  is a bounded sequence.
- (v)  $\liminf_{x \rightarrow \epsilon} \varphi(x) > 0$  for all  $\epsilon > 0$ .
- (vi)  $\limsup_{x \rightarrow \epsilon} \varphi(x) < \liminf_{x \rightarrow \epsilon} \psi(x)$  for all  $\epsilon > 0$ .
- (vii) If  $\{x_n\}$  is a positive bounded sequence and if  $\{\psi(x_n)\}$  and  $\{\varphi(x_n)\}$  are two convergent sequences having the same limit, then  $\lim_{n \rightarrow \infty} x_n = 0$ .

In the following conditions, we let  $\varphi : (0, \infty) \rightarrow (0, \infty)$ .

- (viii) If  $\lim_{n \rightarrow \infty} x_n = \epsilon > 0$ , then  $\liminf_{n \rightarrow \infty} \varphi(x_n) > 0$ .
- (ix)  $\liminf_{x \rightarrow \epsilon} \varphi(x) > 0$  for all  $\epsilon > 0$ .
- (x)  $\limsup_{x \rightarrow \epsilon} \varphi(x) > \limsup_{x \rightarrow \epsilon} \psi(x) - \liminf_{x \rightarrow \epsilon} \psi(x)$ .

Using conditions (i)–(x), Proinov [34] obtained the following lemma.

**Lemma 1.6** ([34])

- (1) Let  $\psi : (0, \infty) \rightarrow \mathbb{R}$ . Then conditions (i), (ii), and (iii) are equivalent.
- (2) Let  $\varphi : (0, \infty) \rightarrow \mathbb{R}$ . Then condition (iv) implies (v).
- (3) Let  $\varphi : (0, \infty) \rightarrow (0, \infty)$ . Then conditions (viii), (vi), and (ix) are equivalent.
- (4) Let  $\psi, \varphi : (0, \infty) \rightarrow \mathbb{R}$  be two mappings satisfying conditions (vi) and (vii). Then  $\lim_{n \rightarrow \infty} x_n = 0$ .
- (5) Let  $\varphi : (0, \infty) \rightarrow (0, \infty)$  and  $\psi : (0, \infty) \rightarrow \mathbb{R}$ . Then condition (x) implies (iv).

Let  $(\mathcal{A}, d)$  be a metric space, let  $P(\mathcal{A})$  denote the set of all nonempty subsets of  $\mathcal{A}$ , let  $P_{cb}(\mathcal{A})$  denote the set of all nonempty closed bounded subsets of  $\mathcal{A}$ , and let  $C(\mathcal{A})$  denote the compact subsets of  $\mathcal{A}$ .

Let  $d(q, A) = \inf_{a \in A} d(q, a)$ , and let the mapping

$$H : P(\mathcal{A}) \times P(\mathcal{A}) \rightarrow [0, \infty)$$

be defined by

$$H(A, B) = \max \left\{ \sup_{q \in A} D(q, B), \sup_{b \in B} D(b, A) \right\}.$$

The mapping  $H$  satisfies all the axioms of metric and is known as the Hausdorff metric induced by the metric  $d$ .

**Definition 1.7** Let  $T : \mathcal{A} \rightarrow P(\mathcal{A})$  be a set-valued mapping. A point  $\sigma \in \mathcal{A}$  is said to be a fixed point of  $T$  if  $\sigma \in T(\sigma)$ .

**Definition 1.8** Let  $T : \mathcal{A} \rightarrow P(\mathcal{A})$  and  $f : \mathcal{A} \times \mathcal{A} \rightarrow [0, \infty)$ . The mapping  $T$  is said to be strictly  $f$ -admissible if for all  $q \in \mathcal{A}$  and  $\varsigma \in T(q)$  with  $f(q, \varsigma) > 1$ , there exists  $\omega \in T(\varsigma)$  such that  $f(\varsigma, \omega) > 1$ .

**Definition 1.9** Let  $(\mathcal{A}, d)$  be a metric space, and let  $f : \mathcal{A} \times \mathcal{A} \rightarrow [0, \infty)$ . The space  $(\mathcal{A}, d)$  is said to be strictly  $f$ -regular if for any sequence  $\{q_n\} \subset \mathcal{A}$  such that  $f(q_n, q_{n+1}) > 1$  for all  $n \in \mathbb{N}$  and  $q_n \rightarrow q$  as  $n \rightarrow \infty$ , we have  $f(q_n, q) > 1$  for all  $n \in \mathbb{N}$ .

**Definition 1.10** A mapping  $T : (X, d) \rightarrow (X, d)$  is said to be asymptotically regular at a point  $x$  of  $X$  if

$$\lim_{n \rightarrow \infty} d(T^n x, T^{n+1} x) = 0.$$

If  $T$  is asymptotically regular at every point of  $X$ , then it is called an asymptotically regular mapping.

Lemma 1.11 plays a key role in the upcoming results.

**Lemma 1.11** ([29]) *Let  $A$  and  $B$  be nonempty closed bounded subsets of a metric space  $(\mathcal{A}, d)$ , and let  $q > 1$ . Then for all  $a \in A$ , there exists  $b \in B$  such that  $d(a, b) \leq qH(A, B)$ .*

## 2 Set-valued $(\psi, \varphi)_f$ -contractions and related fixed point problems

In this section, we introduce set-valued  $(\psi, \varphi)_f$ -contractions. We discuss their nature and generality. We investigate various conditions for the existence of fixed points of set-valued  $(\psi, \varphi)_f$ -contractions.

**Definition 2.1** Let  $(\mathcal{A}, d)$  be a metric space. A mapping  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  is said to be a set-valued  $(\psi, \varphi)_f$ -contraction if there exists  $f : \mathcal{A} \times \mathcal{A} \rightarrow [0, \infty)$ , such that

$$\psi(f(q, \varsigma)H(T(q), T(\varsigma))) \leq \varphi(d(q, \varsigma)) \tag{2.1}$$

for all  $q, \varsigma \in \mathcal{A}$  with  $f(q, \varsigma) > 1$  and  $H(T(q), T(\varsigma)) > 0$ .

*Remark 2.2* Inequality (2.1) reduces to multivalued F-contraction [2] if  $\varphi(\sigma) = \psi(\sigma) - \tau$  for all  $\sigma \in (0, \infty)$ . Moreover, it turns into Nadler contraction [29] for  $\psi(\sigma) = \ln(\sigma)$ . Let  $\psi : (0, \infty) \rightarrow (0, \infty)$  be a nondecreasing mapping, and let  $\beta : (0, \infty) \rightarrow (0, 1)$  be a mapping satisfying  $\limsup_{y \rightarrow \epsilon^+} \beta(y) < 1$  for any  $\epsilon > 0$ . Then substituting  $\varphi(y) = \beta(y)\psi(y)$  and  $\psi(y) = y$  for all  $y > 0$ , we obtain a very famous multivalued Geraghty’s contraction discussed in [5].

The following theorem suggests a set of conditions for the existence of a fixed point of mapping  $T$ .

**Theorem 2.3** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space. Let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be an  $f$ -admissible mapping satisfying (2.1). Suppose the mappings  $\psi, \varphi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i) *for any  $q_0 \in \mathcal{A}$ , there exists  $q_1 \in T(q_0)$  such that  $f(q_0, q_1) \geq 1$ ;*
- (ii)  *$\psi$  is nondecreasing, and  $\varphi(y) < \psi(y)$  for all  $y > 0$ ;*
- (iii)  *$\limsup_{y \rightarrow r^+} \varphi(y) < \psi(r)$  for all  $r > 0$ .*

*Then  $T$  admits a fixed point in  $\mathcal{A}$ .*

*Proof* Step 1. By assumption (i), for any  $q_0 \in \mathcal{A}$ , there exists  $q_1 \in T(q_0)$  such that  $f(q_0, q_1) > 1$ . Since  $T$  is an  $f$ -admissible mapping, there exists  $q_2 \in T(q_1)$  such that  $f(q_1, q_2) > 1$  and  $q_3 \in T(q_2)$  such that  $f(q_2, q_3) > 1$ . In general, there exist  $q_{n+1} \in T(q_n)$  such that  $f(q_n, q_{n+1}) > 1$  for all  $n \geq 0$ . Note that if  $q_n \in T(q_n)$ , then  $q_n$  is a fixed point of  $T$  for all  $n \geq 0$ . So we assume that  $q_n \notin T(q_n)$  for all  $n \geq 0$ . Thus  $H(Tq_{n-1}, Tq_n) > 0$ ; otherwise,  $q_n \in Tq_n$ . Since  $f(q_n, q_{n+1}) > 1$  and  $T(q_n), T(q_{n+1})$  are closed and bounded sets for all  $n \geq 0$ , by Lemma 1.11 there exist  $q_{n+1} \in T(q_n)$  ( $q_n \neq q_{n+1}$ ) such that  $d(q_n, q_{n+1}) \leq f(q_{n-1}, q_n)H(T(q_{n-1}), T(q_n))$  for all  $n \geq 1$ . By first part of (ii) and (2.1) we have

$$\psi(d(q_n, q_{n+1})) \leq \psi(f(q_{n-1}, q_n)H(T(q_{n-1}), T(q_n))) \leq \varphi(d(q_{n-1}, q_n)).$$

By the second part of assumption (ii) we have

$$\psi(d(q_n, q_{n+1})) \leq \varphi(d(q_{n-1}, q_n)) < \psi(d(q_{n-1}, q_n)). \tag{2.2}$$

Since  $\psi$  is a nondecreasing mapping,  $d(q_n, q_{n+1}) < d(q_{n-1}, q_n)$  for every  $n \geq 1$ . This shows that the sequence  $\{d(q_{n-1}, q_n)\}$  is positively decreasing. Thus there exists  $L \geq 0$  such that  $\lim_{n \rightarrow \infty} d(q_{n-1}, q_n) = L$ . If  $L > 0$ , then by (2.2) we obtain a contradiction to assumption (iii) as follows:

$$\psi(L) = \lim_{n \rightarrow \infty} \psi(d(q_n, q_{n+1})) \leq \lim_{n \rightarrow \infty} \sup \varphi(d(q_{n-1}, q_n)) \leq \lim_{\sigma \rightarrow L^+} \sup \varphi(\sigma).$$

Hence  $L = 0$ , and, consequently,  $T$  is an asymptotically regular mapping.

Step 2. We show that  $\{q_n\}$  is a Cauchy sequence. Assume on the contrary that  $\{q_n\}$  is not a Cauchy sequence. In this case, by Lemma 1.5 there exist two subsequences  $\{q_{n_k}\}, \{q_{m_k}\}$  of  $\{q_n\}$  and  $\epsilon > 0$  such that (1.3) and (1.4) hold. By (1.3) we infer that  $d(q_{n_k+1}, q_{m_k+1}) > \epsilon$  and  $f(q_{n_k}, q_{m_k}) > 1$  for all  $k \geq 1$ . Letting  $q = q_{n_k}$  and  $\zeta = q_{m_k}$  in (2.1), we have

$$\psi(d(q_{n_k+1}, q_{m_k+1})) \leq \psi(f(q_{n_k}, q_{m_k})H(Tq_{n_k}, Tq_{m_k})) \leq \varphi(d(q_{n_k}, q_{m_k})) \quad \text{for all } k \geq 1,$$

since if  $a_k = d(q_{n_k+1}, q_{m_k+1})$  and  $b_k = d(q_{n_k}, q_{m_k})$ , then

$$\psi(a_k) \leq \varphi(b_k) < \psi(b_k) \quad \text{for any } k \geq 1 \text{ implies that } a_k < b_k.$$

Since  $\lim_{k \rightarrow \infty} a_k = \epsilon +$ , we also have  $\lim_{k \rightarrow \infty} b_k = \epsilon +$ . Thus

$$\psi(\epsilon +) = \lim_{k \rightarrow \infty} \psi(a_k) \leq \lim_{k \rightarrow \infty} \sup \varphi(b_k) \leq \lim_{\sigma \rightarrow \epsilon +} \varphi(\sigma).$$

This is a contradiction to assumption (iii), and, consequently,  $\{q_n\}$  is a Cauchy sequence in  $(\mathcal{A}, d)$ . Since  $(\mathcal{A}, d)$  is a complete metric space, there exists  $q^* \in \mathcal{A}$  such that  $q_n \rightarrow q^*$  as  $n \rightarrow \infty$ , and the  $f$ -regularity of the space  $(\mathcal{A}, d)$  implies  $f(q_n, q^*) > 1$ . We claim that  $d(q^*, T(q^*)) = 0$ . On the contrary, assume that  $d(q^*, T(q^*)) > 0$ . Then there exists  $n_1 \in \mathbb{N}$  such that  $d(q_n, T(q^*)) > 0$  for each  $n \geq n_1$ . By (2.1)

$$\psi(d(q_{n+1}, T(q^*))) \leq \psi(f(q_n, q^*)H(T(q_n), T(q^*))) \leq \varphi(d(q_n, q^*)) < \psi(d(q_n, q^*)).$$

By the first part of assumption (ii) we have  $d(q_{n+1}, T(q^*)) < d(q_n, q^*)$ . Taking the limit on both sides of the last inequality as  $n \rightarrow \infty$ , we have  $d(q^*, T(q^*)) < 0$ . This implies  $d(q^*, T(q^*)) = 0$ . Since  $T(q^*)$  is closed,  $q^* \in T(q^*)$ . The uniqueness of  $q^*$  is obvious from the contractive condition (2.1). □

The following theorem suggests another set of conditions for the existence of a fixed point of a self-mapping  $T$  satisfying (2.1).

**Theorem 2.4** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space. Let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be an  $f$ -admissible mapping satisfying (2.1). Suppose mappings  $\psi, \varphi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i) *for all  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ ;*
- (ii)  *$\psi$  is nondecreasing, and  $\varphi(y) < \psi(y)$  for all  $y > 0$ ;*
- (iii)  *$\inf_{\sigma > \epsilon} \psi(\sigma) > -\infty$ ;*
- (iv) *if the sequences  $\{\psi(\sigma_n)\}$  and  $\{\varphi(\sigma_n)\}$  converge to the same limit and  $\{\psi(\sigma_n)\}$  is strictly decreasing, then  $\lim_{n \rightarrow \infty} \sigma_n = 0$ ;*
- (v)  *$\limsup_{\sigma \rightarrow \epsilon} \varphi(\sigma) < \liminf_{\sigma \rightarrow \epsilon+} \psi(\sigma)$  for all  $\epsilon > 0$ ;*
- (vi)  *$\limsup_{\sigma \rightarrow \epsilon_1} \varphi(\sigma) < \liminf_{\sigma \rightarrow \epsilon} \varphi(\sigma)$  for all  $\epsilon, \epsilon_1 > 0$ .*

*Then  $T$  has a unique fixed point in  $\mathcal{A}$ .*

*Proof* For the proof, the first four conditions (i)–(iv) are needed to prove that  $T$  is asymptotically regular. Condition (v) is required to prove that  $\{q_n\}$  is a Cauchy sequence, and condition (vi) is helpful to show the existence of a fixed point.

By assumption (i), for any  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) > 1$ . Since  $T$  is an  $f$ -admissible mapping, there exist  $\sigma_2 \in T(\sigma_1)$  such that  $f(\sigma_1, \sigma_2) > 1$  and  $\sigma_3 \in T(\sigma_2)$  such that  $f(\sigma_2, \sigma_3) > 1$ . In general, there exist  $\sigma_{n+1} \in T(\sigma_n)$  such that  $f(\sigma_n, \sigma_{n+1}) > 1$  for all  $n \geq 0$ . Note that if  $\sigma_n \in T(\sigma_n)$ , then  $\sigma_n$  is a fixed point of  $T$  for all  $n \geq 0$ . We assume that  $\sigma_n \notin T(\sigma_n)$  for all  $n \geq 0$ . Thus  $H(T\sigma_{n-1}, T\sigma_n) > 0$ ; otherwise,  $\sigma_n \in T\sigma_n$ . Since  $f(\sigma_n, \sigma_{n+1}) > 1$  and  $T(\sigma_n), T(\sigma_{n+1})$  are closed bounded sets for all  $n \geq 0$ , by Lemma 1.11 there exists

$\sigma_{n+1} \in T(\sigma_n)$  ( $\sigma_n \neq \sigma_{n+1}$ ) such that  $d(\sigma_n, \sigma_{n+1}) \leq f(\sigma_{n-1}, \sigma_n)H(T(\sigma_{n-1}), T(\sigma_n))$  for all  $n \geq 1$ . By the first part of (ii) and (2.1) we have that for all  $n \geq 1$ ,

$$\begin{aligned} \psi(d(\sigma_n, \sigma_{n+1})) &\leq \psi(f(\sigma_{n-1}, \sigma_n)H(T(\sigma_{n-1}), T(\sigma_n))) \\ &\leq \varphi(d(\sigma_{n-1}, \sigma_n)) < \psi(d(\sigma_{n-1}, \sigma_n)). \end{aligned} \tag{2.3}$$

Inequality (2.3) shows that  $\{\psi(d(\sigma_{n-1}, \sigma_n))\}$  is a strictly decreasing sequence. Then it is either bounded below or not. If it is not bounded below, then by assumption (iii) and Lemma 1.6(1) we infer that  $\lim_{n \rightarrow \infty} d(\sigma_{n-1}, \sigma_n) = 0$ . If it bounded below, then  $\{\psi(d(\sigma_{n-1}, \sigma_n))\}$  is a convergent sequence, and by (2.3) the sequence  $\{\varphi(d(\sigma_{n-1}, \sigma_n))\}$  also converges, and both have the same point of convergence. Thus by assumption (iv) we have  $\lim_{n \rightarrow \infty} d(\sigma_{n-1}, \sigma_n) = 0$ . Hence  $T$  is asymptotically regular.

Following Step 2 of the proof of Theorem 2.3, we have

$$\psi(a_k) \leq \varphi(b_k), \quad \text{for any } k \geq 1. \tag{2.4}$$

By (1.3) and (1.4) we have  $\lim_{k \rightarrow \infty} a_k = \epsilon +$  and  $\lim_{k \rightarrow \infty} b_k = \epsilon$ . By (2.4) we infer that

$$\liminf_{\sigma \rightarrow \epsilon+} \psi(\sigma) \leq \liminf_{k \rightarrow \infty} \psi(a_k) \leq \limsup_{k \rightarrow \infty} \varphi(b_k) \leq \limsup_{\sigma \rightarrow \epsilon} \varphi(\sigma).$$

This is a contradiction to (v), and hence  $\{\sigma_n\}$  is a Cauchy sequence in  $(\mathcal{A}, d)$ . Since  $(\mathcal{A}, d)$  is a complete metric space, there exists  $\sigma^* \in \mathcal{A}$  such that  $\sigma_n \rightarrow \sigma^*$  as  $n \rightarrow \infty$ .

Now we have to prove that the point of convergence  $\sigma^*$  is a fixed point of  $T$ . We consider two cases.

Case 1. If  $d(\sigma_{n+1}, T\sigma^*) = 0$  for some  $n \geq 0$ , then by the triangle property of  $d$  we obtain

$$d(\sigma^*, T\sigma^*) \leq d(\sigma^*, \sigma_{n+1}) + d(\sigma_{n+1}, T\sigma^*) = d(\sigma^*, \sigma_{n+1}).$$

Taking the limit as  $n \rightarrow \infty$  on both sides, we have  $d(\sigma^*, T\sigma^*) \leq 0$ . This implies  $d(\sigma^*, T\sigma^*) = 0$ . Since  $T(\sigma^*)$  is closed,  $\sigma^* \in T(\sigma^*)$ .

Case 2. If  $d(\sigma_{n+1}, T\sigma^*) > 0$  for all  $n \geq 0$ , then by the  $f$ -regularity of the space  $(\mathcal{A}, d)$  we have  $f(\sigma_n, \sigma^*) > 1$ . By contractive condition (2.1) we have

$$\psi(d(\sigma_{n+1}, T\sigma^*)) \leq \psi(f(\sigma_n, \sigma^*)H(T\sigma_n, T\sigma^*)) \leq \varphi(d(\sigma_n, \sigma^*)) \quad \text{for all } n \geq 0.$$

Let  $a_n = d(\sigma_{n+1}, T\sigma^*)$  and  $b_n = d(\sigma_n, \sigma^*)$ . Then the last inequality reduces to

$$\psi(a_n) \leq \varphi(b_n) \quad \text{for all } n \geq 0. \tag{2.5}$$

Let  $\epsilon = d(\sigma^*, T\sigma^*)$ . Then we observe that  $a_n \rightarrow \epsilon$  and  $b_n \rightarrow 0$  as  $n \rightarrow \infty$ . Applying the limits on (2.5), we have

$$\liminf_{\sigma \rightarrow \epsilon} \psi(\sigma) \leq \liminf_{n \rightarrow \infty} \psi(a_n) \leq \limsup_{n \rightarrow \infty} \varphi(b_n) \leq \liminf_{\sigma \rightarrow 0} \varphi(\sigma).$$

The last inequality is a contradiction to assumption (vi) if  $\epsilon > 0$ . Thus we have  $d(\sigma^*, T\sigma^*) = 0$ . Hence  $\sigma^* \in T\sigma^*$ , that is,  $\sigma^*$  is a fixed point of  $T$ . The uniqueness of  $\sigma^*$  is obvious from the contractive condition (2.1). □

Note that Theorems 2.3 and 2.4 reduce to the Nadler fixed point theorem [15] if  $\psi(y) = y$  and  $\varphi(y) = \lambda y$  for all  $y > 0$  and  $0 \leq \lambda < 1$ . If  $\psi(y) = y$  for all  $y > 0$ , then they reduce to the multivalued version of the Boyd–Wong fixed point theorem (Theorem 1.1). By substituting  $\varphi(y) = \psi(y) - \tau$  into Theorems 2.3 and 2.4 we obtain an improvement of fixed point theorems established in [2, 22] and of the results presented by Secelean [36] and Lukacs and Kajanto [27] as follows.

**Corollary 2.5** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space, and let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be a set-valued strictly  $f$ -admissible mapping satisfying the following inequality:*

$$\psi(f(x, y)H(Tx, Ty)) \leq \psi(d(x, y)) - \tau \quad \forall x, y \in \mathcal{A}, \text{ provided that } H(Tx, Ty) > 0,$$

where  $\psi : (0, \infty) \rightarrow \mathbb{R}$  is a nondecreasing mapping, and  $\tau > 0$ . If for any initial guess  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ , then  $T$  has a unique fixed point in  $\mathcal{A}$ .

If  $\psi$  is lower semicontinuous and  $\varphi$  is upper semicontinuous, then Theorem 2.4 is an improvement of the Amini–Harandi–Petrusel fixed point theorem [10]. If we take  $\varphi(y) = h(\psi(y))$  in Theorem 2.3, we obtain the following improvement of Moradi’s theorem [28].

**Corollary 2.6** *Let  $(\mathcal{A}, d)$  be a  $f$ -regular complete metric space, and let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be a set-valued strictly  $f$ -admissible mapping satisfying the following inequality:*

$$\psi(f(x, y)H(Tx, Ty)) \leq h(\psi(d(x, y))) \quad \forall x, y \in \mathcal{A}, \text{ provided } H(Tx, Ty) > 0,$$

where

- (i)  $h : I \rightarrow [0, \infty)$  is an upper semicontinuous mapping such that  $h(y) < y$  for all  $y \in I \subset \mathbb{R}$ ;
- (ii)  $\psi : (0, \infty) \rightarrow I$  is nondecreasing.

If for any initial guess  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ , then  $T$  has a unique fixed point in  $\mathcal{A}$ .

Taking  $h(y) = y^r$  with  $r \in (0, 1)$  in Corollary 2.6, we obtain the following result.

**Corollary 2.7** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space, and let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be a set-valued strictly  $f$ -admissible mapping satisfying the following inequality:*

$$\psi(f(x, y)H(Tx, Ty)) \leq (\psi(d(x, y)))^r \quad \forall x, y \in \mathcal{A}, \text{ provided that } H(Tx, Ty) > 0,$$

where,  $\psi : (0, \infty) \rightarrow (0, 1)$  is a nondecreasing mapping. If for any initial guess  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ . Then  $T$  has a unique fixed point in  $\mathcal{A}$ .

It is obvious that Corollary 2.7 improves the Jleli–Samet fixed point theorem [24] and the results presented by Ahmad et al. [7] and Li and Jiang [26].

We also note that an improvement of particular case of the Skof fixed point theorem [37] can be obtained by taking  $\varphi(y) = \lambda \psi(y)$  in Theorems 2.3 and 2.4 as follows.



**Corollary 2.8** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space, and let  $T : \mathcal{A} \rightarrow P_{cb}(\mathcal{A})$  be a set-valued strictly  $f$ -admissible mapping satisfying the following inequality:*

$$\psi(f(x, y)H(Tx, Ty)) \leq \lambda\psi(d(x, y)) \quad \forall x, y \in \mathcal{A}, \text{ provided that } H(Tx, Ty) > 0,$$

where  $\psi : (0, \infty) \rightarrow (0, \infty)$  is a nondecreasing mapping, and  $\lambda \in (0, 1)$ . If for any initial guess  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ , then  $T$  has a unique fixed point in  $\mathcal{A}$ .

Let us consider a nondecreasing mapping  $\psi : (0, \infty) \rightarrow (0, \infty)$  and a mapping  $\beta : (0, \infty) \rightarrow (0, 1)$  satisfying  $\limsup_{y \rightarrow \epsilon^+} \beta(y) < 1$  for any  $\epsilon > 0$ . Then taking  $\varphi(y) = \beta(y)\psi(y)$  and  $\psi(y) = y$  for all  $y > 0$  in Theorem 2.3, we obtain an improvement of the well-known Geraghty fixed point theorem [23].

### 3 Theorems on generalized $(\psi, \varphi)_f$ -contractions

Since the generalized  $(\psi, \varphi)_f$ -contractions are not  $(\psi, \varphi)_f$ -contractions in general, in this section, we give some fixed-point results for the class of generalized  $(\psi, \varphi)_f$ -contractions defined below.

**Definition 3.1** Let  $(\mathcal{A}, d)$  be a metric space. A mapping  $T : \mathcal{A} \rightarrow P(\mathcal{A})$  is said to be a set-valued generalized  $(\psi, \varphi)_f$ -contraction if there exists  $f : \mathcal{A} \times \mathcal{A} \rightarrow [0, \infty)$  such that

$$\psi(f(q, \varsigma)H(T(q), T(\varsigma))) \leq \varphi(A(q, \varsigma)) \tag{3.1}$$

for all  $q, \varsigma \in \mathcal{A}$  with  $f(q, \varsigma) > 1$  and  $H(T(q), T(\varsigma)) > 0$ , where

$$A(q, \varsigma) = \max\{d(q, \varsigma), d(q, Tq), d(\varsigma, T\varsigma), (d(q, T\varsigma) + d(Tq, \varsigma))/2\}.$$

The following theorems generalize many fixed point theorems involving Ciric type contractions. For Ćirić contraction and related fixed-point results, see ([3, 21, 41]).

**Theorem 3.2** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space. Let  $T : \mathcal{A} \rightarrow C(\mathcal{A})$  be an  $f$ -admissible mapping satisfying (3.1). Suppose mappings  $\psi, \varphi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i) for all  $q_0 \in \mathcal{A}$ , there exists  $q_1 \in T(q_0)$  such that  $f(q_0, q_1) \geq 1$ ;
- (ii)  $\psi$  is nondecreasing, and  $\varphi(y) < \psi(y)$  for all  $y > 0$ ;
- (iii)  $\limsup_{y \rightarrow r^+} \varphi(y) < \psi(r)$  for all  $r > 0$ .

Then  $T$  admits a fixed point in  $\mathcal{A}$ .

*Proof* Let  $q_0 \in \mathcal{A}$  be an arbitrary initial guess. Following the arguments in Step 1 of the proof of Theorem 2.3, we have  $d(q_n, q_{n+1}) \leq f(q_{n-1}, q_n)H(T(q_{n-1}), T(q_n))$  for all  $n \geq 1$ . By the first part of (ii) and (3.1) we have

$$\psi(d(q_n, q_{n+1})) \leq \psi(f(q_{n-1}, q_n)H(T(q_{n-1}), T(q_n))) \leq \varphi(A(q_{n-1}, q_n)).$$

Since  $T(x)$  is compact for all  $x \in \mathcal{A}$ , there exists  $q_n \in T(q_{n-1})$  such that  $d(q_{n-1}, q_n) = d(q_{n-1}, T(q_{n-1}))$  for all  $n \geq 1$  and

$$\begin{aligned} &\psi(d(q_n, q_{n+1})) \\ &\leq \varphi(A(q_{n-1}, q_n)) \\ &= \varphi(\max\{d(q_{n-1}, q_n), d(q_{n-1}, T(q_{n-1})), d(q_n, T(q_n)), d(q_{n-1}, T(q_n)) \\ &\quad + d(q_n, T(q_{n-1}))/2\}) \\ &= \varphi(\max\{d(q_{n-1}, q_n), d(q_n, q_{n+1})\}). \end{aligned}$$

If  $d(q_{n-1}, q_n) < d(q_n, q_{n+1})$ , then  $\psi(d(q_n, q_{n+1})) \leq \varphi(d(q_n, q_{n+1}))$ , which is a contradiction to the second part of assumption (ii). Thus we have  $d(q_{n-1}, q_n) > d(q_n, q_{n+1})$  and

$$\psi(d(q_n, q_{n+1})) \leq \varphi(d(q_{n-1}, q_n)).$$

By the second part of assumption (ii) we have

$$\psi(d(q_n, q_{n+1})) \leq \varphi(d(q_{n-1}, q_n)) < \psi(d(q_{n-1}, q_n)). \tag{3.2}$$

Since  $\psi$  is a nondecreasing mapping,  $d(q_n, q_{n+1}) < d(q_{n-1}, q_n)$  for every  $n \geq 1$ . This shows that the sequence  $\{d(q_{n-1}, q_n)\}$  is positively decreasing. Thus there exists  $L \geq 0$  such that  $\lim_{n \rightarrow \infty} d(q_{n-1}, q_n) = L+$ . If  $L > 0$ , then by (3.2) we obtain a contradiction to assumption (iii) as follows:

$$\psi(L+) = \lim_{n \rightarrow \infty} \psi(d(q_n, q_{n+1})) \leq \lim_{n \rightarrow \infty} \sup \varphi(d(q_{n-1}, q_n)) \leq \lim_{\sigma \rightarrow L+} \sup \varphi(\sigma).$$

Hence  $L = 0$ , and, consequently,  $T$  is an asymptotically regular mapping.

Now we show that  $\{q_n\}$  is a Cauchy sequence. Assume on the contrary that the sequence  $\{q_n\}$  is not Cauchy. In this case, by Lemma 1.5 there exist two subsequences  $\{q_{n_k}\}$ ,  $\{q_{m_k}\}$  of  $\{q_n\}$  and  $\epsilon > 0$  such that (1.3) and (1.4) hold. By (1.3) we infer that  $d(q_{n_k+1}, q_{m_k+1}) > \epsilon$  and  $f(q_{n_k}, q_{m_k}) > 1$  for all  $k \geq 1$ . Letting  $q = q_{n_k}$  and  $\varsigma = q_{m_k}$  in (3.1), we have

$$\psi(d(q_{n_k+1}, q_{m_k+1})) \leq \psi(f(q_{n_k}, q_{m_k})H(Tq_{n_k}, Tq_{m_k})) \leq \varphi(A(q_{n_k}, q_{m_k})) \quad \text{for all } k \geq 1.$$

If  $a_k = d(q_{n_k+1}, q_{m_k+1})$  and  $b_k = A(q_{n_k}, q_{m_k})$ , then

$$\psi(a_k) \leq \varphi(b_k) < \psi(b_k) \quad \text{for any } k \geq 1 \text{ implies that } a_k < b_k.$$

Since  $\lim_{k \rightarrow \infty} a_k = \epsilon+$ ,  $\lim_{k \rightarrow \infty} b_k = \epsilon+$ . Thus

$$\psi(\epsilon+) = \lim_{k \rightarrow \infty} \psi(a_k) \leq \lim_{k \rightarrow \infty} \sup \varphi(b_k) \leq \lim_{\sigma \rightarrow \epsilon+} \varphi(\sigma).$$

This is a contradiction to assumption (iii), and, consequently,  $\{q_n\}$  is a Cauchy sequence in  $(\mathcal{A}, d)$ . Since  $(\mathcal{A}, d)$  is a complete metric space, there exists  $q^* \in \mathcal{A}$  such that  $q_n \rightarrow q^*$  as  $n \rightarrow \infty$ , and the  $f$ -regularity of the space  $(\mathcal{A}, d)$  implies  $f(q_n, q^*) > 1$ . We claim that

$d(q^*, T(q^*)) = 0$ . On the contrary, assume that  $d(q^*, T(q^*)) > 0$ . Then there exists  $n_1 \in \mathbb{N}$  such that  $d(q_n, T(q^*)) > 0$  for each  $n \geq n_1$ . By (3.1)

$$\psi(d(q_{n+1}, T(q^*))) \leq \psi(f(q_n, q^*)H(T(q_n), T(q^*))) \leq \varphi(A(q_n, q^*)) < \psi(A(q_n, q^*)).$$

By the first part of assumption (ii) we have  $d(q_{n+1}, T(q^*)) < A(q_n, q^*)$ . Applying the limit as  $n \rightarrow \infty$  on both sides of the last inequality, we have  $d(q^*, T(q^*)) < d(q^*, T(q^*))$ , a contradiction, and thus  $d(q^*, T(q^*)) = 0$ . Since  $T(q^*)$  is compact,  $q^* \in T(q^*)$ . □

**Theorem 3.3** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space. Let  $T : \mathcal{A} \rightarrow C(\mathcal{A})$  be an  $f$ -admissible mapping satisfying (3.1). Suppose the mappings  $\psi, \varphi : (0, \infty) \rightarrow (-\infty, \infty)$  satisfy the following conditions:*

- (i) for all  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 \in T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ ;
- (ii)  $\psi$  is nondecreasing, and  $\varphi(y) < \psi(y)$  for all  $y > 0$ ;
- (iii)  $\inf_{\sigma > \epsilon} \psi(\sigma) > -\infty$ ;
- (iv) if the sequences  $\{\psi(\sigma_n)\}$  and  $\{\varphi(\sigma_n)\}$  converge to the same limit and  $\{\psi(\sigma_n)\}$  is strictly decreasing, then  $\lim_{n \rightarrow \infty} \sigma_n = 0$ ;
- (v)  $\limsup_{\sigma \rightarrow \epsilon} \varphi(\sigma) < \liminf_{\sigma \rightarrow \epsilon^+} \psi(\sigma)$  for all  $\epsilon > 0$ ;
- (vi)  $\limsup_{\sigma \rightarrow \epsilon_1} \varphi(\sigma) < \liminf_{\sigma \rightarrow \epsilon} \varphi(\sigma)$  for all  $\epsilon, \epsilon_1 > 0$ .

Then  $T$  has a fixed point in  $\mathcal{A}$ .

*Proof* This proof can be obtained by following the proofs of Theorems 2.4 and 3.2. We omit the details. □

For single-valued mappings, we have the following result.

**Theorem 3.4** *Let  $(\mathcal{A}, d)$  be an  $f$ -regular complete metric space, and let  $T : X \rightarrow X$  be a strictly  $f$ -admissible mapping satisfying following inequality:*

$$\tau + \psi(f(\sigma, \varsigma)d(T(\sigma), T(\varsigma))) \leq \psi(A(\sigma, \varsigma)) \tag{3.3}$$

for all  $\sigma, \varsigma \in \mathcal{A}$  with  $d(T(\sigma), T(\varsigma)) > 0$ , where  $\psi : (0, \infty) \rightarrow \mathbb{R}$  is a nondecreasing mapping, and  $\tau > 0$ . If for any initial guess  $\sigma_0 \in \mathcal{A}$ , there exists  $\sigma_1 = T(\sigma_0)$  such that  $f(\sigma_0, \sigma_1) \geq 1$ , then  $T$  admits a unique fixed point.

*Proof* Setting  $\varphi(y) = \psi(y) - \tau$  for all  $y > 0$  and letting  $T(x)$  to be a singleton set for all  $x \in \mathcal{A}$  in Theorem 3.2, we have required result. □

**Remark 3.5** It is noted in [27] that the Riech and Hardy–Roger contractions are reducible to the Ćirić contraction (also called generalized contraction). Thus Theorems 3.2, 3.3, and 3.4 remains true if we replace  $A(\sigma, \varsigma)$  by anyone of the following:

- (1)  $\max\{d(\sigma, \varsigma), d(\sigma, T(\sigma)), d(\varsigma, T(\varsigma))\}$ ,
- (2)  $\max\{d(\sigma, T(\sigma)), d(\varsigma, T(\varsigma))\}$ ,
- (3)  $\max\{d(\sigma, \varsigma), \frac{d(\sigma, T(\sigma)) + d(\varsigma, T(\varsigma))}{2}, \frac{d(\varsigma, T(\sigma)) + d(\sigma, T(\varsigma))}{2}\}$ ,
- (4)  $ad(\sigma, \varsigma) + b(d(\sigma, T(\sigma)) + d(\varsigma, T(\varsigma))) + c(d(\varsigma, T(\sigma)) + d(\sigma, T(\varsigma)))$  with  $a + b + c < 1$ ,
- (5)  $ad(\sigma, \varsigma) + bd(\sigma, T(\sigma)) + cd(\varsigma, T(\varsigma))$  with  $a + b + c < 1$ .

#### 4 Applications to fractional differential equations

Lacroix (1819) introduced and investigated several applicable properties of fractional differentials. Recently, various new models involving the Caputo–Fabrizio derivative (CFD) were discovered and analyzed [8, 14, 38, 39]. In the following, we investigate one of these models in metric spaces. We introduce some notations for this purpose.

Let  $\mathcal{C}_{0,1}$  be the space of continuous functions  $w : [0, 1] \rightarrow \mathbb{R}$ . Define the metric  $d : \mathcal{C}_{0,1} \times \mathcal{C}_{0,1} \rightarrow [0, \infty)$  by

$$d(w, g) = \|w - g\|_\infty = \max_{v \in [0,1]} |w(v) - g(v)| \quad \text{for } w, g \in \mathcal{C}_{0,1}.$$

Then the space  $(\mathcal{C}_{0,1}, d)$  is a complete metric space. Let  $f : \mathcal{C}_{0,1} \times \mathcal{C}_{0,1} \rightarrow (1, \infty)$  be defined by

$$f(r, t) = e^{\|r+t\|_\infty} \quad \text{for } r, t \in \mathcal{C}_{0,1}.$$

Let  $K_1 : [0, 1] \times \mathbb{R} \rightarrow \mathbb{R}$  be a continuous mapping. We will investigate the CFDE

$${}^C D^\beta q(v) = K_1(v, q(v)) \tag{4.1}$$

with boundary conditions

$$q(0) = 0, \quad Iq(1) = q'(0).$$

Here  ${}^C D^\beta$  denotes the CFD of order  $\beta$  defined by

$${}^C D^\beta K_1(v) = \frac{1}{\Gamma(n - \beta)} \int_0^v (v - \eta)^{n-\beta-1} K_1^n(\eta) d\eta,$$

where

$$n - 1 < \beta < n \quad \text{and} \quad n = [\beta] + 1,$$

and  $I^\beta K_1$  is given by

$$I^\beta K_1(v) = \frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta) d\eta \quad \text{with } \beta > 0.$$

Then equation (4.1) can be modified to

$$q(v) = \frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta, q(\eta)) d\eta + \frac{2v}{\Gamma(\beta)} \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} K_1(u, q(u)) du d\eta.$$

**Theorem 4.1** Equation (4.1) admits a solution in  $\mathcal{C}_{0,1}$  provided that:

(I) there exists  $\tau > 0$  such that for all  $q, \varsigma \in \mathcal{C}_{0,1}$ , we have

$$\begin{aligned} & |K_1(\eta, q(\eta)) - K_1(\eta, \varsigma(\eta))| \\ & \leq \frac{e^{-\tau} \Gamma(\beta + 1)}{4M} |q(\eta) - \varsigma(\eta)| (M = \min\{f(q, \varsigma) | q, \varsigma \in \mathcal{C}_{0,1}\}); \end{aligned}$$

(II) there exists  $q_0 \in \mathcal{C}_{0,1}$  such that for all  $v \in [0, 1]$ , we have

$$q_0(v) \leq \frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta, q_0(\eta)) d\eta + \frac{2v}{\Gamma(\beta)} \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} K_1(u, q_0(u)) du d\eta.$$

*Proof* Consistently with the notations introduced, define the mapping  $R : \mathcal{C}_{0,1} \rightarrow \mathcal{C}_{0,1}$  by

$$R(q(v)) = \frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta, q(\eta)) d\eta + \frac{2v}{\Gamma(\beta)} \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} K_1(u, q(u)) du d\eta.$$

By (II) there exists  $q_0 \in \mathcal{C}_{0,1}$  such that  $q_n = R^n(q_0)$ . The continuity of the mapping  $K_1$  leads to the continuity of the mapping  $R$  on  $\mathcal{C}_{0,1}$ . It is easy to verify the assumptions of Theorem 3.4. Let us verify the contractive condition (3.3) of Theorem 3.4.

$$|R(q(v)) - R(\varsigma(v))| = \left| \begin{aligned} &\frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta, q(\eta)) d\eta \\ &- \frac{1}{\Gamma(\beta)} \int_0^v (v - \eta)^{\beta-1} K_1(\eta, \varsigma(\eta)) d\eta \\ &+ \frac{2v}{\Gamma(\beta)} \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} K_1(u, q(u)) du d\eta \\ &- \frac{2v}{\Gamma(\beta)} \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} K_1(u, \varsigma(u)) du d\eta \end{aligned} \right| \quad \text{implies}$$

$$\begin{aligned} &|R(q(v)) - R(\varsigma(v))| \\ &\leq \left| \int_0^v \left( \frac{1}{\Gamma(\beta)} (v - \eta)^{\beta-1} K_1(\eta, q(\eta)) - \frac{1}{\Gamma(\beta)} (v - \eta)^{\beta-1} K_1(\eta, \varsigma(\eta)) \right) d\eta \right| \\ &\quad + \left| \int_0^1 \int_0^\eta \left( \frac{2}{\Gamma(\beta)} (\eta - u)^{\beta-1} K_1(u, q(u)) - \frac{2}{\Gamma(\beta)} (\eta - u)^{\beta-1} K_1(u, \varsigma(u)) \right) du d\eta \right| \\ &\leq \frac{1}{\Gamma(\beta)} \frac{e^{-\tau} \Gamma(\beta + 1)}{4M} \cdot \int_0^v (v - \eta)^{\beta-1} (q(\eta) - \varsigma(\eta)) d\eta \\ &\quad + \frac{2}{\Gamma(\beta)} \frac{e^{-\tau} \Gamma(\beta + 1)}{4M} \cdot \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} (\varsigma(u) - q(u)) du d\eta \\ &\leq \frac{1}{\Gamma(\beta)} \frac{e^{-\tau} \Gamma(\beta + 1)}{4M} \cdot d(q, \varsigma) \cdot \int_0^v (v - \eta)^{\beta-1} d\eta \\ &\quad + \frac{2}{\Gamma(\beta)} \frac{e^{-\tau} \Gamma(\beta) \cdot \Gamma(\beta + 1)}{4M \Gamma(s) \cdot \Gamma(\beta + 1)} \cdot d(q, \varsigma) \cdot \int_0^1 \int_0^\eta (\eta - u)^{\beta-1} du d\eta \\ &\leq \left( \frac{e^{-\tau} \Gamma(\beta) \cdot \Gamma(\beta + 1)}{4M \Gamma(\beta) \cdot \Gamma(\beta + 1)} \right) \cdot d(q, \varsigma) + 2e^{-\tau} B(\beta + 1, 1) \frac{\Gamma(\beta) \cdot \Gamma(\beta + 1)}{4M \Gamma(\beta) \cdot \Gamma(\beta + 1)} \cdot d(q, \varsigma) \\ &\leq \frac{e^{-\tau}}{4M} d(q, \varsigma) + \frac{e^{-\tau}}{2M} d(q, \varsigma) < \frac{e^{-\tau}}{M} d(q, \varsigma) \end{aligned}$$

where  $B$  is the beta mapping. The last inequality can be written as

$$Md(R(q), R(\varsigma)) \leq f(q, \varsigma) d(R(q), R(\varsigma)) \leq e^{-\tau} \psi(q, \varsigma). \tag{4.2}$$

Define the mapping  $\psi(q(v)) = \ln(q(v))$  for  $q, \varsigma \in \mathcal{C}_{0,1}$ . Then inequality (4.2) can be written as

$$\tau + \psi(f(q, \varsigma)d(R(q), R(\varsigma))) \leq \psi(\psi(q, \varsigma)).$$

By Theorem 3.4 the self-mapping  $R$  admits a fixed point, and hence equation (4.1) has a solution.  $\square$

## 5 Conclusion

The  $(\psi, \varphi)_f$ -contractions are general enough to contain famous contractions. The theorems give a general criterion for the existence of unique fixed points of the self-mappings satisfying  $(\psi, \varphi)_f$ -contractions. We investigated the existence of a solution to a fractional differential equation through fixed point methodology.

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### Authors' contributions

The authors equally conceived of the study, participated in its design and coordination, drafted the manuscript, participated in the sequence alignment, and read and approved the final manuscript.

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